



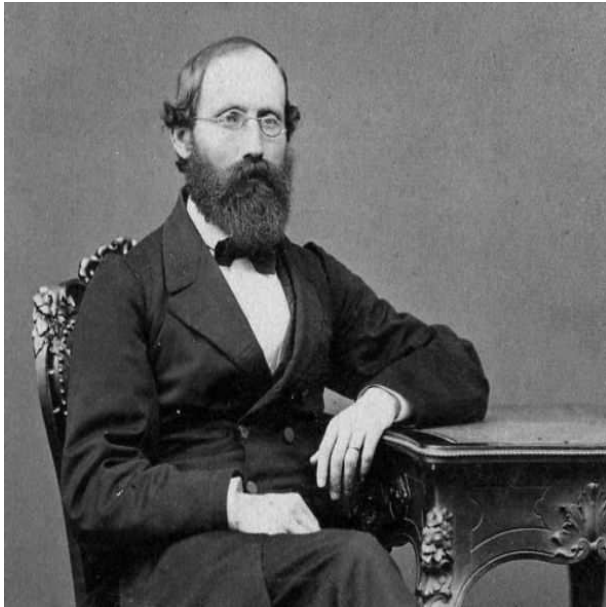
# Riemannian Geometry with Skew Torsion

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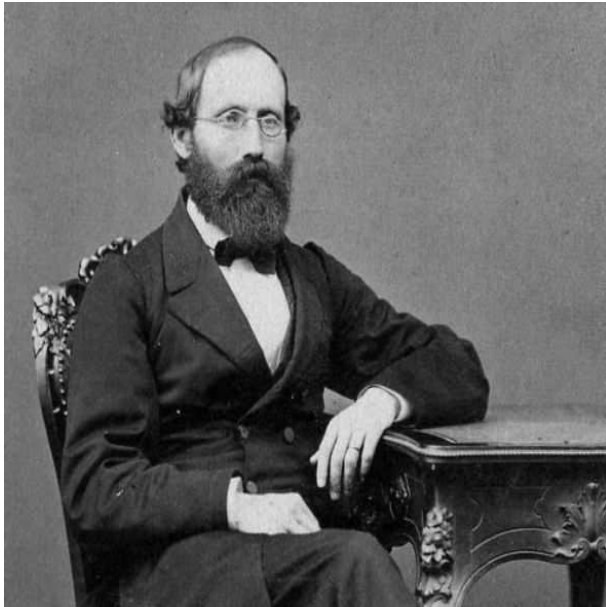


European Women in Mathematics – Rauischholzhausen – 2nd May 2015

## Three major players...



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Bernhard Riemann  
(1826-1866)



Albert Einstein  
(1879-1955)



Élie Cartan  
(1869-1951)

# Small fish in a big shark tank...

Riemannian geometry with skew torsion



Ana Cristina Castro Ferreira  
St Cross College  
University of Oxford

*A thesis submitted for the degree of  
Doctor of Philosophy  
Hilary Term 2010*



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## The center of the world...





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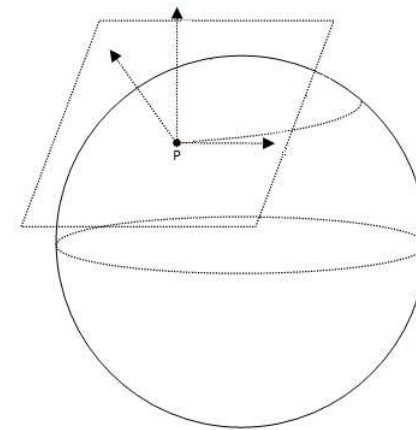
## **Philipps-Universität Marburg**



# Basic ingredients

**Riemannian manifolds**  $(M^n, g)$

B. Riemann's Habilitationsvortrag (Göttingen, 1854) “Über die Hypothesen, welche der Geometrie zugrunde liegen”



$M^n$  – a manifold of dimension  $n$

$g$  – a metric, i.e. a scalar product on each tangent space



# Connections

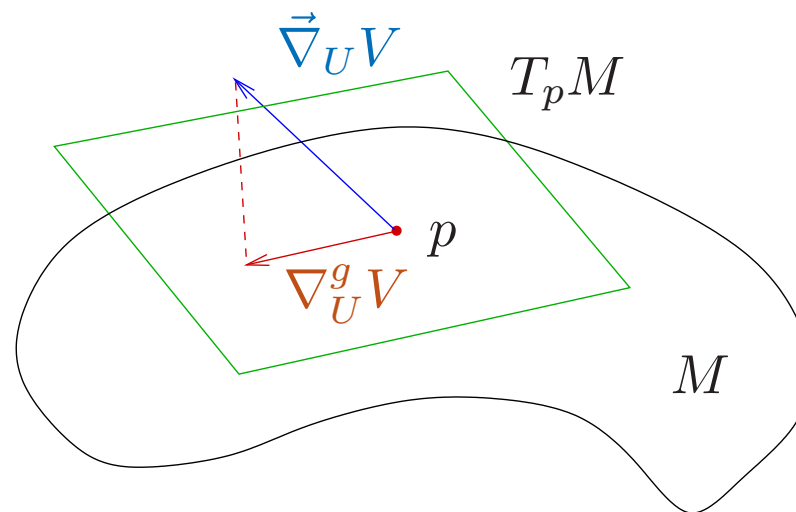
**Throwback to calculus:** Directional derivative of vector-valued smooth functions  $f : \mathbb{R}^p \longrightarrow \mathbb{R}^q \longleftrightarrow \vec{\nabla}$

**Connection  $\nabla$ :** abstract derivation rule satisfying all formal properties of dir. derivative

different name: ‘covariant derivative’

**Ex.** Projection  $\nabla_U^g V$  of dir. derivative  $\vec{\nabla}_U V$  to tangent plane

= ‘Levi-Civita connection’  $\nabla^g$



$[\nabla^g$ : completely determined by  $g$ ]

# Connections

**However...** not only possibility

→ connection **with torsion**

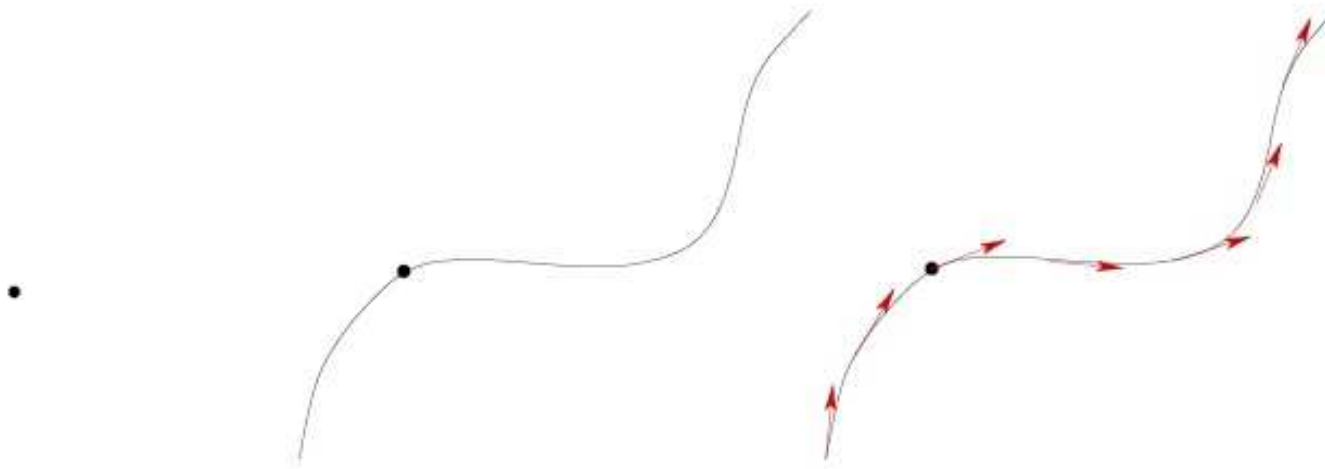
[Dfn: Cartan, 1925]

**Ex.** Electrodynamics:  $\nabla_U V := \vec{\nabla}_U V + \frac{ie}{\hbar} A(U) V$  ( $\Leftrightarrow \nabla_\mu = \partial_\mu + \frac{ie}{\hbar} A_\mu$ )  
A: gauge potential = electromagnetic potential

**Ex.** If  $n = 3$ :  $\nabla_U V := \vec{\nabla}_U V + U \times V$   
additional term gives space an ‘internal angular momentum’, a **torsion**

**Fact:** 3 types of torsion: vectorial, **skew symmetric**, and [something else].

# Classical general relativity and electromagnetism



point particle

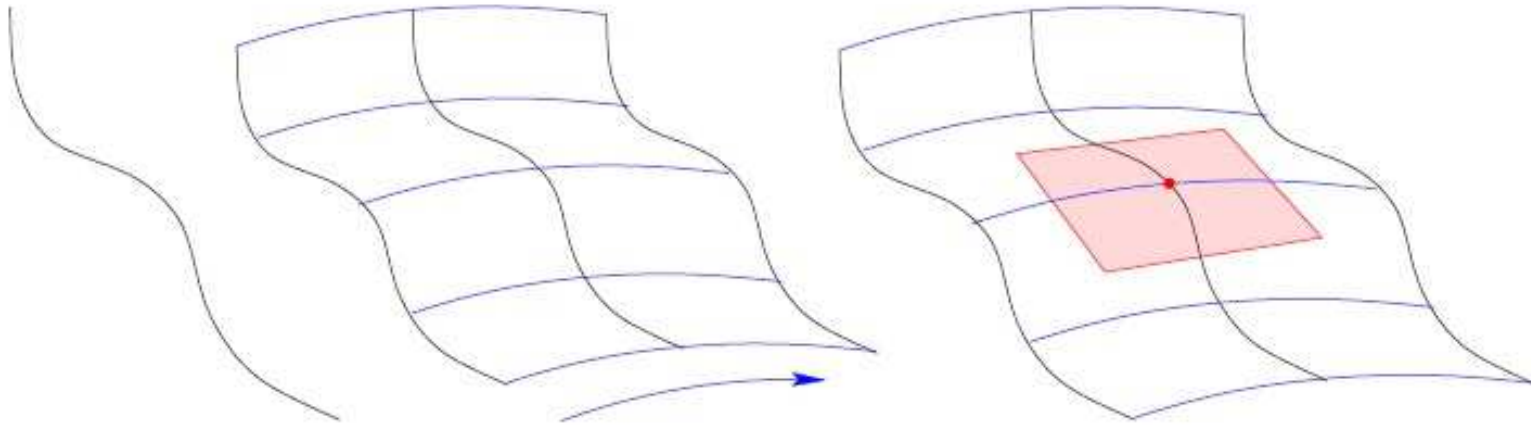
moves along  
a curve  $\gamma$

physical action:  $\int_{\gamma} A$   
for a potential  $A$  : 1-form

field strength  
 $F = dA$  : 2-form  $\Leftrightarrow$  geometric concept  
of curvature

curvature measures deviation from vacuum !

## Modern unified models



string particle

moves along  
a surface  $S$

physical action:  $\int_S \tilde{A}$  for  
a higher order potential  $\tilde{A}$  : **2-Form**

higher order field strength

$$F = d\tilde{A} : \text{3-form}$$



geometric concept  
of **torsion**

**torsion** measures deviation from vacuum (“integrable case”) !



## Torsion and curvature

$x_1, \dots, x_n$  coordinates on  $M^n$ ; vector fields  $\frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_n}$

$$T\left(\frac{\partial}{\partial x_i}, \frac{\partial}{\partial x_j}\right) = \nabla_{\frac{\partial}{\partial x_i}} \frac{\partial}{\partial x_j} - \nabla_{\frac{\partial}{\partial x_j}} \frac{\partial}{\partial x_i}$$

$$R\left(\frac{\partial}{\partial x_i}, \frac{\partial}{\partial x_j}\right) = \nabla_{\frac{\partial}{\partial x_i}} \nabla_{\frac{\partial}{\partial x_j}} - \nabla_{\frac{\partial}{\partial x_j}} \nabla_{\frac{\partial}{\partial x_i}} \quad \left[ \frac{\partial^2}{\partial x_i \partial x_j} \stackrel{?}{=} \frac{\partial^2}{\partial x_j \partial x_i} \right]$$

**Also:** Ricci curvature, scalar curvature...

**New data:**  $(M^n, g, T)$

More adapted to certain geometries:

- Lie groups, KT manifolds, Generalized geometry, Homogeneous spaces
- Almost Hermitian manifolds – almost Kähler, nearly Kähler – almost contact metric manifolds – quasi-Sasaki – cocalibrated G2

## Einstein metrics

Field Equations:  $M^4$  spacetime,  $g$  signature (3,1)

$$R_{\mu\nu} - \frac{1}{2}g_{\mu\nu} R + g_{\mu\nu} \Lambda = \frac{8\pi G}{c^4} T_{\mu\nu}$$

**Mathematical Einstein equations:**

$(M^n, g)$  Riemannian manifold

$$R_{\mu\nu} = \frac{R}{n} g_{\mu\nu}$$

Topological obstruction – known only in dimension 4

**Hitchin-Thorpe Inequality:**  $2\chi \geq 3|\tau|$

[1969/1974]

# Einstein metrics with skew torsion

**Dfn:** In dimension 4, based on the phenomenon of self-duality

[F. '11]

- Hitchin-Thorpe Inequality holds  $\checkmark$
- $*T$  is a Killing field

**Question:** How to generalize to higher dimensions?

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# Einstein metrics with skew torsion

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- $*T$  is a Killing field

**Question:** How to generalize to higher dimensions?

¿  $R_{\mu\nu} = \frac{R}{n} g_{\mu\nu}$  ?

→ some 'issues' with this definition...

# Einstein metrics with parallel skew torsion

Assume  $\nabla T = 0$ . Then

[Agricola-F. '13]

- $R_{\mu\nu}$  is symmetric
- scalar curvature is a constant
- $R > 0 \Rightarrow M$  compact and  $\pi_1$  finite

→ Best possible analogy with the Riemannian case ←

- Hordes of examples of manifolds with parallel torsion:  
Sasaki, nearly Kähler, nearly parallel  $G_2$ , naturally reductive spaces...
- Systematic investigation of such examples ✓

# Homogeneous spaces

- Links algebraic theory of Lie groups and geometric notions such as isometry and curvature
- good examples in Riemannian geometry
- classification of (Riemannian) symmetric spaces [Cartan 1926]

**However** classification without further assumptions is impossible

- very small dimensions
- positive curvature
- isotropy irreducible (examples of Einstein manifolds)

**Our class:**

naturally reductive homogeneous spaces

# Homogeneous spaces

- $(M, g)$  plus  $G \subseteq \text{Iso}(M)$  s.t.  $G$  acts on  $M$  transitively.  
K stabilizer of a point  $p \in M \longrightarrow M = G/K$ .

**Thm.**

[Ambrose-Singer 1958]

$(M, g)$  is homogeneous iff exists torsion  $T$  s.t.  $\nabla T = \nabla \mathcal{R} = 0$

$T$  skew symmetric  $\longleftrightarrow (M, g)$  naturally reductive

## Previous classifications of nat. red. spaces

→ Dim 3 (Tricerri-Vanhecke, 1983)

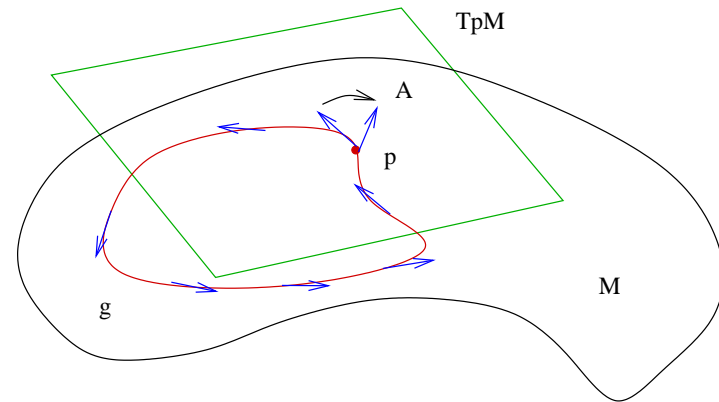
→ Dim 4 and 5 (Kowalski-Vanhecke, 1983, 1985)



# Our methods

[Agricola-F.-Friedrich '2015]

- Look at the parallel torsion as the fundamental object.
- Use recent development in the holonomy theory of connections with parallel skew torsion.
- Determine the “geometric nature” of  $M$



## An important tool

- $\sigma_T := \frac{1}{2} \sum_{i=1}^n (e_i \lrcorner T) \wedge (e_i \lrcorner T) = \overset{X,Y,Z}{\mathfrak{S}} g(T(X, Y), T(Z, V)) \quad (= 0 \text{ if } n \leq 4)$

→ For “non-degenerate” torsion, the connection in (AS) is the characteristic connection for some known geometry (almost contact, almost Hermitian...).

# Classifications

$\sigma_T = 0$ : ( $n \geq 5$ )  $M$  is a compact simple Lie group or its dual noncompact symmetric space

$\sigma_T \neq 0$ :

dim.	space	remarks
	$\mathbb{R}^3, \mathbb{S}^3, \mathbb{H}^3$ $SU(2), SL(2, \mathbb{R}), H^3$	$T \sim \text{dvol}$ spaces forms left. inv. metric
4	$N^3 \times \mathbb{R}$	$*T$ parallel field $N^3$ nat. red.
5	$H^5$ $(G_1 \times G_2)/SO(2)$ $SU(3)/SU(2), SU(2, 1)/SU(2)$	$*\sigma_T$ Reeb field quasi-Sasaki $\alpha$ -Sasaki

# Classifications

dim.	space	remarks
6		$*\sigma_T$ skew-sym. endomorph.
	$G_1 \times G_2$	$\text{rk}(*\sigma_T) = 2$
	cannot occur	$\text{rk}(*\sigma_T) = 4$
	$S^6, S^3 \times S^3, \mathbb{C}P^3, U(3)/U(1)^3$	$\text{rk}(*\sigma_T) = 6$ type $\mathcal{W}_1$
	$\mathbb{R}^3 \times \mathbb{R}^3, \mathbb{S}^3 \times \mathbb{R}^3, \mathbb{S}^3 \times \mathbb{R}^3$ $\mathbb{S}^3 \times \mathbb{S}^3, \text{SL}(2, \mathbb{C})$	type $\mathcal{W}_1 \oplus \mathcal{W}_3$

**; Vielen Dank für Ihre Aufmerksamkeit !**