

WORKSHOP ON "DIRAC OPERATORS AND SPECIAL GEOMETRIES"  
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Almost contact metric 3-structures  
with torsion

# Some preliminaries on almost contact manifolds.

An **almost contact manifold** is a  $(2n+1)$ -dimensional manifold  $M$  endowed with

- ▶ a field  $\varphi$  of endomorphisms of the tangent spaces
- ▶ a global 1-form  $\eta$
- ▶ a global vector field  $\xi$ , called *Reeb vector field*

such that

$$\varphi^2 = -I + \eta \otimes \xi \quad \text{and} \quad \eta(\xi) = 1.$$

Given an almost contact manifold  $(M^{2n+1}, \varphi, \xi, \eta)$ , one can define on  $M^{2n+1} \times \mathbb{R}$  an almost complex structure  $J$  by setting

$$J(X, f d/dt) = (\varphi X - f\xi, \eta(X)d/dt)$$

for all  $X \in \Gamma(TM^{2n+1})$  and  $f \in C^\infty(M^{2n+1} \times \mathbb{R})$ .

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for all  $X \in \Gamma(TM^{2n+1})$  and  $f \in C^\infty(M^{2n+1} \times \mathbb{R})$ .

Then  $(\varphi, \xi, \eta)$  is said to be **normal** if the almost complex structure  $J$  is integrable, that is  $[J, J] \equiv 0$ . This happens if and only if

$$N := [\varphi, \varphi] + 2\eta \otimes \xi \equiv 0.$$

Given an almost contact structure  $(\varphi, \xi, \eta)$  on  $M$ , there exists a Riemannian metric  $g$  such that

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If we fix such a metric,  $(M, \varphi, \xi, \eta, g)$  is called an **almost contact metric manifold** and we can define the *fundamental 2-form*  $\Phi$  by

$$\Phi(X, Y) = g(X, \varphi Y).$$

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- An almost contact metric manifold such that  $N \equiv 0$  and  $d\Phi = 0$ ,  $d\eta = 0$  is said to be a **cosymplectic manifold**.

**Definition** (Blair, *J. Differential Geom.* 1967).

If  $d\Phi = 0$  and  $N \equiv 0$  then  $(M^{2n+1}, \varphi, \xi, \eta, g)$  is said to be a **quasi-Sasakian manifold**.

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An almost contact manifold  $(M^{2n+1}, \varphi, \xi, \eta)$  is said to be of

- ▶ rank  $2p$  if  $(d\eta)^p \neq 0$  and  $\eta \wedge (d\eta)^p = 0$  on  $M^{2n+1}$ , for some  $p \leq n$
- ▶ rank  $2p+1$  if  $\eta \wedge (d\eta)^p \neq 0$  and  $(d\eta)^{p+1} = 0$  on  $M^{2n+1}$ , for some  $p \leq n$ .

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**Theorem** (Blair, Tanno)

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No quasi-Sasakian manifold has even rank.

Remarkable subclasses of quasi-Sasakian manifolds are given by

- ▶ **Sasakian manifolds** ( $d\eta = \Phi$ , maximal rank  $2n+1$ )
- ▶ **cosymplectic manifolds** ( $d\eta = 0$ ,  $d\Phi = 0$ , minimal rank 1).

# 3-structures

An **almost contact 3-structure** on a manifold  $M$  is given by three distinct almost contact structures  $(\varphi_1, \bar{\xi}_1, \eta_1)$ ,  $(\varphi_2, \bar{\xi}_2, \eta_2)$ ,  $(\varphi_3, \bar{\xi}_3, \eta_3)$  on  $M$  satisfying the following relations, for an even permutation  $(i, j, k)$  of  $\{1, 2, 3\}$ ,

$$\begin{aligned}\varphi_k &= \varphi_i \varphi_j - \eta_j \otimes \bar{\xi}_i = -\varphi_j \varphi_i + \eta_i \otimes \bar{\xi}_j, \\ \bar{\xi}_k &= \varphi_i \bar{\xi}_j = -\varphi_j \bar{\xi}_i, \quad \eta_k = \eta_i \circ \varphi_j = -\eta_j \circ \varphi_i.\end{aligned}$$

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One can prove that (Kuo, Udriste)

- $\dim(M) = 4n+3$  for some  $n \geq 1$ ,
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- $\dim(M) = 4n+3$  for some  $n \geq 1$ ,
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If each almost contact structure is *normal*, then the 3-structure is said to be **hyper-normal**.

Moreover, there exists a Riemannian metric  $g$  compatible with each almost contact structure  $(\varphi_i, \xi_i, \eta_i)$ , i.e. satisfying

$$g(\varphi_i X, \varphi_i Y) = g(X, Y) - \eta_i(X)\eta_i(Y)$$

for each  $i \in \{1, 2, 3\}$ .

Then we say that  $(M^{4n+3}, \varphi_i, \xi_i, \eta_i, g)$  is an **almost 3-contact metric manifold**.

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Remarkable examples of (hyper-normal) almost 3-contact metric manifolds are given by

- **3-Sasakian manifolds** (each structure  $(\varphi_i, \xi_i, \eta_i)$  is Sasakian)
- **3-cosymplectic manifolds** (each structure  $(\varphi_i, \xi_i, \eta_i)$  is cosymplectic)
- **3-quasi-Sasakian manifolds** (each structure  $(\varphi_i, \xi_i, \eta_i)$  is quasi-Sasakian).

# “Foliated” 3-structures

Let  $(M^{4n+3}, \varphi_i, \xi_i, \eta_i, g)$  be an almost 3-contact (metric) manifold.  
Putting

$$\mathcal{V} := \text{span}\{\xi_1, \xi_2, \xi_3\} \quad \text{and} \quad \mathcal{H} := \ker(\eta_1) \cap \ker(\eta_2) \cap \ker(\eta_3),$$

we have the (orthogonal) decomposition

$$T_p M = \mathcal{V}_p \oplus \mathcal{H}_p.$$

$\mathcal{V}$  is called *Reeb distribution* (or *vertical distribution*), whereas  $\mathcal{H}$  *horizontal distribution*.

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Is the distribution  $\mathcal{V}$  integrable?

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**Question** (Kuo-Tachibana, 1970)

Is the distribution  $\mathcal{V}$  integrable?

The answer is negative, in general.

**Example** (C. M. - De Nicola - Dileo, *Ann. Glob. Anal. Geom.* 2008)

Let  $\mathfrak{g}$  be the 7-dimensional Lie algebra with basis  $\{X_1, X_2, X_3, X_4, \xi_1, \xi_2, \xi_3\}$  and Lie brackets given by

$$[X_h, X_k] = [X_h, \xi_j] = 0, \quad [\xi_1, \xi_2] = [\xi_2, \xi_3] = [\xi_3, \xi_1] = X_1.$$

Let  $G$  be a Lie group whose Lie algebra is  $\mathfrak{g}$  and let us define three tensor fields  $\varphi_1, \varphi_2, \varphi_3$  on  $G$ , and three 1-forms  $\eta_1, \eta_2, \eta_3$ , by putting, for all  $i, j, k \in \{1, 2, 3\}$ ,  $\varphi_i \xi_j = \varepsilon_{ijk} \xi_k$  and

$$\begin{aligned} \varphi_1 X_1 &= X_2, & \varphi_1 X_2 &= -X_1, & \varphi_1 X_3 &= X_4, & \varphi_1 X_4 &= -X_3, \\ \varphi_2 X_1 &= X_3, & \varphi_2 X_2 &= -X_4, & \varphi_2 X_3 &= -X_1, & \varphi_2 X_4 &= X_2, \\ \varphi_3 X_1 &= X_4, & \varphi_3 X_2 &= X_3, & \varphi_3 X_3 &= -X_2, & \varphi_3 X_4 &= -X_1, \end{aligned}$$

and setting  $\eta_i(X_h) = 0$  and  $\eta_i(\xi_j) = \delta_{ij}$ .

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- ▶  $(\varphi_i, \xi_i, \eta_i)$  is an almost contact 3-structure on  $G$
- ▶ by construction the Reeb distribution is not integrable.

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- ▶  $(\varphi_i, \xi_i, \eta_i)$  is an almost contact 3-structure on  $G$
- ▶ by construction the Reeb distribution is not integrable.

### Remark

$(G, \varphi_i, \xi_i, \eta_i)$  is not hyper-normal since  $N_1(\xi_1, \xi_2) = -X_1 + X_2 \neq 0$ .

It is known that the Reeb distribution  $\mathcal{V} := \text{span}\{\xi_1, \xi_2, \xi_3\}$  is integrable in 3-Sasakian manifolds and in 3-cosymplectic manifolds.

<i>manifold</i>	<i>space of leaves</i>	
3-Sasakian	Quaternionic-Kähler	Ishihara ( <i>Kodai Math. Sem. Rep. 1973</i> ) Boyer-Galicki-Mann ( <i>J. Reine Angew. Math. 1994</i> )
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### **Question**

Does the hyper-normality of the almost contact 3-structure imply the integrability of  $\mathcal{V}$ ?

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### **Question**

Does the hyper-normality of the almost contact 3-structure imply the integrability of  $\mathcal{V}$ ?

Rather surprisingly, the answer is NO.

**Example** (C. M., *Differential Geom. Appl.* 2009)

Let  $\mathfrak{g}$  be the  $(4n+3)$ -dimensional Lie algebra with basis  $\{E_1, \dots, E_{4n}, \xi_1, \xi_2, \xi_3\}$  and Lie brackets defined by

$$[\xi_1, \xi_2] = E_1, \quad [\xi_2, \xi_3] = E_{n+1}, \quad [\xi_2, \xi_3] = E_{2n+1}, \quad [E_h, E_k] = [\xi_i, X_k] = 0.$$

Let  $G$  be a Lie group whose Lie algebra is  $\mathfrak{g}$ . We define on  $G$  a left-invariant almost contact 3-structure  $(\varphi_i, \xi_i, \eta_i)$  by putting  $\varphi_i \xi_j = \varepsilon_{ijk} \xi_k$  and

$$\begin{aligned} \varphi_1 E_h &= E_{n+h}, & \varphi_1 E_{n+h} &= -E_h, & \varphi_1 E_{2n+h} &= E_{3n+h}, & \varphi_1 E_{3n+h} &= -E_{2n+h}, \\ \varphi_2 E_h &= E_{2n+h}, & \varphi_2 E_{n+h} &= -E_{3n+h}, & \varphi_2 E_{2n+h} &= -E_h, & \varphi_2 E_{3n+h} &= E_{n+h}, \\ \varphi_3 E_h &= E_{3n+h}, & \varphi_3 E_{n+h} &= E_{2n+h}, & \varphi_3 E_{2n+h} &= -E_{n+h}, & \varphi_3 E_{3n+h} &= -E_h, \end{aligned}$$

and setting  $\eta_i(E_k) = 0$  and  $\eta_i(\xi_j) = \delta_{ij}$ . Then  $(\varphi_i, \xi_i, \eta_i)$  is a **hyper-normal** almost contact 3-structure on  $G$  though **the Reeb distribution is not integrable**.

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Therefore

hyper-normality of the 3-structure  $\not\Rightarrow$  integrability of  $\mathcal{V}$ .

Conversely,

hyper-normality of the 3-structure  $\not\Leftarrow$  integrability of  $\mathcal{V}$ .

### Example

Let  $\mathfrak{g}$  be the 7-dimensional Lie algebra with basis  $\{X_1, X_2, X_3, X_4, \xi_1, \xi_2, \xi_3\}$  and Lie brackets defined by

$$[X_h, X_k] = 0, \quad [\xi_i, \xi_j] = 0, \quad [\xi_i, X_k] = \xi_i.$$

Let  $G$  be a Lie group whose Lie algebra is  $\mathfrak{g}$ . We define on  $G$  a left-invariant almost contact 3-structure  $(\varphi_i, \xi_i, \eta_i)$  by putting  $\varphi_i \xi_j = \varepsilon_{ijk} \xi_k$  and

$$\begin{aligned} \varphi_1 X_1 &= X_2, & \varphi_1 X_2 &= -X_1, & \varphi_1 X_3 &= X_4, & \varphi_1 X_4 &= -X_3, \\ \varphi_2 X_1 &= X_3, & \varphi_2 X_2 &= -X_4, & \varphi_2 X_3 &= -X_1, & \varphi_2 X_4 &= X_2, \\ \varphi_3 X_1 &= X_4, & \varphi_3 X_2 &= X_3, & \varphi_3 X_3 &= -X_2, & \varphi_3 X_4 &= -X_1, \end{aligned}$$

and setting  $\eta_i(X_h) = 0$  and  $\eta_i(\xi_j) = \delta_{ij}$ . Then  $(G, \varphi_i, \xi_i, \eta_i)$  is an almost 3-contact manifold which is **not hyper-normal**. Nevertheless,  $\mathcal{V}$  is **integrable**.

## Definition

An almost 3-contact manifold such that the Reeb distribution is involutive is said to be a **foliated almost 3-contact manifold**.

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**Theorem** (C. M., *Different. Geom. Appl.* 2009)

Let  $(M^{4n+3}, \varphi_i, \xi_i, \eta_i, g)$  be an almost 3-contact metric manifold. Then any two of the following conditions imply the other one:

- (i)  $\mathcal{V} := \text{span}\{\xi_1, \xi_2, \xi_3\}$  is integrable;
- (ii) each Reeb vector field is an infinitesimal automorphism with respect to the horizontal distribution  $\mathcal{H}$ ;
- (iii)  $(\mathcal{L}_{\xi_i} g)|_{\mathcal{H} \times \mathcal{V}} = 0$  for all  $i \in \{1, 2, 3\}$ .

Moreover, if any two, and hence all, of the above conditions hold, then  $\mathcal{V}$  defines a totally geodesic foliation of  $M^{4n+3}$ .

- The most famous example of foliated almost 3-contact manifolds is given by *3-Sasakian manifolds*. Indeed, in any 3-Sasakian manifold

$$[\xi_i, \xi_j] = 2\xi_k.$$

- Another important class is given by *3-cosymplectic manifolds*, where

$$[\xi_i, \xi_j] = 0.$$

- A more general class is given by *3-quasi-Sasakian manifolds*.

# 3-quasi-Sasakian manifolds

A **3-quasi-Sasakian manifold** is an almost 3-contact metric manifold  $(M^{4n+3}, \varphi_i, \xi_i, \eta_i, g)$  such that each structure is quasi-Sasakian, that is for each  $i \in \{1, 2, 3\}$   $N_i \equiv 0$  and  $d\Phi_i = 0$ , where

$$N_i := [\varphi_i, \varphi_i] + 2\eta_i \otimes \xi_i$$

and

$$\Phi_i(X, Y) := g(X, \varphi_i Y).$$

Some recent results on 3-quasi-Sasaki manifolds are obtained in

- C. M., De Nicola, Dileo, *3-quasi-Sasakian manifolds*, Ann. Glob. Anal. Geom. (2008)
- C. M., De Nicola, Dileo, *The geometry of 3-quasi-Sasakian manifolds*, Internat. J. Math. (2009)

## Theorem 1

Let  $(M^{4n+3}, \varphi_i, \xi_i, \eta_i, g)$  be a 3-quasi-Sasakian manifold. Then the Reeb distribution  $\mathcal{V} := \text{span}\{\xi_1, \xi_2, \xi_3\}$  defines a Riemannian foliation with totally geodesic leaves, and the Reeb vector fields obey to the rule

$$[\xi_i, \xi_j] = c\xi_k,$$

for some  $c \in \mathbb{R}$ . Moreover,  $M^{4n+3}$  is 3-cosymplectic if and only if  $c=0$ .

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Sub-classes of the 3-quasi-Sasakian manifolds are given by the 3-Sasakian manifolds ( $c=2$ ) e by the 3-cosymplectic manifolds ( $c=0$ ).

Nevertheless there are also examples of 3-quasi-Sasakian manifolds which are neither 3-Sasakian nor 3-cosymplectic.

# The rank of a 3-quasi-Sasakian manifold

In a 3-quasi-Sasakian manifold one has, in principle, the three odd ranks  $r_1, r_2, r_3$  associated to the 1-forms  $\eta_1, \eta_2, \eta_3$ , since we have three distinct, although related, quasi-Sasakian structures.

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We have proved that  $r_1 = r_2 = r_3$ .

## Theorem 2

Let  $(M^{4n+3}, \varphi_i, \xi_i, \eta_i, g)$  be 3-quasi-Sasakian manifold. Then the almost contact structures  $(\varphi_1, \xi_1, \eta_1), (\varphi_2, \xi_2, \eta_2), (\varphi_3, \xi_3, \eta_3)$  have the same rank, which we call *the rank* of the 3-quasi-Sasakian manifold  $M^{4n+3}$ , and

$$\begin{aligned} \text{rank}(M) &= 1 && \text{if } M \text{ is 3-cosymplectic } (c=0) \\ \text{rank}(M) &= 4l+3, \quad l \leq n, && \text{in the other cases } (c \neq 0) \end{aligned}$$

Furthermore,  $M$  is of maximal rank if and only if it is 3- $\alpha$ -Sasakian (i.e.  $d\eta_i = \alpha\Phi_i$  for each  $i = 1, 2, 3$ ).

### **Theorem 3**

Let  $(M^{4n+3}, \varphi_i, \xi_i, \eta_i, g)$  be a 3-quasi-Sasakian manifold of rank  $4l+3$  with  $[\xi_i, \xi_j] = 2\xi_k$ . Then  $M^{4n+3}$  is locally a Riemannian product of a 3-Sasakian manifold  $S^{4l+3}$  and a hyper-Kähler manifold  $\mathcal{K}^{4m}$ , where  $m = n-l$ .

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### **Theorem 4**

Every 3-quasi-Sasakian manifold has non-negative scalar curvature

$$\frac{1}{2}c^2(2n+1)(4l+3),$$

where  $\dim(M) = 4n+3$ ,  $\text{rank}(M) = 4l+3$  and  $[\xi_i, \xi_j] = c\xi_k$ .

Furthermore, any 3-quasi-Sasakian manifold is Einstein if and only if it is 3- $\alpha$ -Sasakian (strictly positive scalar curvature) or 3-cosymplectic (Ricci-flat).

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- Such results are peculiar to the 3-quasi-Sasakian setting, since they do not hold in general for a single quasi-Sasakian structure on a manifold  $M^{2n+1}$ .

# 3-structures with torsion

Another class of foliated almost 3-contact manifolds is given by the “almost 3-contact metric manifolds with torsion”.

## Definition

A linear connection  $\nabla$  on a Riemannian manifold  $(M, g)$  is said to be a **metric connection with torsion** if  $\nabla g = 0$  and the torsion tensor  $T$ , defined as

$$T(X, Y, Z) = g(T^\nabla(X, Y), Z),$$

is a 3-form.

Riemannian manifolds admitting a metric connection with totally skew-symmetric torsion recently become of interest in Theoretical and Mathematical Physics, especially in

- ▶ supersymmetry theories
- ▶ supergravity
- ▶ string theory

Of particular interest are **hyper-Kähler manifolds with torsion** (HKT) and **quaternionic-Kähler manifolds with torsion** (QKT)

► A **HKT** manifold is a hyper-Hermitian manifold  $(M^{4n}, J_1, J_2, J_3, g)$  which admits a metric connection with torsion  $\nabla$  such that  $\nabla J_1 = \nabla J_2 = \nabla J_3 = 0$ .

► Likewise, a **QKT** manifold is an almost quaternionic-Hermitian manifold  $(M^{4n}, Q, g)$  admitting a metric connection with torsion  $\nabla$  such that  $\nabla Q \subset Q$  and

$$T(X, Y, Z) = T(J_i X, J_i Y, Z) + T(J_i X, Y, J_i Z) + T(X, J_i Y, J_i Z),$$

for all  $X, Y, Z \in \Gamma(TM^{4n})$  and  $i \in \{1, 2, 3\}$ , where  $\{J_1, J_2, J_3\}$  is an admissible basis which locally spans the almost quaternionic structure  $Q$ .

- I. Agricola, *The Srní lectures on non-integrable geometries with torsion*, Arch. Math. (Brno) **42** (2006), 5-84.

## Question

What is a possible generalization in odd dimension of the notion of hyper-Kähler structure with torsion?

**Theorem** (Friedrich - Ivanov, *Asian J. Math.* 2002)

An almost contact metric manifold  $(M^{2n+1}, \varphi, \xi, \eta, g)$  admits a metric connection  $\nabla$  with totally skew-symmetric torsion  $T$  such that  $\nabla\xi = \nabla\eta = \nabla\varphi = 0$  if and only if  $\xi$  is a Killing vector field and the tensor  $N'$  given by

$$N'(X, Y, Z) := g(N(X, Y), Z) = g([\varphi, \varphi](X, Y) + d\eta(X, Y)\xi, Z)$$

is skew-symmetric. The connection  $\nabla$  is explicitly given by

$$g(\nabla_x Y, Z) = g(\nabla^g_x Y, Z) + \frac{1}{2}T(X, Y, Z)$$

with

$$T = \eta \wedge d\eta + d^\varphi\Phi + N' - \eta \wedge (i_\xi N'),$$

where  $d^\varphi\Phi$  denotes the “ $\varphi$ -twisted” derivative defined by  $d^\varphi\Phi(X, Y, Z) := -d\Phi(\varphi X, \varphi Y, \varphi Z)$ .

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where  $d^\varphi\Phi$  denotes the “ $\varphi$ -twisted” derivative defined by  $d^\varphi\Phi(X, Y, Z) := -d\Phi(\varphi X, \varphi Y, \varphi Z)$ .

- In particular, if  $(M^{2n+1}, \varphi, \xi, \eta, g)$  is Sasakian then  $N \equiv 0$  and  $d\eta = \Phi$  (hence  $d^\varphi\Phi = 0$ ), and so

$$T = \eta \wedge d\eta.$$

Using that result, Agricola pointed out that a 3-Sasakian manifold  $(M^{4n+3}, \varphi_i, \xi_i, \eta_i, g)$  can not admit any metric connection  $\nabla$  with totally skew-symmetric torsion such that  $\nabla \xi_i = \nabla \eta_i = \nabla \varphi_i = 0$ , for each  $i \in \{1, 2, 3\}$ .

Indeed by the previous theorem we have that  $M^{4n+3}$  admits three connections  $\nabla^1, \nabla^2, \nabla^3$ , one for each Sasakian structure  $(\varphi_i, \xi_i, \eta_i, g)$ , such that

$$\nabla^i \xi_i = \nabla^i \eta_i = \nabla^i \varphi_i = 0 \quad \text{and} \quad T^i = \eta_i \wedge d\eta_i$$

for each  $i \in \{1, 2, 3\}$ .

But the problem is that these three connections do not coincide and so the 3-Sasakian structure in question is not preserved by any metric connection with skew-symmetric torsion.

## Definition

An **almost 3-contact metric manifold with torsion** is a hyper-normal almost 3-contact metric manifold  $(M, \varphi_i, \xi_i, \eta_i, g)$  admitting a linear connection  $\nabla$  such that

$$\nabla g = 0, \quad \nabla \eta_1 = \nabla \eta_2 = \nabla \eta_3 = 0, \quad \nabla \xi_1 = \nabla \xi_2 = \nabla \xi_3 = 0,$$

$$(\nabla_X \varphi_1)Y = -c\eta_2(X)\varphi_3 Y^h + c\eta_3(X)\varphi_2 Y^h,$$

$$(\nabla_X \varphi_2)Y = -c\eta_3(X)\varphi_1 Y^h + c\eta_1(X)\varphi_3 Y^h,$$

$$(\nabla_X \varphi_3)Y = -c\eta_1(X)\varphi_2 Y^h + c\eta_2(X)\varphi_1 Y^h,$$

for some  $c \in \mathbb{R}$ , and whose torsion tensor  $T$  satisfies the following conditions:

(i)  $T$  is horizontally skew-symmetric,

(ii)  $T(X, Y, \xi_i) = T(X, \xi_i, Y) = T(X, \xi_j, \xi_i) = T(\xi_i, \xi_j, X) = 0$  for all  $X, Y \in \Gamma(\mathcal{H})$ ,

(iii)  $T(\xi_i, \xi_j, \xi_k) = -c\varepsilon_{ijk}$  for all  $i, j, k \in \{1, 2, 3\}$ .

## Remark

The conditions

$$(\nabla_X \varphi_1)Y = -c\eta_2(X)\varphi_3Y^h + c\eta_3(X)\varphi_2Y^h$$

$$(\nabla_X \varphi_2)Y = -c\eta_3(X)\varphi_1Y^h + c\eta_1(X)\varphi_3Y^h$$

$$(\nabla_X \varphi_3)Y = -c\eta_1(X)\varphi_2Y^h + c\eta_2(X)\varphi_1Y^h$$

are equivalent to

$$\nabla \varphi_1 = -c(\eta_2 \otimes \varphi_3 - \eta_3 \otimes \varphi_2 + (\eta_2 \otimes \eta_2 + \eta_3 \otimes \eta_3) \otimes \xi_1 - \eta_1 \otimes \eta_2 \otimes \xi_2 - \eta_1 \otimes \eta_3 \otimes \xi_3)$$

$$\nabla \varphi_2 = -c(\eta_3 \otimes \varphi_1 - \eta_1 \otimes \varphi_3 - \eta_1 \otimes \eta_2 \otimes \xi_1 + (\eta_1 \otimes \eta_1 + \eta_3 \otimes \eta_3) \otimes \xi_2 - \eta_3 \otimes \eta_2 \otimes \xi_3)$$

$$\nabla \varphi_3 = -c(\eta_2 \otimes \varphi_3 - \eta_3 \otimes \varphi_2 + (\eta_2 \otimes \eta_2 + \eta_3 \otimes \eta_3) \otimes \xi_1 - \eta_1 \otimes \eta_2 \otimes \xi_2 - \eta_1 \otimes \eta_3 \otimes \xi_3)$$

- C. M., *3-structures with torsion*, Different. Geom. Appl. **27** (2009), 496–506

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### **Theorem 1**

Let  $(M^{4n+3}, \varphi_i, \xi_i, \eta_i, g)$  be a hyper-normal almost 3-contact metric manifold. Then  $M^{4n+3}$  is an “almost 3-contact metric manifold with torsion” if and only if

1.  $d^{\varphi_1} \Phi_1 = d^{\varphi_2} \Phi_2 = d^{\varphi_3} \Phi_3$  on  $\mathcal{H}$ ,
2.  $\xi_1, \xi_2, \xi_3$  are Killing,
3. the Reeb distribution  $\mathcal{V} = \text{span}\{\xi_1, \xi_2, \xi_3\}$  is integrable,
4. the tensor fields  $\varphi_1, \varphi_2, \varphi_3$  satisfy the relations

$$\mathcal{L}_{\xi_i} \varphi_j = c \varphi_k.$$

If an “almost 3-contact metric connection with torsion” exists, then it is unique.

## Theorem 2

Any almost 3-contact metric manifold with torsion is a *foliated* almost 3-contact manifold. Moreover, the Reeb vector fields obey to the rule

$$[\xi_i, \xi_j] = c\xi_k.$$

The space of leaves (with respect to  $\mathcal{V}$ ) is HKT or QKT according to  $c = 0$  or  $c \neq 0$ , respectively.

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Thus we may divide almost 3-contact metric manifolds with torsion in two classes according to the behavior of the leaves of  $\mathcal{V}$ : those for which each leaf of  $\mathcal{V}$  is locally  $SO(3)$  (which corresponds to the case  $c \neq 0$ ) and those for which each leaf of  $\mathcal{V}$  is locally an abelian group ( $c = 0$ ).

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- ▶ Almost 3-contact metric manifolds with torsion such that  $c=2$  are called **3-Sasakian manifolds with torsion**.
- ▶ Almost 3-contact metric manifolds with torsion such that  $c=0$  are called **3-cosymplectic manifolds with torsion**.

## **Corollary 1**

The torsion  $T$  is totally skew-symmetric if and only if the horizontal distribution  $\mathcal{H}$  is integrable.

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### **Corollary 2**

An almost contact metric 3-structure with torsion  $(\varphi_i, \xi_i, \eta_i, g, \nabla)$  on  $M$  is 3-quasi-Sasakian if and only if the torsion is given by

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- if  $c=2$  then  $M^{4n+3}$  is 3-Sasakian and  $\nabla$  coincides with the Biquard connection.

# Some open problems

- ▶ Classification of foliated almost contact 3-structures
- ▶ The class of (foliated) almost 3-contact metric manifolds which are Einstein.
  - Conjecture: the only foliated almost 3-contact metric manifolds which are Einstein are the 3-Sasakian and the 3-cosymplectic manifolds.
  - Example with negative curvature?
- ▶ Curvature properties of 3-Sasakian and 3-cosymplectic manifolds with torsion (ongoing paper)

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**THANK YOU!**

## Example

Consider  $\mathbb{R}^{4n+3}$  with its global coordinates  $x_1, \dots, x_n, y_1, \dots, y_n, u_1, \dots, u_n, v_1, \dots, v_n, z_1, z_2, z_3$ . Let  $M$  be the open submanifold of  $\mathbb{R}^{4n+3}$  obtained by removing the points where  $\sin(z_2) = 0$  and define three vector fields on  $M$

$$\bar{\xi}_1 := c\partial_1$$

$$\bar{\xi}_2 := c(\cos(z_1)\cot(z_2)\partial_1 + \sin(z_1)\partial_2 - \cos(z_1)/\sin(z_2)\partial_3)$$

$$\bar{\xi}_3 := c(-\sin(z_1)\cot(z_2)\partial_1 + \cos(z_1)\partial_2 + \sin(z_1)/\sin(z_2)\partial_3)$$

(where  $\partial_i = \partial/\partial z_i$ ) for some  $c \neq 0$ , and three 1-forms

$$\eta_1 := c^{-1}(dz_1 + \cos(z_2)dz_3)$$

$$\eta_2 := c^{-1}(\sin(z_1)dz_2 - \cos(z_1)\sin(z_2)dz_3)$$

$$\eta_3 := c^{-1}(\cos(z_1)dz_2 + \sin(z_1)\sin(z_2)dz_3).$$

One has  $[\bar{\xi}_i, \bar{\xi}_j] = c\bar{\xi}_k$  and  $\eta_i(\bar{\xi}_j) = \delta_{ij}$ .

Define a Riemannian metric  $g$  by declaring that the set  $\{X_i = \partial/\partial x_i, Y_i = \partial/\partial y_i, U_i = \partial/\partial u_i, V_i = \partial/\partial v_i, \bar{\xi}_1, \bar{\xi}_2, \bar{\xi}_3\}$  ( $i = 1, \dots, n$ ) is a global orthonormal frame.

Moreover, define three tensor fields  $\varphi_1, \varphi_2, \varphi_3$  on  $M$  by setting

$$\varphi_i \bar{\xi}_j = \varepsilon_{ijk} \bar{\xi}_k$$

$$\begin{aligned} \varphi_1 X_i &= Y_i, & \varphi_1 Y_i &= -X_i, & \varphi_1 U_i &= V_i, & \varphi_1 V_i &= -U_i, \\ \varphi_2 X_i &= U_i, & \varphi_2 Y_i &= -V_i, & \varphi_2 X_3 &= -X_1, & \varphi_2 V_i &= Y_i, \\ \varphi_3 X_i &= V_i, & \varphi_3 Y_i &= U_i, & \varphi_3 U_i &= -Y_i, & \varphi_3 V_i &= -X_i. \end{aligned}$$

One can prove that  $(M, \varphi_i, \bar{\xi}_i, \eta_i, g)$  is a 3-quasi-Sasakian manifold, which is

- neither 3-cosymplectic, since the Reeb vector fields do not commute,
- nor 3-Sasakian, since it admits Darboux-like coordinates

**Theorem** (C. M. - De Nicola, *J. Geom. Phys.* 2007)

A 3-Sasakian manifold can not admit a Darboux-like coordinate system.

For “Darboux-like coordinate system” we mean local coordinates  $x_1, \dots, x_{4n}, z_1, z_2, z_3$  with respect to which, for each  $i \in \{1, 2, 3\}$ ,  $\Phi_i = d\eta_i$  has constant components and  $\bar{\xi}_i = a^1_i \partial/\partial z_1 + a^2_i \partial/\partial z_2 + a^3_i \partial/\partial z_3$ , where  $a^j_i$  are functions depending only on the coordinates  $z_1, z_2, z_3$ .

Furthermore,  $(M, \varphi_i, \xi_i, \eta_i, g)$  is  $\eta$ -Einstein, i.e. the Ricci tensor is of the form

$$\text{Ric} = ag + b_1\eta_1 \otimes \eta_1 + b_2\eta_2 \otimes \eta_2 + b_3\eta_3 \otimes \eta_3.$$

Indeed one has

$$\text{Ric} = c^2/4 (\eta_1 \otimes \eta_1 + \eta_2 \otimes \eta_2 + \eta_3 \otimes \eta_3).$$

Thus, differently from 3-Sasakian and 3-cosymplectic geometry, there are 3-quasi-Sasakian manifolds which are not Einstein.

Let us write the explicit expression of the “connection with torsion” stated in the previous theorem.

Since  $\mathcal{V}$  is involutive, we can consider the corresponding Bott connection  $\nabla^B$ . Then we put

$$\nabla_X Y := \begin{cases} (\nabla^1_X Y)^h = (\nabla^2_X Y)^h = (\nabla^3_X Y)^h & \text{if } X, Y \in \Gamma(\mathcal{H}) \\ \nabla^B_V Y & \text{if } V \in \Gamma(\mathcal{V}), Y \in \Gamma(\mathcal{H}) \\ X(\eta_1(Y))\xi_1 + X(\eta_2(Y))\xi_2 + X(\eta_3(Y))\xi_3 & \text{if } Y \in \Gamma(\mathcal{V}). \end{cases}$$

The complete expression of the torsion is the following:

$$T(X, Y, Z) = d\Phi_i(\varphi_i X, \varphi_i Y, \varphi_i Z), \quad T(\xi_i, X, Y) = d\eta_i(X, Y),$$

$$T(\xi_i, \xi_j, \xi_k) = -c\varepsilon_{ijk}$$

for all  $X, Y, Z \in \Gamma(\mathcal{H})$ , the remaining terms being zero.

## Example of 3-structure with torsion

Let  $g$  be the 11-dimensional Lie algebra with basis  $\{E_1, \dots, E_8, \xi_1, \xi_2, \xi_3\}$  and Lie brackets defined by

$$[E_1, E_2] = -[E_3, E_4] = E_5, \quad [E_1, E_3] = [E_2, E_4] = E_6, \quad [E_1, E_4] = -[E_2, E_3] = E_7,$$

with the remaining brackets zero. Let  $G$  be a Lie group whose Lie algebra is  $g$ . Define on  $G$  an almost contact metric 3-structure  $(\varphi_i, \xi_i, \eta_i, g)$

by putting  $\eta_i(E_h) = 0$ ,  $\eta_i(\xi_j) = \delta_{ij}$  for all  $i, j \in \{1, 2, 3\}$ ,  $h \in \{1, \dots, 8\}$ , and

$$\begin{array}{llllll} \varphi_1 E_1 = E_2 & \varphi_1 E_2 = -E_1 & \varphi_1 E_3 = E_4 & \varphi_1 E_4 = -E_3 & \varphi_1 E_5 = E_6 & \varphi_1 E_6 = -E_5 \\ \varphi_1 E_7 = E_8 & \varphi_1 E_8 = -E_7 & \varphi_1 \xi_1 = 0 & \varphi_1 \xi_2 = \xi_3 & \varphi_1 \xi_3 = -\xi_2 & \\ \varphi_2 E_1 = E_3 & \varphi_2 E_2 = -E_4 & \varphi_2 E_3 = -E_1 & \varphi_2 E_4 = E_2 & \varphi_2 E_5 = E_7 & \varphi_2 E_6 = -E_8 \\ \varphi_2 E_7 = -E_5 & \varphi_2 E_8 = E_6 & \varphi_2 \xi_1 = -\xi_3 & \varphi_2 \xi_2 = 0 & \varphi_2 \xi_3 = \xi_1 & \\ \varphi_3 E_1 = E_4 & \varphi_3 E_2 = E_3 & \varphi_3 E_3 = -E_2 & \varphi_3 E_4 = -E_1 & \varphi_3 E_5 = E_8 & \varphi_3 E_6 = E_7 \\ \varphi_3 E_7 = -E_6 & \varphi_3 E_8 = -E_5 & \varphi_3 \xi_1 = \xi_2 & \varphi_3 \xi_2 = -\xi_1 & \varphi_3 \xi_3 = 0. & \end{array}$$

The Riemannian metric  $g$  is defined by requiring that  $\{E_1, \dots, E_8, \xi_1, \xi_2, \xi_3\}$  is  $g$ -orthonormal.

## Definition

Let  $M^{4n+3}$  be a smooth manifold of dimension  $4n+3$ . A **quaternionic-contact structure** (QC-structure) is given by:

- a distribution  $H$  of codimension 3 on  $M^{4n+3}$ , locally defined by the kernel of a  $\mathbb{R}^3$ -valued 1-form  $\eta = (\eta_1, \eta_2, \eta_3)$ ,  $H = \ker(\eta)$ ,
- a metric tensor  $g$  on  $H$  and a local hyper-complex structure  $Q = (I_1, I_2, I_3)$  on  $H$  ( $I_s: H \rightarrow H$ ,  $s=1,2,3$ ), compatible with  $g$ , i.e. such that  $g(X, I_s Y) = d\eta_s(X, Y)$ ,  $s = 1, 2, 3$ ,  $X, Y \in \Gamma(H)$ .

O. Biquard, *Métriques d'Einstein asymptotiquement symétriques*, Astérisque **265** (2000).

## Theorem (Biquard)

Let  $H$  be a quaternionic-contact structure on  $M^{4n+3}$  and let us assume  $n > 1$ . Then there exists a unique distribution  $V$  supplementary to  $H$  and a unique linear connection  $\nabla$  on  $M^{4n+3}$  such that

1.  $V$  and  $H$  are  $\nabla$ -parallel,
2.  $\nabla g = 0$ ,
3.  $\nabla Q \subset Q$ ,
4. the torsion tensor field  $T$  of  $\nabla$  satisfies the conditions
  - a. for any  $X, Y \in \Gamma(H)$ ,  $T(X, Y) = -[X, Y]|_V$
  - b. for any  $\xi \in \Gamma(V)$ , the endomorphism  $T_\xi := (X \mapsto (T(X, \xi))|_H) \in (sp(n) \oplus sp(1))^\perp \subset so(4n)$ .

The unique connection stated in the theorem is called **Biquard connection**. In dimension 7 its existence was proved, under a further assumption, by Duchemin.

## Corollary

Let  $(\varphi_i, \xi_i, \eta_i, g)$ ,  $i \in \{1, 2, 3\}$ , be an almost contact metric 3-structure of  $M^{4n+3}$  such that each Reeb vector field  $\xi_i$  is Killing and is an infinitesimal automorphism with respect to  $\mathcal{H}$ . Then  $(M^{4n+3}, \varphi_i, \xi_i, \eta_i, g)$  is a foliated almost 3-contact manifold. More precisely,  $\mathcal{V}$  defines a Riemannian foliation of  $M^{4n+3}$  with totally geodesic leaves and the Reeb vector fields satisfy

$$[\xi_i, \xi_j] = c\xi_k$$

for any even permutation  $(i, j, k)$  of  $\{1, 2, 3\}$  and for some  $c \in \mathbb{R}$ .

The peculiarity of 3-quasi-Sasakian manifolds is that they are foliated by four canonical Riemannian foliations, namely

- |   |                       |
|---|-----------------------|
| ▶ $\mathcal{V} := \text{span}\{\xi_1, \xi_2, \xi_3\}$   | <i>dimension</i><br>3 |
| ▶ $\mathcal{H}_1 := \{X \in \mathcal{H} \mid i_X(d\eta_j) = 0 \text{ for each } j=1,2,3\}$          | 4m                    |
| ▶ $\mathcal{H}_1 \oplus \mathcal{V}$  | 4m+3                  |
| ▶ $\mathcal{H}_2 \oplus \mathcal{V}$ , with $\mathcal{H}_2 := \mathcal{H}_1^\perp \cap \mathcal{H}$ | 4l+3                  |

where:  $4n+3 = \dim(M)$ ,  $4l+3 = \text{rank}(M)$ ,  $m = n - l$ .

- The distributions  $\mathcal{H}_1$ ,  $\mathcal{H}_2$  and  $\mathcal{V}$  are mutually orthogonal and one has the following orthogonal decomposition

$$T_p M = \mathcal{H}_{1p} \oplus \mathcal{H}_{2p} \oplus \mathcal{V}_p = \mathcal{H}_p \oplus \mathcal{V}_p.$$

- $\varphi_i(\mathcal{H}_1) \subset \mathcal{H}_1$ ,  $\varphi_i(\mathcal{H}_2) \subset \mathcal{H}_2$  and  $\varphi_i(\mathcal{V}) \subset \mathcal{V}$ , for each  $i \in \{1,2,3\}$ .
- $[\xi_i, \mathcal{H}_1] \subset \mathcal{H}_1$ ,  $[\xi_i, \mathcal{H}_2] \subset \mathcal{H}_2$ , for each  $i \in \{1,2,3\}$ .

The results of our study on the “transverse geometry” with respect to those foliations is summarized in the following table:

<i>foliation</i>	<i>leaves</i>	<i>space of leaves</i>
$\mathcal{V}$	3-dimensional Lie groups $\mathbb{R}^3$ or $SO(3)$	Almost quaternionic- Hermitian
$\mathcal{H}_1$	Hyper-Kähler	3- $\alpha$ -Sasakian
$\mathcal{H}_1 \oplus \mathcal{V}$	3-cosymplectic	Quaternionic-Kähler
$\mathcal{H}_2 \oplus \mathcal{V}$	3- $\alpha$ -Sasakian	Hyper-Kähler