

$$\psi_3^{\mathbb{R}} = \begin{bmatrix} \psi_3 \\ \tilde{\psi}_3 \end{bmatrix}$$

$$\psi_3 = \begin{bmatrix} \psi_{d_R} & \psi_{e_R} & \psi_{u_R} & \psi_{d_L} & \psi_{e_L} & \psi_{u_L} & \psi_{\nu_L} \end{bmatrix} = \begin{bmatrix} \psi_R \\ \psi_L \end{bmatrix}$$

$$\psi_R = \underbrace{\psi_{d_R}} \psi_{e_R} \psi_{u_R} = \begin{bmatrix} \psi_d \mathbf{\Sigma} \begin{bmatrix} d_R \\ e_R \end{bmatrix} \\ \psi_u \mathbf{\Sigma} u_R \end{bmatrix}$$

$$\psi_L = \begin{bmatrix} \psi_{d_L} \\ \psi_{e_L} \\ \psi_{u_L} \\ \psi_{\nu_L} \end{bmatrix} = \Psi \mathbf{\Sigma} \begin{bmatrix} q_L \\ \ell_L \end{bmatrix}$$

$$\tilde{\psi}_3 = \begin{bmatrix} \psi_{\bar{d}_R} & \psi_{\bar{e}_R} & \psi_{\bar{u}_R} & \psi_{\bar{d}_L} & \psi_{\bar{e}_L} & \psi_{\bar{u}_L} & \psi_{\bar{\nu}_L} \end{bmatrix} = \begin{bmatrix} \bar{\psi}_R \\ \bar{\psi}_L \end{bmatrix}$$

$$\bar{\psi}_R = \begin{bmatrix} \psi_{\bar{d}_R} \\ \psi_{\bar{e}_R} \\ \psi_{\bar{u}_R} \end{bmatrix}$$

$$\bar{\psi}_L = \begin{bmatrix} \psi_{\bar{d}_L} \\ \psi_{\bar{e}_L} \\ \psi_{\bar{u}_L} \\ \psi_{\bar{\nu}_L} \end{bmatrix}$$

$$Q_3^{\mathbb{R}} = \frac{Q_3}{0} \left| \begin{array}{c} 0 \\ -Q_3 \end{array} \right.$$

$$3Q_3 = \begin{array}{ccc|c} -1 & 0 & 0 & \\ \hline 0 & -3 & 0 & 0 \\ \hline 0 & 0 & 2 & \\ \hline 0 & & & \left[ \begin{array}{cccc} -1 & 0 & 0 & 0 \\ 0 & -3 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] \end{array}$$

$$\begin{bmatrix} d_R \\ e_R \\ u_R \\ d_L \\ e_L \\ u_L \\ \nu_L \end{bmatrix} = \begin{bmatrix} d_R \\ e_R \\ u_R \\ d_L \\ e_L \\ u_L \\ \nu_L \end{bmatrix}$$

$$I_3^{\mathbb{R}} = \frac{I_3 \mid 0}{0 \mid \tilde{I}_3}$$

$$I_3 = \frac{\frac{I\mathbf{x} \mid x/3 \mid 0}{0 \mid y} \mid 0 \mid 0}{0 \mid I\mathbf{x}x/3 \mid 0} \mid \frac{I\mathbf{x} \mid x/3 \mid 0}{0 \mid y}$$

$$\tilde{I}_3 = \frac{\frac{I\mathbf{x} \mid \tilde{x}/3 \mid 0}{0 \mid \tilde{y}} \mid 0 \mid 0}{0 \mid I\mathbf{x}\tilde{x} \mid 0} \mid \frac{I\mathbf{x} \mid \tilde{x}/3 \mid 0}{0 \mid \tilde{y}}$$

$$3Q_3 = \frac{\frac{\frac{I\mathbf{x} \mid x/3 \mid 0}{0 \mid y} \mid 0 \mid 0}{0 \mid I\mathbf{x}x/3 \mid 0} \mid 0}{0 \mid 0 \mid \frac{I\mathbf{x} \mid x/3 \mid 0}{0 \mid y}} \mid \frac{\frac{I\mathbf{x} \mid \tilde{x}/3 \mid 0}{0 \mid \tilde{y}} \mid 0 \mid 0}{0 \mid I\mathbf{x}\tilde{x} \mid 0} \mid \frac{I\mathbf{x} \mid \tilde{x}/3 \mid 0}{0 \mid \tilde{y}}$$

$$\Gamma_3^{\mathbb{R}} = \begin{bmatrix} \Gamma\mathbf{x}1_R & 0 & 0 & 0 \\ 0 & -\Gamma\mathbf{x}1_L & 0 & 0 \\ 0 & 0 & -\varkappa\Gamma\mathbf{x}\bar{1}_R & 0 \\ 0 & 0 & 0 & \varkappa\Gamma\mathbf{x}\bar{1}_L \end{bmatrix} = \frac{\Gamma_3 \mid 0}{0 \mid -\varkappa\Gamma_3} = \frac{\Gamma_3 \mid 0}{0 \mid \varkappa J\Gamma_3 J}$$

$$\Gamma_3 = \frac{\frac{\Gamma\mathbf{x} \mid 1 \mid 0}{0 \mid 1} \mid 0 \mid 0}{0 \mid \Gamma\mathbf{x}1 \mid 0} \mid \frac{-\Gamma\mathbf{x} \mid 1 \mid 0}{0 \mid 1}$$

$$\tilde{I} = \gamma^0 \gamma^{2-}$$

$$J_3^{\mathbb{R}} = \begin{bmatrix} 0 & 0 & \tilde{I} \mathbf{x} \bar{1}_R & 0 \\ 0 & 0 & 0 & \tilde{I} \mathbf{x} \bar{1}_L \\ -\varkappa \tilde{I} \mathbf{x} \bar{1}_R & 0 & 0 & 0 \\ 0 & -\varkappa \tilde{I} \mathbf{x} \bar{1}_L & 0 & 0 \end{bmatrix} = \frac{0 \mid J_3}{-\varkappa J_3 \mid 0}$$

$$J_3 = \frac{\tilde{I} \mathbf{x} \begin{array}{c|c} 1 & 0 \\ \hline 0 & \bar{1} \end{array}}{0 \mid \tilde{I} \mathbf{x} \bar{1}} \mid \begin{array}{c|c} 0 & 0 \\ \hline 0 & \tilde{I} \mathbf{x} \begin{array}{c|c} 1 & 0 \\ \hline 0 & \bar{1} \end{array} \end{array}$$

$$\left(J_3^{\mathbb{R}}\right)^2 = \varkappa \text{id}$$

$$\varkappa = \begin{cases} -1 & p = d/2 = 2 + + + + \\ 1 & p = 3 + - - - \end{cases}$$

$$\frac{0 \mid J_3}{-\varkappa J_3 \mid 0} \frac{0 \mid J_3}{-\varkappa J_3 \mid 0} = \frac{-\varkappa J_3^2 \mid 0}{0 \mid -\varkappa J_3^2} = \frac{\varkappa \mid 0}{0 \mid \varkappa} \Leftarrow J_3^2 = -I$$

$$\Gamma_3^{\mathbb{R}} J_3^{\mathbb{R}} = -\varkappa J_3^{\mathbb{R}} \Gamma_3^{\mathbb{R}} \Leftarrow \Gamma^{\sim} = \sim \Gamma$$

$$\Gamma_3^{\mathbb{R}} J_3^{\mathbb{R}} = \begin{bmatrix} \Gamma \mathbf{x} \bar{1}_R & 0 & 0 & 0 \\ 0 & -\Gamma \mathbf{x} \bar{1}_L & 0 & 0 \\ 0 & 0 & -\varkappa \Gamma \mathbf{x} \bar{1}_R & 0 \\ 0 & 0 & 0 & \varkappa \Gamma \mathbf{x} \bar{1}_L \end{bmatrix}$$

$$\begin{bmatrix} 0 & 0 & \tilde{I} \mathbf{x} \bar{1}_R & 0 \\ 0 & 0 & 0 & \tilde{I} \mathbf{x} \bar{1}_L \\ -\varkappa \tilde{I} \mathbf{x} \bar{1}_R & 0 & 0 & 0 \\ 0 & -\varkappa \tilde{I} \mathbf{x} \bar{1}_L & 0 & 0 \end{bmatrix} =$$

$$\begin{bmatrix} 0 & 0 & \tilde{\Gamma} \mathbf{x} \bar{1}_R & 0 \\ 0 & 0 & 0 & -\tilde{\Gamma} \mathbf{x} \bar{1}_L \\ \tilde{\Gamma} \mathbf{x} \bar{1}_R & 0 & 0 & 0 \\ 0 & -\tilde{\Gamma}_{(8)} \mathbf{x} \bar{1}_L & 0 & 0 \end{bmatrix}$$

$$J_3^{\mathbb{R}} \Gamma_3^{\mathbb{R}} = \begin{bmatrix} 0 & 0 & \tilde{I} \mathbf{z} \bar{1}_R & 0 \\ 0 & 0 & 0 & \tilde{I} \mathbf{z} \bar{1}_L \\ -\varkappa \tilde{I} \mathbf{z} \bar{1}_R & 0 & 0 & 0 \\ 0 & -\varkappa \tilde{I} \mathbf{z} \bar{1}_L & 0 & 0 \end{bmatrix} \begin{bmatrix} \Gamma \mathbf{z} \bar{1}_R & 0 & 0 & 0 \\ 0 & -\Gamma \mathbf{z} \bar{1}_L & 0 & 0 \\ 0 & 0 & -\varkappa \Gamma \mathbf{z} \bar{1}_R & 0 \\ 0 & 0 & 0 & \varkappa \Gamma \mathbf{z} \bar{1}_L \end{bmatrix} =$$

$$\varkappa \begin{bmatrix} 0 & 0 & -\tilde{\Gamma} \mathbf{z} \bar{1}_R & 0 \\ 0 & 0 & 0 & \tilde{\Gamma} \mathbf{z} \bar{1}_L \\ -\tilde{\Gamma} \mathbf{z} \bar{1}_R & 0 & 0 & 0 \\ 0 & \tilde{\Gamma} \mathbf{z} \bar{1}_L & 0 & 0 \end{bmatrix}$$

$$\Gamma_3^{\mathbb{R}} J_3^{\mathbb{R}} = \frac{\Gamma_3}{0} \left| \begin{array}{c} 0 \\ -\varkappa \Gamma_3 \end{array} \right| \frac{0}{-\varkappa J_3} \left| \begin{array}{c} J_3 \\ 0 \end{array} \right| = \frac{0}{\Gamma_3 J_3} \left| \begin{array}{c} \Gamma_3 J_3 \\ 0 \end{array} \right| J_3^{\mathbb{R}} \Gamma_3^{\mathbb{R}} = \frac{0}{-\varkappa J_3} \left| \begin{array}{c} J_3 \\ 0 \end{array} \right| \frac{\Gamma_3}{0} \left| \begin{array}{c} 0 \\ -\varkappa \Gamma_3 \end{array} \right|$$

$$= \frac{0}{-\varkappa J_3 \Gamma_3} \left| \begin{array}{c} -\varkappa J_3 \Gamma_3 \\ 0 \end{array} \right| = -\varkappa \Gamma_3^{\mathbb{R}} J_3^{\mathbb{R}} \leftarrow J_3 \Gamma_3 = \Gamma_3 J_3$$