The Ricci flow and its solitons for homogeneous manifolds and the Alekseevskii conjecture

Jorge Lauret, UN Córdoba, Argentina

Marburg, July 6th, 2012

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$$\mathcal{H}_{\boldsymbol{q},\boldsymbol{n}}:=\left\{\mu\in\Lambda^{2}\mathfrak{g}^{*}\otimes\mathfrak{g}:(\mathsf{i})\text{-}(\mathsf{iv})\checkmark\right\}\subset\mathcal{L}_{\boldsymbol{q}+\boldsymbol{n}}.$$

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 variety of Lie algebras

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 $\mathcal{H}_{0,n} = \mathcal{L}_n$ variety of Lie algebras \leftrightarrow left-invariant metrics on all *n*-dimensional s.c. Lie groups.

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• Fix $J : \mathfrak{p} \to \mathfrak{p}, J^2 = -I,$

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$$\begin{split} \mathfrak{g} &= \mathfrak{k} \oplus \mathfrak{p}, \\ \bullet \ \mathsf{Fix} \ J: \mathfrak{p} \to \mathfrak{p}, \ J^2 &= -I, \quad + \quad (\mathsf{iv})' \ [\mathsf{ad}_\mu \, \mathfrak{k}|_\mathfrak{p}, J] = 0, \end{split}$$

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Geometric structures

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• Analogously: Symplectic, Hyper-complex, etc.

Geometric structures

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Deformation theory, convergence, invariants, critical points of functionals, evolution equations ???

Geometric structures

g = 𝔅 ⊕ 𝔅,
Fix J : 𝔅 → 𝔅, J² = −I, + (iv)' [ad_μ 𝔅|_𝔅, J] = 0, μ ∈ ℋ_{q,n} ↔ (G_μ/K_μ, J) almost-complex homogeneous space.
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Deformation theory, convergence, invariants, critical points of functionals, evolution equations ???

(only q = 0 and μ nilpotent has been explored).

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$$\mathfrak{g} = \mathfrak{k} \oplus \mathfrak{p}, \quad \mathcal{H}_{q,n} \subset \mathcal{L}_{q+n} \subset \Lambda^2 \mathfrak{g}^* \otimes \mathfrak{g},$$

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$$\mu \in \mathcal{H}_{q,n}, \ h := \begin{bmatrix} h_q & 0 \\ 0 & h_n \end{bmatrix} \in \mathrm{GL}_{q+n}, \qquad [h_n^t h_n, \mathrm{ad}_\mu \, \mathfrak{k}|_{\mathfrak{p}}] = 0.$$

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$$\mu \in \mathcal{H}_{q,n}, \ h := \begin{bmatrix} q & \\ 0 & h_n \end{bmatrix} \in \operatorname{GL}_{q+n}, \qquad \begin{bmatrix} h_n^* h_n, \operatorname{ad}_{\mu} \mathfrak{e}|_{\mathfrak{p}} \end{bmatrix} = 0.$$
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Lie injectivity radius of ($\mathcal{G}_{\mu}/\mathcal{K}_{\mu}, g_{\mu}$), $\mu \in \mathcal{H}_{q,n}$,

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 $r_{\mu} := \sup \left\{ r > 0 : \pi_{\mu} \circ \exp_{\mu} : B(0, r) \to G_{\mu}/K_{\mu} \quad \text{diffeomorphism}
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Theorem (JL 2010) $\mu_k, \lambda \in \mathcal{H}_{q,n}$ • $\mu_k \to \lambda \Rightarrow (G_{\mu_k}/K_{\mu_k}, g_{\mu_k}) \to (G_{\lambda}/K_{\lambda}, g_{\lambda})$ infinitesimally

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- $(G_{\mu_k}/K_{\mu_k}, g_{\mu_k}) \rightarrow (G_{\lambda}/K_{\lambda}, g_{\lambda})$ locally (smooth on fixed open neighborhoods of the origins).
- $(G_{\mu_k}/K_{\mu_k}, g_{\mu_k}) \rightarrow (G_{\lambda}/K_{\lambda}, g_{\lambda})$ pointed (or Cheeger-Gromov), after passing to a subsequence.

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- $g_{\mu_k} \to g_{\lambda}$ smoothly on $\mathbb{R}^n \equiv \mathfrak{g}$, provided all μ_k are completely solvable (e.g. nilpotent).

Examples of singular behavior

• A sequence $\mu_k \in \mathcal{H}_{1,7}$ of Aloff-Wallach spaces $(SU(3)/S_{p,q}^1)$

• A sequence $\mu_k \in \mathcal{H}_{1,7}$ of Aloff-Wallach spaces $(\mathrm{SU}(3)/S^1_{p,q})$ which infinitesimally converges to another Aloff-Wallach space λ , but such that it does not admit any pointed or local convergent subsequence.

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- A divergent sequence $\mu_k \in \mathcal{H}_{0,3}$ of left-invariant metrics on $\widetilde{\operatorname{SL}}_2(\mathbb{R})$

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- A divergent sequence $\mu_k \in \mathcal{H}_{0,3}$ of left-invariant metrics on $\widetilde{\mathrm{SL}}_2(\mathbb{R})$ which nevertheless pointed converges to $\mathbb{R} \times H^2$.

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- A divergent sequence $\mu_k \in \mathcal{H}_{0,3}$ of left-invariant metrics on $SL_2(\mathbb{R})$ which nevertheless pointed converges to $\mathbb{R} \times H^2$. μ_k is actually isometric to a convergent sequence in $\mathcal{H}_{1,3}$.

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- A sequence μ_k ∈ H_{1,5} of homogeneous metrics on S³ × S² converging to λ ∉ H_{1,5}.

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- A divergent sequence $\mu_k \in \mathcal{H}_{0,3}$ of left-invariant metrics on $SL_2(\mathbb{R})$ which nevertheless pointed converges to $\mathbb{R} \times H^2$. μ_k is actually isometric to a convergent sequence in $\mathcal{H}_{1,3}$.
- A sequence μ_k ∈ H_{1,5} of homogeneous metrics on S³ × S² converging to λ ∉ H_{1,5}. However, λ can be viewed as an element of H_{2,4}, giving rise to a collapsing of the μ_k with bounded curvature to a metric on S² × S².

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 $H_{\mu} \in \mathfrak{p}, \quad \langle H_{\mu}, X \rangle = \operatorname{tr} \operatorname{ad}_{\mu} X \text{ (unimodularity)}$

$$\begin{split} \mu \in \mathcal{H}_{q,n}, \quad \operatorname{Ric}_{\mu} : \mathfrak{p} \to \mathfrak{p} \text{ given by} \\ \hline \operatorname{Ric}_{\mu} = M_{\mu} - \frac{1}{2}B_{\mu} - S(\operatorname{ad}_{\mu}H_{\mu}|_{\mathfrak{p}}) \\ \langle B_{\mu}X, Y \rangle &= \operatorname{tr}\operatorname{ad}_{\mu}X \operatorname{ad}_{\mu}Y \text{ (Killing form),} \\ H_{\mu} \in \mathfrak{p}, \quad \langle H_{\mu}, X \rangle &= \operatorname{tr}\operatorname{ad}_{\mu}X \text{ (unimodularity)} \\ \operatorname{tr} M_{\mu}E &= \frac{1}{4}\langle \pi(E)\mu_{\mathfrak{p}}, \mu_{\mathfrak{p}} \rangle, \quad \forall E \in \operatorname{End}(\mathfrak{p}) \end{split}$$

 $\mu \in \mathcal{H}_{q,n}$, $\operatorname{Ric}_{\mu} : \mathfrak{p} \to \mathfrak{p}$ given by $\operatorname{Ric}_{\mu} = M_{\mu} - \frac{1}{2}B_{\mu} - S(\operatorname{ad}_{\mu}H_{\mu}|_{\mathfrak{p}})|,$ $\langle B_{\mu}X, Y \rangle = \operatorname{tr} \operatorname{ad}_{\mu} X \operatorname{ad}_{\mu} Y$ (Killing form), $H_{\mu} \in \mathfrak{p}, \quad \langle H_{\mu}, X \rangle = \operatorname{tr} \operatorname{ad}_{\mu} X \text{ (unimodularity)}$ tr $M_{\mu}E = \frac{1}{4} \langle \pi(E)\mu_{\mathfrak{p}}, \mu_{\mathfrak{p}} \rangle$, $\forall E \in \text{End}(\mathfrak{p})$ (moment map for the linear action $GL(\mathfrak{p}) \circlearrowleft \Lambda^2 \mathfrak{p}^* \otimes \mathfrak{p}$)

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 M_{μ} and H_{μ} depends only on $\mu_{\mathfrak{p}}$, where $\forall X, Y \in \mathfrak{p}$,

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g(t) Ricci flow starting at the homogeneous manifold

$$(M,g_0)=\left({{{{G}_{{\mu _0}}}}/{{K_{{\mu _0}}}},{g_{{\mu _0}}}}
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Ricci flow on $\mathcal{H}_{q,n}$???

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(3)

$$(M,g_0)=(\mathit{G}_{\mu_0}/\mathit{K}_{\mu_0},g_{\mu_0}), \quad \mu_0\in\mathcal{H}_{q,n}, \quad (ext{recall }\mathfrak{g}=\mathfrak{k}\oplus\mathfrak{p}),$$

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Theorem (JL 2010)

 $\exists \ arphi(t): \textit{M} = \textit{G}_{\mu_0} / \textit{K}_{\mu_0} \longrightarrow \textit{G}_{\mu(t)} / \textit{K}_{\mu(t)}$ such that

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$(M,g(t)), \quad \left(G_{\mu_0}/K_{\mu_0},g_{\langle\cdot,\cdot\rangle_t}\right), \quad \left(G_{\mu(t)}/K_{\mu(t)},g_{\mu(t)}\right),$

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•
$$\mu(t)|_{\mathfrak{k}\times\mathfrak{g}}\equiv\mu_0|_{\mathfrak{k}\times\mathfrak{g}}.$$

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G nilpotent and s.c., $K = \{e\}$,

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G nilpotent and s.c., $K = \{e\}$, $\mathfrak{g} = \mathfrak{p} = \mathbb{R}^n = G$,

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G nilpotent and s.c., $K = \{e\}$, $\mathfrak{g} = \mathfrak{p} = \mathbb{R}^n = G$, μ nilpotent Lie bracket on \mathfrak{g} ,

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negative gradient flow of the square norm of the moment map for the action $\operatorname{GL}_n \circlearrowleft \Lambda^2 \mathfrak{g}^* \otimes \mathfrak{g}$.

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Theorem (JL 2009)

• The Ricci flow g(t) is a type-III solution

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[Guzhvina 2008] Bracket flow for nilmanifolds with applications to almost-flat manifolds.

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[Arroyo 2012] Application to Ricci flow of 4-dim homogeneous manifolds and to Ricci flow of solvmanifolds.

Example in dim = 3

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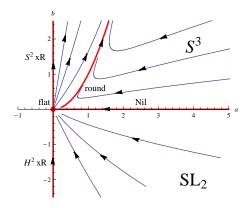


Figure: Phase plane for the ODE system

Jorge Lauret, UN Córdoba, Argentina () The Ricci flow and its solitons for homogenee Marburg, July 6th, 2012 16 / 28

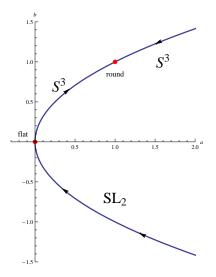


Figure: Volume-normalized bracket flow

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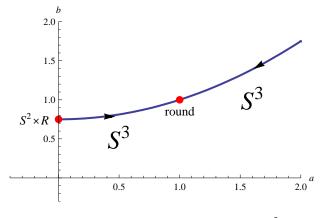


Figure: *R*-normalized bracket flows: $R \equiv \frac{3}{2}$.

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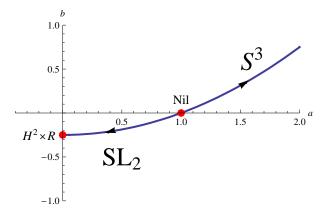


Figure: *R*-normalized bracket flows: $R \equiv -\frac{1}{2}$.

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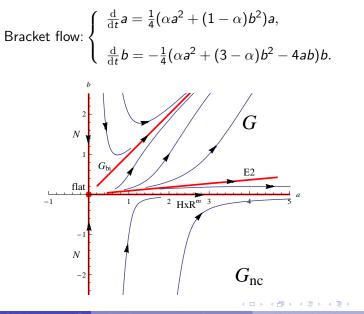
Bracket flow:
$$\begin{cases} \frac{\mathrm{d}}{\mathrm{d}t}a = \frac{1}{4}(\alpha a^2 + (1-\alpha)b^2)a, \\ \\ \frac{\mathrm{d}}{\mathrm{d}t}b = -\frac{1}{4}(\alpha a^2 + (3-\alpha)b^2 - 4ab)b. \end{cases}$$

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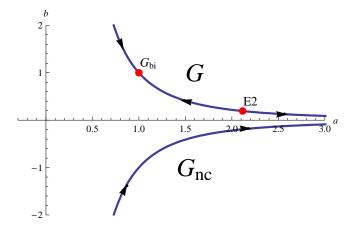


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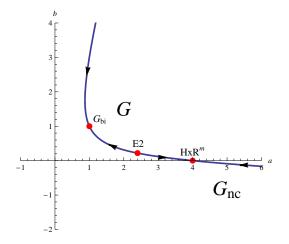


Figure: *R*-normalized bracket flow: $R \equiv 2$

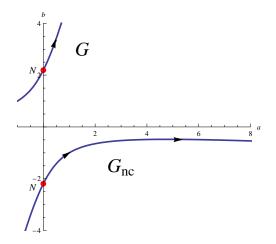


Figure: *R*-normalized bracket flow: $R \equiv -3$

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[Ivey, Naber, Perelman, Petersen-Wylie]

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Classification and structure of solvsolitons: [Lafuente, Will, JL, ...]

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- Any (nonflat) Ricci soliton solvmanifold is isometric to a simply connected solvsoliton.
- Any homogeneous Ricci soliton (M,g) is a semi-algebraic soliton with respect to its full isometry group G = lsom(M,g).

Open questions:

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Alekseevskii's conjecture [Besse, 80's]. Any Einstein connected homogeneous Riemannian manifold of negative scalar curvature is diffeomorphic to a Euclidean space.

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Theorem (Lafuente-JL 2012)

Any example of an algebraic soliton which is not a solvsoliton gives rise to a counterexample to the Alekseevskii conjecture.

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Assume $\mathfrak{g} = \mathfrak{k} \oplus \mathfrak{p}$ is \perp -Killing, and consider the orthogonal decomposition $\mathfrak{p} = \mathfrak{h} \oplus \mathfrak{n}$, where \mathfrak{n} is the nilradical of \mathfrak{g} .

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- $\operatorname{Ric}_{\mathfrak{u}} = cI + C_{\mathfrak{h}}$, where $\operatorname{Ric}_{\mathfrak{u}}$ is the Ricci operator of U/K with $\mathfrak{u} = \mathfrak{k} \oplus \mathfrak{h}$ and $\langle C_{\mathfrak{h}}Y, Y \rangle = \operatorname{tr} Symm(\operatorname{ad} Y|_{\mathfrak{n}})^2$, $\forall Y \in \mathfrak{h}$.

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- Ric_n = cl + D₁, for some D₁ ∈ Der(n), where Ric_n denotes the Ricci operator of (n, ⟨·, ·⟩|_{n×n}) (nilsoliton).

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- $\sum [ad Y_i|_n, (ad Y_i|_n)^t] = 0$, where $\{Y_i\}$ is any orthonormal basis of \mathfrak{h}

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- $[\mathfrak{h},\mathfrak{h}] \subset \mathfrak{k} \oplus \mathfrak{h}$. In particular, $\mathfrak{u} := \mathfrak{k} \oplus \mathfrak{h}$ is a reductive Lie subalgebra of \mathfrak{g} and $\mathfrak{g} = \mathfrak{u} \ltimes \mathfrak{n}$.
- $\operatorname{Ric}_{\mathfrak{u}} = cI + C_{\mathfrak{h}}$, where $\operatorname{Ric}_{\mathfrak{u}}$ is the Ricci operator of U/K with $\mathfrak{u} = \mathfrak{k} \oplus \mathfrak{h}$ and $\langle C_{\mathfrak{h}}Y, Y \rangle = \operatorname{tr} Symm(\operatorname{ad} Y|_{\mathfrak{n}})^2$, $\forall Y \in \mathfrak{h}$.
- Ric_n = cl + D₁, for some D₁ ∈ Der(n), where Ric_n denotes the Ricci operator of (n, ⟨·, ·⟩|_{n×n}) (nilsoliton).
- $\sum [\operatorname{ad} Y_i|_{\mathfrak{n}}, (\operatorname{ad} Y_i|_{\mathfrak{n}})^t] = 0$, where $\{Y_i\}$ is any orthonormal basis of \mathfrak{h} (\Rightarrow (ad $Y|_{\mathfrak{n}})^t \in \operatorname{Der}(\mathfrak{n})$ for all $Y \in \mathfrak{h}$).

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