

$$c \in \Pi \subset X$$

$$\underline{\Pi}_c = X_c^{1/2}$$

$$v \in X_c^{1/2} \Rightarrow {}^*c v - v {}^*c \in \text{aut } X = \mathfrak{k}_{\mathbb{R}} \Rightarrow e^{*c v - v {}^*c} \in \text{Aut } X = K_{\mathbb{R}}$$

$${}^{2c-e}e^{*c v - v {}^*c} = \underbrace{2c - e + v}_{-1/2} \underbrace{e + v^2}_{-1/2} = \underbrace{2c - e + v}_{-1/2} P_{e+v^2}^{-1/4} \in {}^j_j K_{\mathbb{R}} \text{ symm}$$

$$\text{symm } \ell_v = P_{\underbrace{2c - e + v}_{-1/2} \underbrace{e + v^2}_{-1/2}} = P_{2c - e + v} P_{e + v^2}^{-1/2} \in \text{Aut } X = K_{\mathbb{R}}$$

$$\text{LHS} = P_{\underbrace{2c - e + v}_{-1/2} P_{e + v^2}^{-1/4}} = P_{(e + v^2)^{-1/4}} P_{2c - e + v} P_{(e + v^2)^{-1/4}} = P_{e + v^2}^{-1/4} P_{2c - e + v} P_{e + v^2}^{-1/4} = \text{RHS}$$

$${}^u \mathbf{1} = {}^c \ell_v = c P_{2c - e + v} P_{e + v^2}^{-1/2} = \underbrace{c + v + v c v}_{-1} \overbrace{e + v^2}^{-1}$$

$$s_v = {}^{2c-e} \ell_v = \underbrace{2c - e}_{-1} P_{2c - e + v} P_{e + v^2}^{-1/2} = \underbrace{2c - e + 2v + 2v c v - v^2}_{-1} \overbrace{e + v^2}^{-1} = 2 \underbrace{c + v + v c v}_{-1} \overbrace{e + v^2}^{-1} - e$$

$$\begin{cases} u \in X_c^1 \\ v \in X_c^{1/2} \\ w \in X_c^0 \end{cases} \Rightarrow \begin{cases} {}^{2c-e+u+w} \ell_v \in {}^j_j \mathcal{D}_{\mathbb{R}} \\ s_v = {}^{2c-e} \ell_v \in {}^j_j K_{\mathbb{R}} \end{cases}$$

$${}^u \mathbf{1} = \frac{e + s_v}{2} \in X_v^1$$

$${}^w \mathbf{1} = \frac{e - s_v}{2} = e - {}^u \mathbf{1} \in X_v^0$$

$$X_c^1 \ni u \Rightarrow u P_{c+v} \in X_v^1 = X_c^1 P_{c+v}$$

$$X_c^0 \ni w \Rightarrow w P_{v+c-e} \in X_v^0 = X_c^0 P_{v+c-e}$$

$$x = {}^{2c-e+u+w}l_v = s_v + \underline{u+w}l_v$$

$$\dot{u} \overbrace{\partial_u \varphi}^x = \dot{u} l_v \underline{x} \varphi$$

$$\dot{w} \overbrace{\partial_w \varphi}^x = \dot{w} l_v \underline{x} \varphi$$

$$\text{basis } \frac{\begin{smallmatrix} \mathbf{1} \\ \mathbf{1} \\ \mathbf{1} \end{smallmatrix}}{\begin{smallmatrix} \mathbf{1} \\ \mathbf{1} \\ \mathbf{1} \end{smallmatrix}} \text{ von } X_v^1 \times X_v^0$$

$$\dot{u} : \dot{w} \in U \times W \xrightarrow[\text{lin}]{l_v = \mathbf{1}} X \ni \underline{\dot{u} + \dot{w}} l_v$$

$$\frac{\partial \varphi}{\partial \mathcal{V}^i} d_i \mathbf{1} = [\partial_u \varphi \quad \partial_w \varphi] dl_v$$

$$[\dot{u} \partial_u \varphi \quad \dot{w} \partial_w \varphi] dl_v = \left[\dot{u} l_v \underline{x} \varphi \quad \dot{w} l_v \underline{x} \varphi \right] dl_v$$