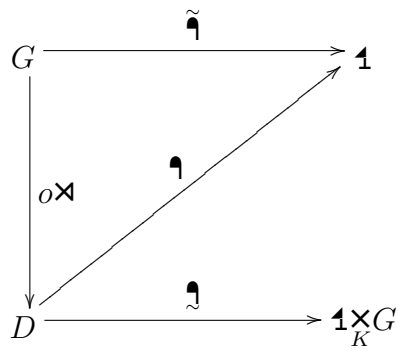


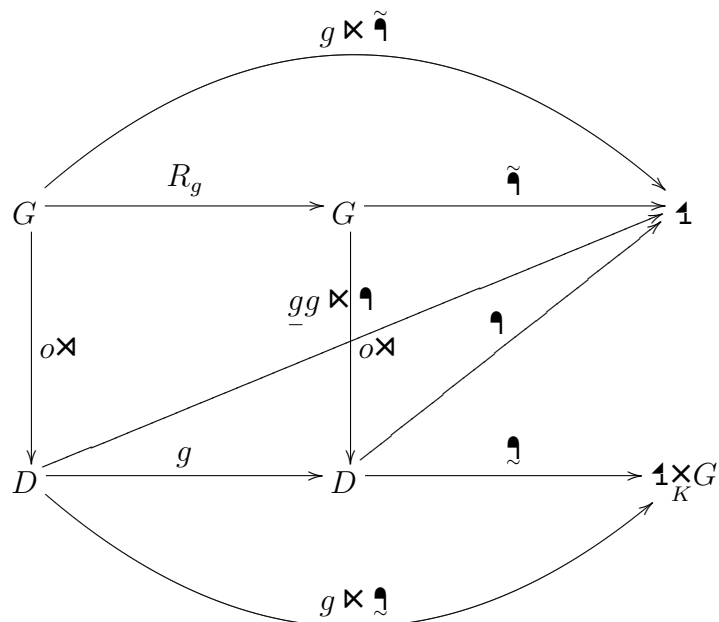
$$\begin{aligned}
 x\tilde{\eta} &= \gamma_x : \gamma_x \tilde{\eta} \\
 \begin{cases} \gamma_x \tilde{\eta} = {}^o\gamma_x \tilde{\eta} \\ g\tilde{\eta} = {}^og \tilde{\eta} \end{cases}
 \end{aligned}$$

cocycle  $x:g \in D \times G \rightarrow K^{\mathbb{C}} \ni xg$



$$\mathbf{1} \ni \begin{cases} \gamma_x \tilde{\eta} = {}_{1/2}^x B_x \tilde{\eta} \\ g\tilde{\eta} = {}^og \tilde{\eta} \end{cases} \Rightarrow {}^{kg} \tilde{\eta} = {}^okg \tilde{\eta} = {}^ok {}^og \tilde{\eta} = {}^ok {}^og \tilde{\eta} = {}^ok {}^{g\tilde{\eta}}$$

$$\mathbf{1} \times (og) \ni \begin{cases} {}^{og} \tilde{\eta} = {}^{g\tilde{\eta}} : g = {}^og \tilde{\eta} : g \\ {}^x \tilde{\eta} = \gamma_x \tilde{\eta} : \gamma_x = {}_{1/2}^x B_x \tilde{\eta} : \gamma_x \end{cases}$$



$${}^y \overline{g \times \tilde{q}} = {}^y \overline{R_g \tilde{q}} = {}^{yg} \tilde{q} \Rightarrow {}^{ky} \overline{g \times \tilde{q}} = {}^{ky} \cdot g \tilde{q} = {}^{k \cdot yg} \tilde{q} = {}^{\underline{k}} \overline{{}^{yg} \tilde{q}} = {}^{\underline{k}} \overline{{}^y \overline{g \times \tilde{q}}}$$

$$\underline{{}^y \overline{gg \times \tilde{q}}} = \underline{{}^{\circ y} \overline{{}^{\circ y} \overline{gg \times \tilde{q}}}} = \underline{{}^{\circ y} \overline{{}^{\circ y} g \tilde{q}}} = \underline{{}^{\circ yg} \overline{{}^{\circ y} \tilde{q}}} = \underline{{}^{yg} \tilde{q}} = \underline{{}^y \overline{R_g \tilde{q}}}$$

$$\underline{{}^g \overline{\dot{k} \times \tilde{q}}} = \underline{\dot{k} \overline{{}^e R_g \times \tilde{q}}}$$

$$\text{LHS} = {}^0 \partial_t \overline{{}^t \epsilon^{\dot{k} g} \tilde{q}} = {}^0 \partial_t \overline{{}^t \epsilon^{\dot{k}} \overline{{}^e R_g \times \tilde{q}}} = \text{RHS}$$

$$\mathfrak{b} \in \underline{G} \Rightarrow \mathfrak{b}_g = \mathfrak{b} \underline{R_g} \in \underline{G}_g$$

$$x: \mathfrak{b} \in \underline{D} \times \underline{G} \xrightarrow{\times} \underline{D} \ni \mathfrak{b}_x$$

$$\mathfrak{b}_{og} = \mathfrak{b}_g \underline{o}^g \times$$

$$\overline{g \nabla_{\underline{b}_o g}} \mathfrak{A} = \underline{\bar{b}}^e \underline{R_g} \times \tilde{\mathfrak{A}}$$

$$\text{LHS} = \overline{g \nabla_{\underline{b}_o g} \mathfrak{A}} = \underline{\bar{b}} \underline{R_g} \overline{g \mathfrak{A}} - \overline{\underline{\bar{b}} \times \tilde{\mathfrak{A}}} = \underline{\bar{b}} \underline{R_g} \times \tilde{\mathfrak{A}} - \underline{\bar{b}}^e \underline{R_g} \times \tilde{\mathfrak{A}} = \underline{\bar{b} - \bar{b}^e} \underline{R_g} \times \tilde{\mathfrak{A}} = \text{RHS}$$

$$\underline{o} g^{-1} \overline{y R_g \times \tilde{\mathfrak{A}}} = \underline{o} g \underline{y} \times g \overline{y R_g \times o \times \mathfrak{A}}$$

$$\overline{y R_g \times \tilde{\mathfrak{A}}} = \underline{y} g \tilde{\mathfrak{A}} = \underline{o} y g \underline{o} y g \mathfrak{A} = \underline{o} g g^{-1} y g \underline{o} y g \mathfrak{A} = \underline{o} g \underline{o} g^{-1} y g \underline{o} y g \mathfrak{A} = \underline{o} g \underline{o} g \underline{y} \times g \underline{o} y g \mathfrak{A} = \text{RHS}$$

$$\overline{x \nabla_x \mathfrak{A}} = \underline{\dot{x}} \underline{x} \mathfrak{A} - \underline{\dot{x}} \bullet \underline{\dot{x}} \times \underline{x} \mathfrak{A}$$

$$\begin{aligned} \overline{y R_g \times \tilde{\mathfrak{A}}} &= \underline{y} g \tilde{\mathfrak{A}} = \underline{o} y g \underline{o} y g \mathfrak{A} = \underline{o} y g \overline{y R_g \times o \times \mathfrak{A}} \\ \underline{\bar{b}}^e \underline{R_g} \times o \times \mathfrak{A} &= \underline{\bar{b}} \underline{R_g} o \underline{g} \times \underline{o} g \mathfrak{A} = \underline{\bar{b}} \underline{R_g} o \underline{g} \times \underline{o} g \mathfrak{A} = \underline{\dot{x}} \underline{x} \mathfrak{A} \\ \underline{o} g \overline{x \nabla_x \mathfrak{A}} &= \underline{g} \overline{\underline{\nabla_x \mathfrak{A}}} = \underline{g} \overline{\underline{\nabla_{\underline{b}_o g} \mathfrak{A}}} = \underline{\bar{b}}^e \underline{R_g} \times \tilde{\mathfrak{A}} = \underline{\bar{b}}^e \underline{o} y g \overline{y R_g \times o \times \mathfrak{A}} \\ &= \underline{\bar{b}}^e \underline{o} y g \overline{y R_g \times o \times \mathfrak{A}} + \underline{o} g \underline{\bar{b}}^e \underline{R_g} \times o \times \mathfrak{A} = \underline{\bar{b}}^e \underline{o} y g \underline{x} \mathfrak{A} + \underline{o} g \underline{\dot{x}} \underline{x} \mathfrak{A} \\ \underline{o} y g &= \underline{o} g g^{-1} y g = \underline{o} g \underline{g^{-1} y g} = \underline{o} g \underline{x} y \times g \\ \underline{\bar{b}}^e \underline{o} y g &= \underline{o} g \underline{\bar{b}}^e \underline{x} \mathfrak{A} g = \underline{o} g \underline{\bar{b}}^e \underline{x} \mathfrak{A} g = \underline{o} g \underline{\bar{b}}^e \underline{x} \mathfrak{A} g \end{aligned}$$

$$\begin{aligned} \underline{\bar{b}} \times g_{wg} &= \underline{\bar{b}}_w \underline{w} g \Rightarrow \underline{\bar{b}} \times g_x \underline{o} g = \underline{\bar{b}} \times g_{wg_o} = \underline{\bar{b}}_w \underline{w} g_o = \underline{a - w^* a w} \underline{w^{-1} B_{-x}^x} \underline{B_x^{1/2}} = \underline{a - w^* a w} \underline{w^{-1} B_{-x_0}^x} \underline{B_x^{1/2}} \\ \underline{\bar{b}} \times g_x &= \frac{0}{w} \underline{a - w^* a w} \underline{w^{-1} B_{-x}} = \frac{0}{w} \underline{a - w^* a w} \underline{0^{-1} B_{-x}} + \underline{a - 0^* a 0} \underline{w^{-1} B_{-x}} \\ &= -a \underline{0^{-1} B_{-x}} \underline{0_w B_{-x}} \underline{0^{-1} B_{-x}} = -a \underline{0_w B_{-x}} = -a \underline{0} \underline{i + 2w \bullet \dot{x} + Q_w Q_x} = -2a \bullet \dot{x} \end{aligned}$$

$$\bar{b} = \bar{b}^\dagger \times \bar{b}$$

$$\bar{b} : \bar{b} (\nabla \eta) = -\frac{1}{2} \bar{b} \times \bar{b}$$

$$\underline{a - x \dot{a} x} \times \underline{b - x \dot{b} x} = a \bullet \dot{b} - b \bullet \dot{a} \in \bar{b}$$

$$G \xrightarrow{o \times} D = K \neg G$$

$$G \xrightarrow{\infty} 1 \xleftarrow{\times} G \times G \xrightarrow{\infty} 1$$

$${}^g \overline{y \times \eta} = {}^{yg} \eta$$

$${}^g \overline{\bar{b} \times \eta} = {}^0 \partial_t {}^{t \epsilon^b g} \eta$$

$$o^g \times = o g$$

$$o \underline{g} \in K^C$$

$$\dot{x} \in \underline{D}_x$$

$$x = o g$$

$$o \times (\gamma_t g) = o \gamma_t g = \underline{o g} \underline{g^{-1} \gamma_t g} = x \underline{g^{-1} \gamma_t g}$$

$$\Rightarrow \underline{\bar{b} R_g} o^g \times = \underline{\bar{b} \times g}_x = \dot{x}$$

$$\bar{b} {}^e R_g \tilde{\eta} = o \underline{g} {}^x \underline{\bar{b} \times g} {}^x \eta + o \underline{g} {}^x \underline{\bar{b} \times g \times \eta}$$

$$\text{LHS} = {}^0 \partial_t {}^{t \epsilon^b g} \tilde{\eta} = {}^0 \partial_t {}^o \underline{\partial_t \epsilon^b g} {}^{o t \epsilon^b g} \eta = {}^0 \partial_t {}^o \underline{g t \epsilon^b \times g} {}^{o g t \epsilon^b \times g} \eta = {}^0 \partial_t {}^o \underline{g} \underline{\epsilon^b \times g} {}^{x t \epsilon^b \times g} \eta$$

$$= o \underline{g} \underline{{}^0 \partial_t \underline{x t \epsilon^b \times g}} {}^x \eta + o \underline{g} \underline{{}^0 \partial_t \underline{x t \epsilon^b \times g}} {}^x \eta = o \underline{g} \underline{{}^x \partial_t \underline{t \epsilon^b \times g}} {}^x \eta + o \underline{g} \underline{{}^0 \partial_t \underline{x t \epsilon^b \times g}} {}^x \eta = \text{RHS}$$

$${}^x \underline{\nabla_x} \eta = \underline{\bar{b} \times g} {}^x \eta + \underline{\bar{b} \times g \times \eta}$$

$$\begin{aligned}
{}^o \underline{g} \overline{\nabla_x \tilde{\mathfrak{A}}} &= {}^o \underline{g} \overline{\nabla_x \tilde{\mathfrak{A}}} = \underline{g} \overline{\nabla_x \tilde{\mathfrak{A}}} = \underline{g} \overline{\nabla_{\mathfrak{b}_g \circ^g \underline{\mathfrak{X}}} \tilde{\mathfrak{A}}} = \underline{\mathfrak{b}}_g \overline{\tilde{\mathfrak{A}}} - {}^0 \partial_t \overline{\exp t \underline{\mathfrak{b}}_g \circ^g \underline{\mathfrak{X}}} \times \tilde{\mathfrak{A}} \\
&= \underline{\mathfrak{b}} \underline{R}_g \overline{\tilde{\mathfrak{A}}} - {}^0 \partial_t \overline{\exp t \underline{\mathfrak{b}} \circ^g \underline{\mathfrak{X}}} \times \tilde{\mathfrak{A}} = \underline{\mathfrak{b}} \underline{R}_g \tilde{\mathfrak{A}} - \underline{\mathfrak{b}}^+ \underline{R}_g \tilde{\mathfrak{A}} = \underline{\mathfrak{b}}^- \underline{R}_g \tilde{\mathfrak{A}} = \underline{\mathfrak{b}}^- \overline{\underline{\mathfrak{b}} \times \tilde{\mathfrak{A}}} = \underline{\mathfrak{b}}^- \underline{R}_g \times \tilde{\mathfrak{A}}
\end{aligned}$$