

$$\begin{aligned}
v_{w\omega} &= v_{0w} - \omega \bar{\omega} v_{1w} \\
{}^{z\zeta}K_{w\omega} &= {}^zK_0w + \zeta \bar{\omega} {}^zK_1w \\
\mathbf{J} &= \underbrace{{}^0J_0 + \omega \bar{\omega} {}^1J_1}_{\text{ev}} + \underbrace{\omega {}^1J_0 + \bar{\omega} {}^0J_1}_{\text{odd}} \\
{}^{z\zeta}P_w\mathbf{J} &= \int \int_{dw \, d\omega} v_{w\omega} {}^{z\zeta}K_{w\omega} {}^{w\omega}\mathbf{J} \\
&= \int \int_{dw \, d\omega} \underbrace{v_{0w} - \omega \bar{\omega} v_{1w}} \underbrace{{}^zK_0w + \zeta \bar{\omega} {}^zK_1w} \underbrace{{}^0J_0 + \omega \bar{\omega} {}^1J_1 + \omega {}^1J_0 + \bar{\omega} {}^0J_1} \\
&= \int \int_{dw \, d\omega} v_{0w} {}^zK_0w \underbrace{{}^0J_0 + \omega \bar{\omega} {}^1J_1 + \omega {}^1J_0 + \bar{\omega} {}^0J_1} + \int \int_{dw \, d\omega} v_{0w} \zeta \bar{\omega} {}^zK_1w \underbrace{{}^0J_0 + \omega \bar{\omega} {}^1J_1 + \omega {}^1J_0 + \bar{\omega} {}^0J_1} \\
&\quad - \int \int_{dw \, d\omega} \omega \bar{\omega} v_{1w} {}^zK_0w \underbrace{{}^0J_0 + \omega \bar{\omega} {}^1J_1 + \omega {}^1J_0 + \bar{\omega} {}^0J_1} - \int \int_{dw \, d\omega} \omega \bar{\omega} v_{1w} \zeta \bar{\omega} {}^zK_1w \underbrace{{}^0J_0 + \omega \bar{\omega} {}^1J_1 + \omega {}^1J_0 + \bar{\omega} {}^0J_1} \\
&= \int \int_{dw \, d\omega} v_{0w} {}^zK_0w \underbrace{{}^0J_0 + \omega \bar{\omega} {}^1J_1 + \omega {}^1J_0 + \bar{\omega} {}^0J_1} + \int \int_{dw \, d\omega} v_{0w} \zeta \bar{\omega} {}^zK_1w \underbrace{{}^0J_0 + \omega {}^1J_0} - \int \int_{dw \, d\omega} \omega \bar{\omega} v_{1w} {}^zK_0w \underbrace{{}^0J_0} \\
&= \int \int_{dw \, d\omega} v_{0w} {}^zK_0w \underbrace{{}^0J_0} + \int \int_{dw \, d\omega} v_{0w} {}^zK_0w \omega \bar{\omega} \underbrace{{}^1J_1} + \int \int_{dw \, d\omega} v_{0w} {}^zK_0w \omega \underbrace{{}^1J_0} + \int \int_{dw \, d\omega} v_{0w} {}^zK_0w \bar{\omega} \underbrace{{}^0J_1} \\
&\quad + \int \int_{dw \, d\omega} v_{0w} \zeta \bar{\omega} {}^zK_1w \underbrace{{}^0J_0} + \int \int_{dw \, d\omega} v_{0w} \zeta \bar{\omega} {}^zK_1w \omega \underbrace{{}^1J_0} - \int \int_{dw \, d\omega} \omega \bar{\omega} v_{1w} {}^zK_0w \underbrace{{}^0J_0} \\
&= - \int_{dw} v_{0w} {}^zK_0w \underbrace{{}^1J_1} + \zeta \int_{dw} v_{0w} {}^zK_1w \underbrace{{}^1J_0} + \int_{dw} v_{1w} {}^zK_0w \underbrace{{}^0J_0} = \overset{10}{P} \underbrace{{}^0J_0} - \overset{00}{P} \underbrace{{}^1J_1} + \zeta \overset{01}{P} \underbrace{{}^1J_0}
\end{aligned}$$

$$\mathcal{T}_J = \frac{\begin{array}{c|c} \begin{array}{c} \overline{10} \\ \overline{0}J_0 \end{array} & \begin{array}{c} \overline{00} \\ \overline{1}J_1 \end{array} \\ \hline \begin{array}{c} \overline{01} \\ \overline{1}J_0 \end{array} & \begin{array}{c} \overline{00} \\ \overline{0}J_1 \end{array} \end{array}}{\begin{array}{c|c} \begin{array}{c} \overline{00} \\ \overline{0}J_1 \end{array} & \begin{array}{c} \overline{01} \\ \overline{0}J_0 \end{array} \\ \hline \begin{array}{c} \overline{01} \\ \overline{1}J_0 \end{array} & \begin{array}{c} \overline{00} \\ \overline{0}J_1 \end{array} \end{array}}$$

$$\begin{aligned} \mathcal{T}_J \mathbf{1} &= P(J\mathbf{1}) = P\left(\underbrace{{}^0J_0 + \omega\bar{\omega}^1J_1 + \omega^1J_0 + \bar{\omega}^0J_{1,0}}_{\mathbf{1}} + \omega_1\mathbf{1}\right) \\ &= P\left({}^0J_{00}\mathbf{1} + \omega\bar{\omega}^1J_{10}\mathbf{1} + \omega^1J_{00}\mathbf{1} + \bar{\omega}^0J_{10}\mathbf{1} + {}^0J_{0\omega_1}\mathbf{1} + \omega\bar{\omega}^1J_{1\omega_1}\mathbf{1} + \omega^1J_{0\omega_1}\mathbf{1} + \bar{\omega}^0J_{1\omega_1}\mathbf{1}\right) \\ &= P\left(\overbrace{{}^0J_{00}\mathbf{1} + \omega\bar{\omega}^1J_{10}\mathbf{1} - {}^0J_{11}\mathbf{1}} + \overbrace{\omega^1J_{00}\mathbf{1} + {}^0J_{01}\mathbf{1}} + \bar{\omega}^0J_{10}\mathbf{1}\right) \\ &= \overbrace{P^{\overline{10}}J_{0,0}\mathbf{1} - P^{\overline{00}}J_{10}\mathbf{1} - {}^0J_{11}\mathbf{1}} + \zeta \overbrace{P^{\overline{01}}J_{00}\mathbf{1} + {}^0J_{01}\mathbf{1}} = \underbrace{\overline{10}J_0 - \overline{1}J_1}_{\mathbf{0}}\mathbf{1} - \underbrace{\overline{00}J_1}_{\mathbf{1}}\mathbf{1} + \zeta \underbrace{\overline{01}J_0 + \overline{0}J_1}_{\mathbf{1}}\mathbf{1} \end{aligned}$$