

# An epiperimetric inequality approach to the regularity of the free boundary in the thin obstacle problem

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EWM Meeting, Schloss Rauischholzhausen

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May 1st, 2015

# Classical obstacle problem



# Classical obstacle problem



Suppose we want to wrap a meatloaf in a plastic wrap. Here the meatloaf is the **obstacle**, and the configuration of the plastic wrap, after it adjusts to the geometry of the meatloaf, represents the solution to the **obstacle problem**.

# Formulation of the classical obstacle problem

We are given:

- $\phi \in C^2(D)$ , the *obstacle*;
- $\psi \in W^{1,2}(D)$  with  $\phi \leq \psi$  on  $\partial D$ , the *boundary values*;
- $f \in L^\infty(D)$  , the *source term*.

We want to minimize

$$\int_D (|\nabla u|^2 + 2fu) dx$$

over  $\mathcal{K} = \{u \in W^{1,2}(D) : u = \psi \text{ on } \partial D, u \geq \phi \text{ a.e. in } D\}$ .

There exists a unique minimizer  $u$  which satisfies:

$$\Delta u = f \text{ in } \{u > \phi\}$$

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- **Coincidence set:**  $\Lambda_\phi(u) = \{x \in D \mid u(x) = \phi(x)\}.$
- **Free boundary:**  $\Gamma_\phi(u) = \partial\{x \in D \mid u(x) = \phi(x)\}.$

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First fundamental question: How smooth is the solution? The optimal regularity of the solution is  $u \in C_{\text{loc}}^{1,1}(D) \cong W_{\text{loc}}^{2,\infty}(D).$

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Second fundamental question: How smooth is the free boundary? In 1977 Kinderlehrer and Nirenberg proved that, if the free boundary is a  $C^1$  hypersurface, then it is  $C^\omega$  (real analytic). In the same year Caffarelli developed his theory of the regularity of the free boundary and proved Lipschitz regularity, and then proved how to go from Lipschitz to  $C^{1,\alpha}.$



# The thin obstacle problem

We are given:

- $D \subset \mathbb{R}^n$ : bounded domain;
- $\mathcal{M}$ : smooth  $(n-1)$ -dimensional manifold in  $\mathbb{R}^n$ , that divides  $D$  into two parts,  $D_+$  and  $D_-$ ;
- $\phi : \mathcal{M} \rightarrow \mathbb{R}$ , the *obstacle*;
- $\psi : \partial D \rightarrow \mathbb{R}$  with  $\psi > \phi$  on  $\mathcal{M} \cap \partial D$ ;
- $A(x) = [a_{ij}(x)]$  in  $D$ .

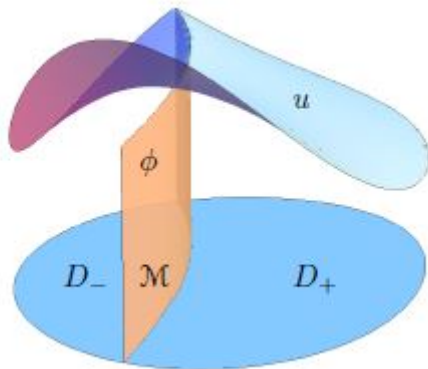
We want to minimize

$$\int_D \langle A(x) \nabla u, \nabla u \rangle dx, \quad (0.1)$$

over the convex set

$$\mathcal{K} = \{u \in W^{1,2}(D) \mid u = \psi \text{ on } \partial D, u \geq \phi \text{ on } \mathcal{M} \cap D\}. \quad (0.2)$$

# The thin obstacle problem



## Where does the thin obstacle problem appear?

- In elasticity (Signorini), when an elastic body is at rest, partially laying on a surface  $\mathcal{M}$ .
- It models the flow of a saline concentration through a semipermeable membrane.
- In mathematical finance, when the random variation of an underlying asset changes discontinuously.

# Notations, definitions

- $B_1 \subset \mathbb{R}^n$ : unit ball;  $\mathcal{M} = B'_1 = B_1 \cap \{x_n = 0\}$ ;
- $S_1 \subset \mathbb{R}^n$ : unit sphere;
- the obstacle  $\varphi \in C^{1,1}(B'_1)$ ;
- $\psi : S_1 \rightarrow \mathbb{R}$  such that  $\psi > \varphi$  on  $S_1 \cap B'_1$
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## Definitions

$$\Lambda_\phi(u) = \{x \in \mathcal{M} \cap D \mid u(x) = \phi(x)\} \quad \text{coincidence set}$$

$$\Gamma_\phi(u) = \partial_{\mathcal{M}} \Lambda_\phi(u) \quad \text{free boundary}$$

## Assumptions on $A(x)$

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- (**ellipticity**)  $\exists \lambda > 0$  such that

$$\lambda |\xi|^2 \leq \langle A(x)\xi, \xi \rangle \leq \lambda^{-1} |\xi|^2, \forall x \in B_1, \forall \xi \in \mathbb{R}^n;$$



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$$\lambda |\xi|^2 \leq \langle A(x)\xi, \xi \rangle \leq \lambda^{-1} |\xi|^2, \forall x \in B_1, \forall \xi \in \mathbb{R}^n;$$

- **Lipschitz continuity of the  $a_{ij}$** ,  $|a_{ij}(x) - a_{ij}(y)| \leq M|x - y|, \forall i, j$ .

# Properties of $u$

Signorini conditions:

- $Lu := \operatorname{div}(A\nabla u) = 0$  in  $B_1^+ \cup B_1^-$ ,
- $u \geq \varphi$  in  $B'_1$ ,
- $\langle A\nabla u, \nu_+ \rangle + \langle A\nabla u, \nu_- \rangle \geq 0$  in  $B'_1$ ,
- $(u - \varphi)(\langle A\nabla u, \nu_+ \rangle + \langle A\nabla u, \nu_- \rangle) = 0$  in  $B'_1$ .

ambiguous boundary conditions

# Regularity of the solution

Caffarelli (1979):

When  $\mathcal{M}$  is a hyperplane,  $\phi$  is  $C^{2,\alpha}$  for some  $0 < \alpha < \frac{1}{2}$  and  $a_{ij} \in C_{loc}^{1,1}$ :  
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Arkhipova and Uraltseva (1985-87):

Same conclusion when  $a_{ij} \in W_{loc}^{1,p}$  and  $\phi \in W_{loc}^{2,p}$ , for some  $p > n$ . This includes, in particular,  $a_{ij} \in W_{loc}^{1,\infty} = C_{loc}^{0,1}$ .

## What about optimal regularity?

Even when  $A(x) \equiv I$ ,  $\mathcal{M}$  is flat and  $\phi = 0$  the best one can hope for is  $C_{loc}^{1, \frac{1}{2}}(D_{\pm} \cup \mathcal{M})$ . One has in fact the following global solution to the Signorini problem with  $\mathcal{M} = \{x_n = 0\}$ , and  $\phi \equiv 0$

$$u(x) = \Re(x_1 + i|x_n|)^{3/2} \in C_{loc}^{1, \frac{1}{2}}(D_{\pm} \cup \mathcal{M}).$$



# Optimal Regularity

Athanasopoulos & Caffarelli (2004): case  $A(x) \equiv I$

Major breakthrough: they proved that when  $\mathcal{M}$  is flat and  $\phi = 0$ , then the solution  $u$  to the Signorini problem is  $C_{loc}^{1, \frac{1}{2}}(D_{\pm} \cup \mathcal{M})$  for any  $n \geq 2$ .

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Guillen (2009):  $A(x) \in C_{loc}^{1, \gamma}$ , for some  $\gamma > 0$

Proved  $C_{loc}^{1, \frac{1}{2}}(D_{\pm} \cup \mathcal{M})$  regularity when  $\mathcal{M}$  is flat and  $\phi$  in  $C^{1, \beta}$  for some  $\beta > \frac{1}{2}$ .



Garofalo & Smit Vega Garcia (2013),  $A(x) \in C_{loc}^{0,1}$

By means of some **new monotonicity formulas**, we have established the  $C_{loc}^{1, \frac{1}{2}}(D_{\pm} \cup \mathcal{M})$  regularity when  $\phi \in C^{1,1}$  and the manifold  $\mathcal{M}$  is flat.

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Theorem (Garofalo & Smit Vega Garcia:)

Let  $u$  be the solution of the Signorini problem (0.1), (0.2) in  $B_1$ , with  $A(x) \in C^{0,1}(B_1)$ , and  $\phi \in C^{1,1}(B'_1)$ . If  $0 \in \Gamma_{\phi}(u)$ , then  $u \in C_{loc}^{1,\frac{1}{2}}(B_1^{\pm} \cup B'_1)$  and

$$\|u\|_{C^{1,\frac{1}{2}}(B_1^{\pm} \cup B'_1)} \leq C(n, \lambda, M, \|u\|_{W^{1,2}(B_1)}).$$

# Historical background: Almgren's monotonicity formula

The crucial tool introduced to study the regularity of the minimizer is a fundamental **monotonicity formula** proved in 1979 by **F. Almgren**, who proved that if  $\Delta u = 0$  in  $B_1$ , then the **frequency** of  $u$ , given by

$$r \rightarrow N(u, r) = \frac{rD(r)}{H(r)} = \frac{r \int_{B_r} |\nabla u|^2}{\int_{S_r} u^2},$$

is **increasing** in  $(0, 1)$ . Furthermore,  $N(r) \equiv \kappa \iff u$  is homogeneous of degree  $\kappa$ , i.e.,  $u(rx) = r^\kappa u(x)$ .

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**Theorem (Athanasopoulos, Caffarelli and Salsa (2007))**

Let  $u$  be the solution of the Signorini problem in  $B_1$  when  $A(x) \equiv I$ , with **zero obstacle** and **flat thin manifold**  $\mathcal{M}$ . Then, the **frequency**  $r \rightarrow N(u, r)$  is **increasing** in  $(0, 1)$ . Moreover,  $N(u, r) \equiv \kappa$  for  $0 < r < 1 \iff u$  is homogeneous of degree  $\kappa$  in  $B_1$ .

## Structure of the proof in the zero obstacle case

Let us consider the general Signorini problem (0.1), (0.2), with  $A(x) \in C^{0,1}(B_1)$ . When the **obstacle is zero**, we introduce the following

$$\text{Frequency function: } N(r) = \frac{rI(r)}{H(r)}, \quad 0 < r < 1,$$

where

$$I(r) = \int_{S_r} u \langle A(x) \nabla u, \nu \rangle = \int_{B_r} \langle A(x) \nabla u, \nabla u \rangle,$$

$$H(r) = \int_{S_r} u^2 \mu d\sigma, \quad \mu(x) = \frac{\langle A(x)x, x \rangle}{|x|^2}.$$

Recall the original frequency function:

$$N(r) = \frac{r \int_{B_r} |\nabla u|^2}{\int_{S_r} u^2}.$$

## Crucial result:

### Theorem (Monotonicity formula for zero obstacle)

There exists a universal  $C > 0$  such that  $r \rightarrow \tilde{N}(r) = e^{Cr} N(r)$  is monotone nondecreasing for  $0 < r < 1$ .

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Important observation: the above theorem is not true for a general Lipschitz matrix  $A(x)$ . We prove it under the assumption that

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However, we show that there exists a local  $C^{1,1}$  diffeomorphism which reduces the general Signorini problem (0.1), (0.2) to one for which (0.3) holds. So (0.3) is not restrictive!



# Blow-ups

Assume  $0 \in \Gamma(u)$ .

Non-homogeneous rescalings of  $u$ :

$$u_r(x) = \frac{u(rx)}{d_r}, \quad x \in B_{\frac{1}{r}}, \quad \text{where } d_r = \left( \frac{1}{r^{n-1}} \int_{S_r} u^2 \mu \right)^{1/2}$$

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Using the monotonicity of  $e^{Cr}N(r)$ :  $\exists u_0 \in W^{1,2}(B_1)$  such that (up to a subsequence),

- $u_{r_j} \rightarrow u_0$  weakly in  $W^{1,2}(B_1)$ ,
- $u_{r_j} \rightarrow u_0$  in  $L^2(S_1, d\sigma)$  and
- $u_{r_j} \rightarrow u_0$  in  $C_{\text{loc}}^1(B_1^\pm \cup B'_1)$

# Properties of the limit

- $\Delta u_0 = 0$  in  $B_1^+ \cup B_1^-$ ;
- $u_0 \geq 0$  on  $B'_1$ ,
- $\langle \nabla u_0, \nu_+ \rangle + \langle \nabla u_0, \nu_- \rangle \geq 0$  on  $B'_1$ ,
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- 
- $u_0$  is homogeneous of degree  $N(0+)$ .
  - $N(0+) = \frac{3}{2}$  or  $N(0+) \geq 2$  (Petrosyan, Shahgholian & Uraltseva).

# Blow up and optimal regularity

## Lemma

Let  $u$  solve the thin obstacle problem in  $B_1$  with  $\varphi = 0$ ,  $0 \in \Gamma(u)$  and  $N(0+) \geq \kappa$ . Then  $\exists C_0 = C_0(n, \lambda, M, \|u\|_{W^{1,2}(B_1)}) > 0$  such that

$$\sup_{B_r} |u| \leq C_0 r^\kappa, 0 < r < r_0.$$

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Now recall that we have  $\kappa \geq \frac{3}{2}$ !

## Challenges of the non-zero obstacle case

When  $\varphi \equiv 0$ , then  $Lu = 0$  outside of  $B'_1$ , so  $\tilde{N}(r) = e^{Cr} N(r) \nearrow$  which gives optimal regularity.



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Natural idea in the case of non zero obstacle is to subtract the obstacle, and consider  $v(x) = u(x) - \varphi(x') - \partial_{\nu_+} u(0)x_n$ .

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Now  $Lv = f$  outside  $B'_1$ , with  $f \in L^\infty$  and life is not so easy...  
When  $L = \Delta$ , then

$$\frac{r}{2} \frac{d}{dr} \log H(r) = N(r) + \frac{n-1}{2}. \quad (0.4)$$

# Challenges of the non-zero obstacle case

For a general  $L$  one has

$$\frac{r}{2} \frac{d}{dr} \log H(r) = \frac{r l(r)}{H(r)} + \frac{r}{2} \frac{\int_{S_r} v^2 L |x|}{H(r)}$$

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The term

$$\frac{r}{2} \frac{\int_{S_r} v^2 L|x|}{H(r)}$$

is the one to be tamed. Its potential bad oscillations could destroy the monotonicity of the adjusted frequency.

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New idea: work with a truncated version of a suitable normalization of  $H(r)$ .

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We introduce functions:

$$\psi(r), \sigma(r) : (0, 1] \rightarrow (0, \infty),$$

where the role of  $\psi(r)$  is to kill the term

$$\frac{r}{2} \frac{\int_{S_r} v^2 L|x|}{H(r)},$$

whereas the role of the function  $\sigma(r)$  is to clean up the blood introduced in the process.

# A new frequency function

We define the **renormalized height and energy**

$$M(r) = \frac{1}{\psi(r)} H(r), \quad J(r) = \frac{1}{\psi(r)} I(r)$$

and introduce the **generalized frequency** of  $v$

$$\Phi(r) = \frac{\sigma(r)J(r)}{M(r)} = \frac{\sigma(r)I(r)}{H(r)},$$



# Partial Monotonicity

Recall that

$$\Phi(r) = \frac{\sigma(r)J(r)}{M(r)} = \frac{\sigma(r)I(r)}{H(r)}.$$

Theorem (Partial monotonicity of the generalized frequency)

Given  $\delta \in (0, 1)$ , there exist  $r_0, K > 0$  such that  $r \rightarrow e^{Kr^{\frac{1-\delta}{2}}} \Phi(r)$  is non-decreasing in the open set

$$\left\{ r \in (0, r_0) \mid M(r) > r^{3+\delta} \right\}.$$

# Full Monotonicity

## Theorem (Monotonicity of the truncated frequency)

Given  $\delta \in (0, 1)$ , there exist  $r_0, K > 0$  (depending on  $\delta$  and  $\|f\|_{L^\infty}$ ), such that

$$N(r) = \frac{\sigma(r)}{2} e^{Kr^{\frac{1-\delta}{2}}} \frac{d}{dr} \log \max \left\{ M(r), r^{3+\delta} \right\}.$$

is monotone non-decreasing on  $(0, r_0)$ .

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Define

$$\tilde{N}(r) = \frac{r}{\sigma(r)} N(r).$$

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Define

$$\tilde{N}(r) = \frac{r}{\sigma(r)} N(r).$$

Since  $\lim_{r \rightarrow 0+} \frac{r}{\sigma(r)} = \alpha > 0$ ,  $\tilde{N}(0+)$  exists.

First we prove, by studying the blow ups, that  $\tilde{N}(0+) \geq \frac{3}{2}$ .

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Then, since  $\tilde{N}(0+) \geq \frac{3}{2}$ , we obtain that

$$\sup_{B_r} |v| \leq Cr^{\frac{3}{2}},$$

which gives optimal regularity.

# Regularity of the regular part of the free boundary

With  $v$  as before and  $x_0 \in \Gamma(v)$ , denote

$$v_{x_0}(x) = v(x_0 + A^{1/2}(x_0)x) - b_{x_0}x_n,$$

$$b_{x_0} = \langle A^{1/2}(x_0)\nabla v(x_0), e_n \rangle.$$

## Definition

$\Gamma_{3/2}(v) = \left\{ x_0 \in \Gamma(v) : \tilde{N}(0+, v_{x_0}) = \frac{3}{2} \right\}$  is the **regular set**.

# The regular set

In the Laplacian case, the regular set is  $C^{1,\alpha}$  regular:

Proposition (Caffarelli, Salsa, Silvestre, 2008:)

Let  $u$  solve the thin obstacle problem in  $B_1$  with  $A \equiv I$  and  $\varphi \in C^{2,1}$ . Then  $\Gamma_{3/2}(u)$  is locally a  $C^{1,\alpha}$ -regular  $(n-2)$ -dimensional surface.



## Weiss monotonicity formula

We introduce a functional suited for the study of the blowups at **regular free boundary points** by analysing the **homogeneous rescallings of  $v$** :

$$C_r(x) = \frac{v(rx)}{r^{3/2}}.$$

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**Weiss type functional:** 
$$W_L(v, r) = \frac{\sigma(r)}{r^3} \left\{ J_L(v, r) - \frac{3}{2r} M_L(v, r) \right\}.$$

**Theorem (Garofalo, Petrosyan & Smit Vega Garcia)**

Assume  $0 \in \Gamma_{3/2}(v)$ . There exists a universal constant  $C > 0$  such that

$$\frac{d}{dr} \left( W_L(v, r) + Cr^{1/2} \right) \geq \frac{2}{r^{n+1}} \int_{S_r} \left( \frac{\langle A \nabla v, \nu \rangle}{\sqrt{\mu}} - \frac{3\sqrt{\mu}}{2r} v \right)^2. \quad (0.5)$$

Hence,  $r \mapsto W_L(v, r) + Cr^{1/2}$  is monotone nondecreasing, therefore the limit  $W_L(0+, v) \stackrel{\text{def}}{=} \lim_{r \rightarrow 0} W_L(v, r)$  exists.

We recall the definition of the **homogeneous rescallings** of  $v$ :

$$C_r(x) = \frac{v(rx)}{r^{3/2}}.$$

### Lemma

Let  $0 \in \Gamma_{3/2}(v)$ . Given  $r_j \rightarrow 0, \exists C_0 \in C_{\text{loc}}^{1,\alpha}((\mathbb{R}^n)^\pm \cup \{0\}), \forall \alpha \in (0, 1/2)$ , such that

$$C_{r_j} \rightarrow C_0 \text{ in } C_{\text{loc}}^{1,\alpha}((\mathbb{R}^n)^\pm \cup \{0\}).$$

$C_0$  is a global solution in  $\mathbb{R}^n$  of the Signorini problem with zero thin obstacle, **homogeneous of degree  $3/2$** .

# Epiperimetric inequality

Let

$$h(x) = \Re(x_1 + i|x_n|)^{\frac{3}{2}}.$$

In the Laplacian case, our Weiss functional takes an easier form:

$$W_{\Delta}(v) := W_{\Delta}(v, 1) = \int_{B_1} |\nabla v|^2 - \frac{3}{2} \int_{S_1} v^2 d\mathcal{H}^{n-1}.$$

Theorem (Garofalo, Petrosyan, Smit Vega Garcia)

There exists  $\kappa \in (0, 1)$  and  $\theta \in (0, 1)$  such that if  $w \in W^{1,2}(B_1)$  is homogeneous of degree  $\frac{3}{2}$ ,  $w \geq 0$  on  $B'_1$  and  $\|w - h\|_{W^{1,2}(B_1)} \leq \theta$ , then there exists  $\zeta \in W^{1,2}(B_1)$  such that  $\zeta = w$  on  $S_1$ ,  $\zeta \geq 0$  on  $B'_1$  and

$$W_{\Delta}(\zeta) \leq (1 - \kappa)W_{\Delta}(w).$$

# Uniquess of blowups

For  $r > 0$  and  $x_0 \in \Gamma_{3/2}(v)$ , we define the homogeneous rescalings

$$C_{x_0,r}(x) = \frac{v(x_0 + A^{1/2}(x_0)x)}{r^{3/2}}.$$

## Proposition

Let  $v$  be as before with  $x_0 \in \Gamma_{3/2}(v)$ . Then,

$\exists r_0 = r_0(x_0), \eta_0 = \eta_0(x_0) > 0$  such that

$$\Gamma(v) \cap B'_{\eta_0}(x_0) \subset \Gamma_{3/2}(v).$$

Moreover, if  $C_{\bar{x},0}$  is any blow up of  $v$  at  $\bar{x} \in \Gamma(v) \cap B'_{\eta_0}(x_0)$ , then

$$\int_{S_1} |C_{\bar{x},r} - C_{\bar{x},0}| \leq Cr^\gamma, \quad \text{for all } r \in (0, r_0),$$

where  $C$  and  $\gamma > 0$  are universal constants.

In particular, the blow-up limit  $C_{\bar{x},0}$  is unique.

# Regularity of the regular set

Theorem (Garofalo, Petrosyan, Smit Vega Garcia, 2015)

Let  $v$  be a solution of the thin obstacle problem with  $x_0 \in \Gamma_{3/2}(v)$ . Then there exists  $\eta_0 = \eta_0(x_0) > 0$  such that

$$B'_{\eta_0}(x_0) \cap \Gamma(v) \subset \Gamma_{3/2}(v)$$

and

$$B'_{\eta_0}(x_0) \cap \Lambda(v) = B'_{\eta_0}(x_0) \cap \{x_{n-1} \leq g(x'')\}$$

for  $g \in C^{1,\beta}(\mathbb{R}^{n-2})$  with a universal exponent  $\beta \in (0, 1)$ , after a possible rotation of coordinate axes in  $\mathbb{R}^{n-1}$ .

Thank you!