

Geodesic completeness of pseudo-Riemannian Lie groups

Ana Cristina Ferreira

Centro de Matemática da Universidade do Minho

(Joint with A. Elshafei, M. Sánchez and A. Zeghib)



Prospects in Geometry and Global Analysis
Schloss Rauischholzhausen
21–25 August, 2023

A 2-dimensional example

A 2-dimensional example

Consider

$\text{Aff}^+(\mathbb{R})$: group of orientation preserving motions of the real line
 $f(x) = ax + b, \quad a, b \in \mathbb{R}, a > 0$

A 2-dimensional example

Consider

$\text{Aff}^+(\mathbb{R})$: group of orientation preserving motions of the real line

$$f(x) = ax + b, \quad a, b \in \mathbb{R}, a > 0$$

$$\text{Aff}^+(\mathbb{R}) = \mathbb{R}^+ \ltimes \mathbb{R} = \left\{ \begin{pmatrix} x & y \\ 0 & 1 \end{pmatrix} : x, y \in \mathbb{R}, x > 0 \right\}$$

Left-invariant vector fields: $X_1 = x \frac{\partial}{\partial x}$, $X_2 = x \frac{\partial}{\partial y}$

Left-invariant metrics: $g(X_i, X_j) = \text{const.}$, $i, j = 1, 2$

$$g = \frac{1}{x^2}(c_1 dx^2 + c_2(dx dy + dy dx) + c_3 dy^2), \quad c_1 c_3 - c_2^2 \neq 0.$$

A 2-dimensional example

Consider

$\text{Aff}^+(\mathbb{R})$: group of orientation preserving motions of the real line

$$f(x) = ax + b, \quad a, b \in \mathbb{R}, a > 0$$

$$\text{Aff}^+(\mathbb{R}) = \mathbb{R}^+ \ltimes \mathbb{R} = \left\{ \begin{pmatrix} x & y \\ 0 & 1 \end{pmatrix} : x, y \in \mathbb{R}, x > 0 \right\}$$

Left-invariant vector fields: $X_1 = x \frac{\partial}{\partial x}$, $X_2 = x \frac{\partial}{\partial y}$

Left-invariant metrics: $g(X_i, X_j) = \text{const.}$, $i, j = 1, 2$

$$g = \frac{1}{x^2}(c_1 dx^2 + c_2(dx dy + dy dx) + c_3 dy^2), \quad c_1 c_3 - c_2^2 \neq 0.$$

→ Question: Which of these metrics are *complete*?

Geodesic equations

(M, g) (connected) pseudo-Riemannian manifold

$\mathcal{X}_\gamma(M)$: vector fields along a curve γ in M

Covariant derivative: $\nabla_{\dot{\gamma}} : \mathcal{X}_\gamma(M) \longrightarrow \mathcal{X}_\gamma(M)$

Geodesic equations

(M, g) (connected) pseudo-Riemannian manifold

$\mathcal{X}_\gamma(M)$: vector fields along a curve γ in M

Covariant derivative: $\nabla_{\dot{\gamma}} : \mathcal{X}_\gamma(M) \longrightarrow \mathcal{X}_\gamma(M)$

γ is called a **geodesic** if it satisfies $\nabla_{\dot{\gamma}}\dot{\gamma} = 0$.

In local coordinates (x_1, \dots, x_n)

$$\ddot{\gamma}^k(t) + \dot{\gamma}^i(t)\dot{\gamma}^j(t)\Gamma_{ij}^k(\gamma(t)) = 0$$

where Γ_{ij}^k are the Christoffel symbols (of the Levi-Civita connection).

Geodesic equations

(M, g) (connected) pseudo-Riemannian manifold

$\mathcal{X}_\gamma(M)$: vector fields along a curve γ in M

Covariant derivative: $\nabla_{\dot{\gamma}} : \mathcal{X}_\gamma(M) \longrightarrow \mathcal{X}_\gamma(M)$

γ is called a **geodesic** if it satisfies $\nabla_{\dot{\gamma}}\dot{\gamma} = 0$.

In local coordinates (x_1, \dots, x_n)

$$\ddot{\gamma}^k(t) + \dot{\gamma}^i(t)\dot{\gamma}^j(t)\Gamma_{ij}^k(\gamma(t)) = 0$$

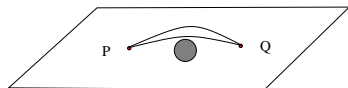
where Γ_{ij}^k are the Christoffel symbols (of the Levi-Civita connection).

A geodesic γ is called

→ **complete** if it is defined in \mathbb{R} .

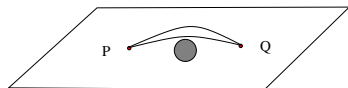
→ (M, g) is said to be **complete** if all of its geodesics are complete.

Remark

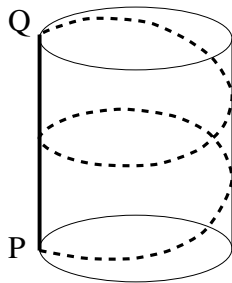


→ There might not be a geodesic between two arbitrary points.

Remark



→ There might not be a geodesic between two arbitrary points.



→ There might be more than one geodesic between two points.
→ A geodesic is not necessarily minimizing.

Riemannian vs. pseudo-Riemannian geometry

Hopf-Rinow theorem

For a Riemannian manifold (M, g) the following conditions are equivalent:

- (MC) As a metric space with Riem. distance d , (M, d) is Cauchy-complete.
- (GC) (M, g) is geodesically complete.
- (HB) Every closed and bounded subset of M is compact.

Riemannian vs. pseudo-Riemannian geometry

Hopf-Rinow theorem

For a Riemannian manifold (M, g) the following conditions are equivalent:

- (MC) As a metric space with Riem. distance d , (M, d) is Cauchy-complete.
- (GC) (M, g) is geodesically complete.
- (HB) Every closed and bounded subset of M is compact.

Companion results:

For a complete Riemannian manifold (M, g)

- Any two points can be joined by a minimizing geodesic segment.
- The length of any diverging curve is infinite.

Riemannian vs. pseudo-Riemannian geometry

Hopf-Rinow theorem

For a Riemannian manifold (M, g) the following conditions are equivalent:

(MC) As a metric space with Riem. distance d , (M, d) is Cauchy-complete.

(GC) (M, g) is geodesically complete.

(HB) Every closed and bounded subset of M is compact.

Companion results:

For a complete Riemannian manifold (M, g)

→ Any two points can be joined by a minimizing geodesic segment.

→ The length of any diverging curve is infinite.

Theorem

(G, g) : G a Lie group with g a left-invariant Riemannian metric is geodesically complete.

However:

PR manifolds can fail to be complete even in the compact case!

However:

PR manifolds can fail to be complete even in the compact case!

Example: Clifton-Pohl torus

$$(M = \mathbb{R}^2 \setminus \{(0,0)\}, g), \quad g = 2 \frac{dx dy}{x^2 + y^2}$$

$$\text{Geodesic equations: } \ddot{x} = \frac{2x}{x^2 + y^2} (\dot{x})^2, \quad \ddot{y} = \frac{2y}{x^2 + y^2} (\dot{y})^2$$

The curve $\alpha(t) = \left(\frac{1}{1-t}, 0\right)$ is an incomplete (null) geodesic.

However:

PR manifolds can fail to be complete even in the compact case!

Example: Clifton-Pohl torus

$$(M = \mathbb{R}^2 \setminus \{(0,0)\}, g), \quad g = 2 \frac{dxdy}{x^2 + y^2}$$

$$\text{Geodesic equations: } \ddot{x} = \frac{2x}{x^2+y^2} (\dot{x})^2, \quad \ddot{y} = \frac{2y}{x^2+y^2} (\dot{y})^2$$

The curve $\alpha(t) = \left(\frac{1}{1-t}, 0\right)$ is an incomplete (null) geodesic.

$\mu(x, y) = 2(x, y)$ is an isometry, $\Gamma = \{\mu^n\}$ is properly discontinuous.

$T = M/\Gamma$ is a torus which is incomplete with the induced metric.

However:

PR manifolds can fail to be complete even in the compact case!

Example: Clifton-Pohl torus

$$(M = \mathbb{R}^2 \setminus \{(0,0)\}, g), \quad g = 2 \frac{dxdy}{x^2 + y^2}$$

$$\text{Geodesic equations: } \ddot{x} = \frac{2x}{x^2+y^2} (\dot{x})^2, \quad \ddot{y} = \frac{2y}{x^2+y^2} (\dot{y})^2$$

The curve $\alpha(t) = \left(\frac{1}{1-t}, 0\right)$ is an incomplete (null) geodesic.

$\mu(x, y) = 2(x, y)$ is an isometry, $\Gamma = \{\mu^n\}$ is properly discontinuous.

$T = M/\Gamma$ is a torus which is incomplete with the induced metric.

Nevertheless...

(Marsden, 1973)

Compact PR **homogeneous spaces** are geodesically complete.

Euler-Arnold formalism on Lie groups

Euler-Arnold formalism on Lie groups

Euler and later Arnold:

→ described the motions of a rigid body as geodesics of a Lie group in the context of perfect fluids.

Euler-Arnold formalism on Lie groups

Euler and later Arnold:

→ described the motions of a rigid body as geodesics of a Lie group in the context of perfect fluids.

→ Key idea:

Geodesic curves	$\xleftrightarrow{1:1}$	Integral curves of vector field
on Lie group		on Lie algebra

Euler-Arnold formalism on Lie groups

Euler and later Arnold:

→ described the motions of a rigid body as geodesics of a Lie group in the context of perfect fluids.

→ Key idea:

Geodesic curves	$\xleftrightarrow{1:1}$	Integral curves of vector field
on Lie group		on Lie algebra

→ Key advantage:

geodesics seen as curves in \mathbb{R}^n with standard topology;
easier to control behaviour at infinity.

$\gamma(t)$ curve in G and $x(t)$ the associated curve in \mathfrak{g} given by $x(t) = \gamma^{-1}(t)\dot{\gamma}(t)$

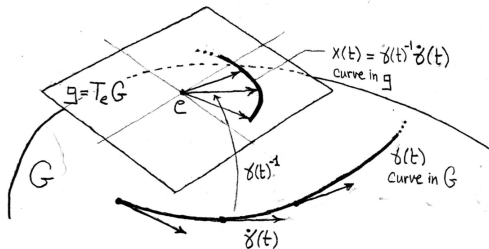


Figure: Associate curve in \mathfrak{g}

$\gamma(t)$ curve in G and $x(t)$ the associated curve in \mathfrak{g} given by $x(t) = \gamma^{-1}(t)\dot{\gamma}(t)$

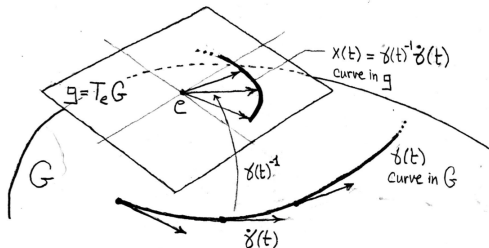


Figure: Associate curve in \mathfrak{g}

Theorem

(Arnold, 1966)

Then $\gamma(t)$ is a geodesic iff $x(t)$ is an integral curve of

$$\dot{x}(t) = \text{ad}_{x(t)}^\dagger x(t)$$

Clairaut first integrals

Interesting facts:

- If γ is geodesic, X is Killing field, then $g(\dot{\gamma}(t), X_{\gamma(t)}) = \text{constant}$.
- If X is a right-invariant vector field, then X is Killing for any LI metric.

Clairaut first integrals

Interesting facts:

- If γ is geodesic, X is Killing field, then $g(\dot{\gamma}(t), X_{\gamma(t)}) = \text{constant}$.
- If X is a right-invariant vector field, then X is Killing for any LI metric.

The construction:

Let (e_i) be a basis of \mathfrak{g} .

Denote by Y_i the extension of e_i as a right-invariant vector field.

Then $\omega^i = g(Y_i, \cdot)$ is a first integral of the geodesic equations.

The (ω^i) span T^*G .

Clairaut first integrals

Interesting facts:

- If γ is geodesic, X is Killing field, then $g(\dot{\gamma}(t), X_{\gamma(t)}) = \text{constant}$.
- If X is a right-invariant vector field, then X is Killing for any LI metric.

The construction:

Let (e_i) be a basis of \mathfrak{g} .

Denote by Y_i the extension of e_i as a right-invariant vector field.

Then $\omega^i = g(Y_i, \cdot)$ is a first integral of the geodesic equations.

The (ω^i) span T^*G .

Definition

(Elshafei, F., Sánchez, Zeghib, 2023)

The *Clairaut metric* associated to g from (e_i) is the Riemannian metric defined by

$$h = \sum_i \omega^i \otimes \omega^i$$

Transformation law:

For $u, v \in \mathfrak{g}$

$$\begin{aligned}\omega^i(p.u) &= g_p(Y_i(p), p.u) = g_p(ei.p, p.u) = g_1(\mathrm{Ad}_{p^{-1}}(e_i), u) \\ &= g_1(e_i, ((\mathrm{Ad}_p)^{-1})^\dagger(u)) = \omega_1^i(((\mathrm{Ad}_p)^\dagger)^{-1}(u))\end{aligned}$$

Transformation law:

For $u, v \in \mathfrak{g}$

$$\begin{aligned}\omega^i(p.u) &= g_p(Y_i(p), p.u) = g_p(ei.p, p.u) = g_1(\text{Ad}_{p^{-1}}(e_i), u) \\ &= g_1(e_i, ((\text{Ad}_p)^{-1})^\dagger(u)) = \omega_1^i(((\text{Ad}_p)^\dagger)^{-1}(u))\end{aligned}$$

and a concrete expression for h is

$$h(p.u, p.v) = \sum_i g_1((\text{Ad}_{p^{-1}})(e_i), u) g_1((\text{Ad}_{p^{-1}})(e_i), v).$$

Transformation law:

For $u, v \in \mathfrak{g}$

$$\begin{aligned}\omega^i(p.u) &= g_p(Y_i(p), p.u) = g_p(e_i.p, p.u) = g_1(\text{Ad}_{p^{-1}}(e_i), u) \\ &= g_1(e_i, ((\text{Ad}_p)^{-1})^\dagger(u)) = \omega_1^i(((\text{Ad}_p)^\dagger)^{-1}(u))\end{aligned}$$

and a concrete expression for h is

$$h(p.u, p.v) = \sum_i g_1((\text{Ad}_{p^{-1}})(e_i), u) g_1((\text{Ad}_{p^{-1}})(e_i), v).$$

→ h is **not** left-invariant (nor right-invariant unless g is bi-invariant)

Transformation law:

For $u, v \in \mathfrak{g}$

$$\begin{aligned}\omega^i(p.u) &= g_p(Y_i(p), p.u) = g_p(e_i.p, p.u) = g_1(\text{Ad}_{p^{-1}}(e_i), u) \\ &= g_1(e_i, ((\text{Ad}_p)^{-1})^\dagger(u)) = \omega_1^i(((\text{Ad}_p)^\dagger)^{-1}(u))\end{aligned}$$

and a concrete expression for h is

$$h(p.u, p.v) = \sum_i g_1((\text{Ad}_{p^{-1}})(e_i), u) g_1((\text{Ad}_{p^{-1}})(e_i), v).$$

→ h is **not** left-invariant (nor right-invariant unless g is bi-invariant)

Definition Two Riemannian metrics R and \hat{R} are said to be **bi-Lipschitz** bounded if there exists a constant $c > 0$ s.t. $c R \leq \hat{R} \leq R/c$.

Transformation law:

For $u, v \in \mathfrak{g}$

$$\begin{aligned}\omega^i(p.u) &= g_p(Y_i(p), p.u) = g_p(e_i.p, p.u) = g_1(\text{Ad}_{p^{-1}}(e_i), u) \\ &= g_1(e_i, ((\text{Ad}_p)^{-1})^\dagger(u)) = \omega_1^i(((\text{Ad}_p)^\dagger)^{-1}(u))\end{aligned}$$

and a concrete expression for h is

$$h(p.u, p.v) = \sum_i g_1((\text{Ad}_{p^{-1}})(e_i), u) g_1((\text{Ad}_{p^{-1}})(e_i), v).$$

→ h is **not** left-invariant (nor right-invariant unless g is bi-invariant)

Definition Two Riemannian metrics R and \hat{R} are said to be **bi-Lipschitz** bounded if there exists a constant $c > 0$ s.t. $c R \leq \hat{R} \leq R/c$.

Proposition

(EFSZ, 23)

Let h and \hat{h} be two Clairaut metrics associated to g from the bases (e_i) and (\hat{e}_i) , resp., then h and \hat{h} are bi-Lipschitz bounded.

Completeness

- $\omega^i(\dot{\gamma}(t))$ is constant for any inextensible geodesic γ of g
- thus $h(\dot{\gamma}(t), \dot{\gamma}(t))$ is constant

Completeness

- $\omega^i(\dot{\gamma}(t))$ is constant for any inextensible geodesic γ of g
- thus $h(\dot{\gamma}(t), \dot{\gamma}(t))$ is constant

Theorem

(EFSZ, 23)

The left-invariant **pseudo-Riemannian** metric g is complete if its associated Clairaut metric h is complete.

Completeness

→ $\omega^i(\dot{\gamma}(t))$ is constant for any inextensible geodesic γ of g

→ thus $h(\dot{\gamma}(t), \dot{\gamma}(t))$ is constant

Theorem

(EFSZ, 23)

The left-invariant **pseudo-Riemannian** metric g is complete if its associated Clairaut metric h is complete.

Proof: The curve γ restricted to any bounded interval $I \subset \mathbb{R}$ has finite h -length. Thus, by the completeness of h , γ is continuously extensible to the closure of I and, then, it is extensible as a geodesic of g . □

Completeness

→ $\omega^i(\dot{\gamma}(t))$ is constant for any inextensible geodesic γ of g

→ thus $h(\dot{\gamma}(t), \dot{\gamma}(t))$ is constant

Theorem

(EFSZ, 23)

The left-invariant **pseudo-Riemannian** metric g is complete if its associated Clairaut metric h is complete.

Proof: The curve γ restricted to any bounded interval $I \subset \mathbb{R}$ has finite h -length. Thus, by the completeness of h , γ is continuously extensible to the closure of I and, then, it is extensible as a geodesic of g . □

Corollary

Any **bi-invariant** PR metric g on G is complete.

Completeness

→ $\omega^i(\dot{\gamma}(t))$ is constant for any inextensible geodesic γ of g

→ thus $h(\dot{\gamma}(t), \dot{\gamma}(t))$ is constant

Theorem

(EFSZ, 23)

The left-invariant **pseudo-Riemannian** metric g is complete if its associated Clairaut metric h is complete.

Proof: The curve γ restricted to any bounded interval $I \subset \mathbb{R}$ has finite h -length. Thus, by the completeness of h , γ is continuously extensible to the closure of I and, then, it is extensible as a geodesic of g . □

Corollary

Any **bi-invariant** PR metric g on G is complete.

Corollary

(Marsden, 1973)

Any left-invariant PR metric g on a **compact** Lie group G is complete.

Wick rotation

(G, g) PR Lie group.

- Choose an ON basis (e_i) for g_1
- Construct a LI Riem. metric \tilde{g} by imposing that (e_i) is ON for \tilde{g}_1 .

Wick rotation

(G, g) PR Lie group.

- Choose an ON basis (e_i) for g_1
- Construct a LI Riem. metric \tilde{g} by imposing that (e_i) is ON for \tilde{g}_1 .
- \tilde{g} is obtained from g by *Wick rotation*.

Wick rotation

(G, g) PR Lie group.

→ Choose an ON basis (e_i) for g_1

→ Construct a LI Riem. metric \tilde{g} by imposing that (e_i) is ON for \tilde{g}_1 .

→ \tilde{g} is obtained from g by *Wick rotation*.

More precisely, consider

→ the linear map ψ such that $\psi(e_i) = \epsilon_i e_i$

→ \tilde{g} be the LI Riem. metric such that $\tilde{g}_1(e_i, e_j) = \delta_{ij} = g_1(e_i, \psi(e_j))$.

Wick rotation

(G, g) PR Lie group.

→ Choose an ON basis (e_i) for g_1

→ Construct a LI Riem. metric \tilde{g} by imposing that (e_i) is ON for \tilde{g}_1 .

→ \tilde{g} is obtained from g by *Wick rotation*.

More precisely, consider

→ the linear map ψ such that $\psi(e_i) = \epsilon_i e_i$

→ \tilde{g} be the LI Riem. metric such that $\tilde{g}_1(e_i, e_j) = \delta_{ij} = g_1(e_i, \psi(e_j))$.

Proposition

(EFSZ, 23)

Let g, \tilde{g} be Wick rotated metrics and h the Clairaut metric associated to g from (e_i) . Then, h is unique (independent of the chosen (e_i)) and

$$h_p(p.u, p.v) = \tilde{g}_1(\text{Ad}_{p-1}^*(\psi(u)), \text{Ad}_{p-1}^*(\psi(v)))$$

Wick rotation

(G, g) PR Lie group.

→ Choose an ON basis (e_i) for g_1

→ Construct a LI Riem. metric \tilde{g} by imposing that (e_i) is ON for \tilde{g}_1 .

→ \tilde{g} is obtained from g by *Wick rotation*.

More precisely, consider

→ the linear map ψ such that $\psi(e_i) = \epsilon_i e_i$

→ \tilde{g} be the LI Riem. metric such that $\tilde{g}_1(e_i, e_j) = \delta_{ij} = g_1(e_i, \psi(e_j))$.

Proposition

(EFSZ, 23)

Let g, \tilde{g} be Wick rotated metrics and h the Clairaut metric associated to g from (e_i) . Then, h is unique (independent of the chosen (e_i)) and

$$h_p(p.u, p.v) = \tilde{g}_1(\text{Ad}_{p-1}^*(\psi(u)), \text{Ad}_{p-1}^*(\psi(v)))$$

Remark: If g is Riemannian then $\tilde{g} = g$.

The action of $\text{Aut}(G)$

The action of $\text{Aut}(G)$

Lie's second theorem : $\text{Aut}(\mathfrak{g})$ is in 1:1 correspondence with $\text{Aut}(\tilde{G})$.

The action of $\text{Aut}(G)$

Lie's second theorem : $\text{Aut}(\mathfrak{g})$ is in 1:1 correspondence with $\text{Aut}(\tilde{G})$.

→ $\text{Aut}(\mathfrak{g})$ acts on $\text{Sym}(\mathfrak{g})$ by

$$(\varphi.m)(u, v) = m(\varphi^{-1}u, \varphi^{-1}v).$$

with $\varphi \in \text{Aut}(\mathfrak{g})$, $m \in \text{Sym}(\mathfrak{g})$ and $u, v \in \mathfrak{g}$.

The action of $\text{Aut}(G)$

Lie's second theorem : $\text{Aut}(\mathfrak{g})$ is in 1:1 correspondence with $\text{Aut}(\tilde{G})$.

→ $\text{Aut}(\mathfrak{g})$ acts on $\text{Sym}(\mathfrak{g})$ by

$$(\varphi.m)(u, v) = m(\varphi^{-1}u, \varphi^{-1}v).$$

with $\varphi \in \text{Aut}(\mathfrak{g})$, $m \in \text{Sym}(\mathfrak{g})$ and $u, v \in \mathfrak{g}$.

Proposition

(EFSZ, 23)

G connected Lie group, g LI PR metric, $\varphi \in \text{Aut}(\mathfrak{g})$, g^φ the LI metric such that $(g^\varphi)_1 = \varphi.g_1$. Then:

- (1) g^φ is complete if and only if so is g .
- (2) LI PR metrics in each orbit of $\text{Sym}(\mathfrak{g})$ are all complete or incomplete.
- (3) Clairaut metrics associated to LI metrics on the same orbit are all bi-Lipschitz bounded.

2-dimensional example revisited

Recall

$$G = \text{Aff}^+(\mathbb{R}) = \mathbb{R}^+ \ltimes \mathbb{R} = \left\{ \begin{pmatrix} x & y \\ 0 & 1 \end{pmatrix} : x, y \in \mathbb{R}, x > 0 \right\}$$

and the LI PR metrics

$$g = \frac{1}{x^2}(c_1 dx^2 + c_2(dx dy + dy dx) + c_3 dy^2), \quad c_1 c_3 - c_2^2 \neq 0.$$

2-dimensional example revisited

Recall

$$G = \text{Aff}^+(\mathbb{R}) = \mathbb{R}^+ \ltimes \mathbb{R} = \left\{ \begin{pmatrix} x & y \\ 0 & 1 \end{pmatrix} : x, y \in \mathbb{R}, x > 0 \right\}$$

and the LI PR metrics

$$g = \frac{1}{x^2}(c_1 dx^2 + c_2(dx dy + dy dx) + c_3 dy^2), \quad c_1 c_3 - c_2^2 \neq 0.$$

→ Three special metrics

$$g^{(1)} = \frac{1}{x^2}(dx^2 + dy^2) \qquad (c_1 = 1, c_2 = 0, c_3 = 1)$$

$$g^{(-1)} = \frac{1}{x^2}(dx^2 - dy^2) \qquad (c_1 = 1, c_2 = 0, c_3 = -1)$$

$$g^{(0)} = \frac{1}{x^2}(dx dy + dy dx) \qquad (c_1 = 0, c_2 = 1, c_3 = 0)$$

2-dimensional example revisited

Recall

$$G = \text{Aff}^+(\mathbb{R}) = \mathbb{R}^+ \ltimes \mathbb{R} = \left\{ \begin{pmatrix} x & y \\ 0 & 1 \end{pmatrix} : x, y \in \mathbb{R}, x > 0 \right\}$$

and the LI PR metrics

$$g = \frac{1}{x^2}(c_1 dx^2 + c_2(dx dy + dy dx) + c_3 dy^2), \quad c_1 c_3 - c_2^2 \neq 0.$$

→ Three special metrics

$$g^{(1)} = \frac{1}{x^2}(dx^2 + dy^2) \quad (c_1 = 1, c_2 = 0, c_3 = 1)$$

$$g^{(-1)} = \frac{1}{x^2}(dx^2 - dy^2) \quad (c_1 = 1, c_2 = 0, c_3 = -1)$$

$$g^{(0)} = \frac{1}{x^2}(dx dy + dy dx) \quad (c_1 = 0, c_2 = 1, c_3 = 0)$$

→ Can be studied to characterize completeness on G , as shall be seen.

$$\longrightarrow g^{(1)} = \frac{1}{x^2}(dx^2 + dy^2)$$

LI Riemannian (hyperbolic) metric, therefore complete.

$$\text{Clairaut metric: } h^{(1)} = \frac{1}{x^4} (x^2 dx^2 + (1 + y^2) dy^2 + xy(dx dy + dy dx))$$

After some work: $h^{(1)}$ is proved to be complete.

$$\longrightarrow g^{(1)} = \frac{1}{x^2}(dx^2 + dy^2)$$

LI Riemannian (hyperbolic) metric, therefore complete.

$$\text{Clairaut metric: } h^{(1)} = \frac{1}{x^4} (x^2 dx^2 + (1 + y^2) dy^2 + xy(dx dy + dy dx))$$

After some work: $h^{(1)}$ is proved to be complete.

$$\longrightarrow g^{(-1)} = \frac{1}{x^2}(dx^2 - dy^2)$$

$$\gamma(t) = \left(\frac{1}{1-t}, \frac{1}{1-t} \right) \text{ incomplete (null) geodesic.}$$

$$\text{Clairaut metric: } h^{(-1)} = \frac{1}{x^4} (x^2 dx^2 + (1 + y^2) dy^2 - xy(dx dy + dy dx))$$

$h^{(1)}$ is automatically incomplete.

$$\longrightarrow g^{(1)} = \frac{1}{x^2}(dx^2 + dy^2)$$

LI Riemannian (hyperbolic) metric, therefore complete.

$$\text{Clairaut metric: } h^{(1)} = \frac{1}{x^4} (x^2 dx^2 + (1 + y^2) dy^2 + xy(dxdy + dydx))$$

After some work: $h^{(1)}$ is proved to be complete.

$$\longrightarrow g^{(-1)} = \frac{1}{x^2}(dx^2 - dy^2)$$

$$\gamma(t) = \left(\frac{1}{1-t}, \frac{1}{1-t} \right) \text{ incomplete (null) geodesic.}$$

$$\text{Clairaut metric: } h^{(-1)} = \frac{1}{x^4} (x^2 dx^2 + (1 + y^2) dy^2 - xy(dxdy + dydx))$$

$h^{(1)}$ is automatically incomplete.

$$\longrightarrow g^{(0)} = \frac{1}{x^2}(dxdy + dydx)$$

$$\gamma(t) = \left(\frac{1}{1-t}, 0 \right) \text{ incomplete (null) geodesic.}$$

$$\text{Clairaut metric: } h^{(0)} = \frac{1}{x^4} ((1 + y^2) dx^2 + x^2 dy^2 + xy(dxdy + dydx))$$

$h^{(0)}$ is automatically incomplete.

Three classes and their (in)completeness

Consider the action $\text{Aut}(\mathfrak{g})$ on $\text{Sym}(\mathfrak{g})$.

- Basis (e_1, e_2) s.t. $[e_1, e_2] = e_2$.
- $\varphi : \mathfrak{g} \longrightarrow \mathfrak{g} \in \text{Aut}(\mathfrak{g})$ satisfies $[\varphi(e_1), \varphi(e_2)] = \varphi(e_2)$
- W.r.t basis (e_1, e_2) , φ is represented by the matrix

$$M = \begin{pmatrix} 1 & 0 \\ \alpha & \beta \end{pmatrix}, \quad \beta \neq 0.$$

Three classes and their (in)completeness

Consider the action $\text{Aut}(\mathfrak{g})$ on $\text{Sym}(\mathfrak{g})$.

- Basis (e_1, e_2) s.t. $[e_1, e_2] = e_2$.
- $\varphi : \mathfrak{g} \longrightarrow \mathfrak{g} \in \text{Aut}(\mathfrak{g})$ satisfies $[\varphi(e_1), \varphi(e_2)] = \varphi(e_2)$
- W.r.t basis (e_1, e_2) , φ is represented by the matrix

$$M = \begin{pmatrix} 1 & 0 \\ \alpha & \beta \end{pmatrix}, \quad \beta \neq 0.$$

→ $\varphi^{-1} \in \text{Aut}(\mathfrak{g})$ acts on $\text{Sym}(\mathfrak{g})$ by $M^T B M$, for a bilinear form B .

Three classes and their (in)completeness

Consider the action $\text{Aut}(\mathfrak{g})$ on $\text{Sym}(\mathfrak{g})$.

- Basis (e_1, e_2) s.t. $[e_1, e_2] = e_2$.
- $\varphi : \mathfrak{g} \longrightarrow \mathfrak{g} \in \text{Aut}(\mathfrak{g})$ satisfies $[\varphi(e_1), \varphi(e_2)] = \varphi(e_2)$
- W.r.t basis (e_1, e_2) , φ is represented by the matrix

$$M = \begin{pmatrix} 1 & 0 \\ \alpha & \beta \end{pmatrix}, \quad \beta \neq 0.$$

→ $\varphi^{-1} \in \text{Aut}(\mathfrak{g})$ acts on $\text{Sym}(\mathfrak{g})$ by $M^T B M$, for a bilinear form B .

→ Orbit of $B = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$:

$$M^T B M = \begin{pmatrix} 1 & 0 \\ \alpha & \beta \end{pmatrix}^T \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ \alpha & \beta \end{pmatrix} = \begin{pmatrix} 1 + \alpha^2 & \alpha\beta \\ \alpha\beta & \beta^2 \end{pmatrix}$$

Up to (positive or negative) scaling, this orbit contains Euclidean (or negative definite) scalar products and, moreover, all of them.

→ Orbit of $B = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$:

$$M^T B M = \begin{pmatrix} 1 & 0 \\ \alpha & \beta \end{pmatrix}^T \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ \alpha & \beta \end{pmatrix} = \begin{pmatrix} 1 - \alpha^2 & -\alpha\beta \\ -\alpha\beta & -\beta^2 \end{pmatrix}$$

Up to scaling, this orbit corresponds to all Lorentzian scalar products such that $\langle e_2, e_2 \rangle \neq 0$.

→ Orbit of $B = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$:

$$M^T B M = \begin{pmatrix} 1 & 0 \\ \alpha & \beta \end{pmatrix}^T \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ \alpha & \beta \end{pmatrix} = \begin{pmatrix} 1 - \alpha^2 & -\alpha\beta \\ -\alpha\beta & -\beta^2 \end{pmatrix}$$

Up to scaling, this orbit corresponds to all Lorentzian scalar products such that $\langle e_2, e_2 \rangle \neq 0$.

→ Orbit of $B = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$:

$$M^T B M = \begin{pmatrix} 1 & 0 \\ \alpha & \beta \end{pmatrix}^T \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ \alpha & \beta \end{pmatrix} = \begin{pmatrix} 2\alpha & \beta \\ \beta & 0 \end{pmatrix}$$

This orbit corresponds to all Lorentzian scalar products such that $\langle e_2, e_2 \rangle = 0$.

→ Orbit of $B = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$:

$$M^T B M = \begin{pmatrix} 1 & 0 \\ \alpha & \beta \end{pmatrix}^T \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ \alpha & \beta \end{pmatrix} = \begin{pmatrix} 1 - \alpha^2 & -\alpha\beta \\ -\alpha\beta & -\beta^2 \end{pmatrix}$$

Up to scaling, this orbit corresponds to all Lorentzian scalar products such that $\langle e_2, e_2 \rangle \neq 0$.

→ Orbit of $B = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$:

$$M^T B M = \begin{pmatrix} 1 & 0 \\ \alpha & \beta \end{pmatrix}^T \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ \alpha & \beta \end{pmatrix} = \begin{pmatrix} 2\alpha & \beta \\ \beta & 0 \end{pmatrix}$$

This orbit corresponds to all Lorentzian scalar products such that $\langle e_2, e_2 \rangle = 0$.

Therefore:

Prop.(2) proves that **all** the LI **Lorentzian** metrics on G are incomplete.

Prop.(3) shows the existence of only 3 bi-Lipschitz Clairaut classes.

A question

→ What classes of Lie groups have **all** of their PR LI metrics **complete**?

A question

→ What classes of Lie groups have **all** of their PR LI metrics **complete**?

Positive answers

→ Abelian

→ Compact

(Marsden, 1973)

→ 2-step nilpotent

(Guediri, 1994)

→ $\mathrm{SO}(2) \ltimes \mathbb{R}^2$

(Bromberg-Medina, 2008)

A question

→ What classes of Lie groups have **all** of their PR LI metrics **complete**?

Positive answers

→ Abelian

→ Compact

(Marsden, 1973)

→ 2-step nilpotent

(Guediri, 1994)

→ $SO(2) \ltimes \mathbb{R}^2$

(Bromberg-Medina, 2008)

Negative answer

(Elshafei, F., Reis, 2023)

G non-compact semisimple real Lie group.

G can be equipped with (many) **incomplete** LI PR metrics

A question

→ What classes of Lie groups have **all** of their PR LI metrics **complete**?

Positive answers

→ Abelian

→ Compact

(Marsden, 1973)

→ 2-step nilpotent

(Guediri, 1994)

→ $SO(2) \ltimes \mathbb{R}^2$

(Bromberg-Medina, 2008)

Negative answer

(Elshafei, F., Reis, 2023)

G non-compact semisimple real Lie group.

G can be equipped with (many) **incomplete** LI PR metrics

However...

Proposition

(Elshafei, F., Reis, 2023)

G quadratic Lie group.

For **every possible signature**, there is a open set of LI PR **complete** metrics.

Preservation of completeness

Proposition

(M, R) connected **complete Riemannian** manifold.

Choose $x_0 \in M$ and let $M \ni x \mapsto d_R(x)$ be the distance function from x_0 .

If h is a Riemannian metric on M with pointwise norm $\|\cdot\|_h$ satisfying:

$$\|v_x\|_h \geq \frac{\|v_x\|_R}{a + b d_R(x)}, \quad \forall x \in M, v_x \in T_x M$$

for some constants $a, b \geq 0$, then h is **complete**.

Preservation of completeness

Proposition

(M, R) connected **complete Riemannian** manifold.

Choose $x_0 \in M$ and let $M \ni x \mapsto d_R(x)$ be the distance function from x_0 .

If h is a Riemannian metric on M with pointwise norm $\|\cdot\|_h$ satisfying:

$$\|v_x\|_h \geq \frac{\|v_x\|_R}{a + b d_R(x)}, \quad \forall x \in M, v_x \in T_x M$$

for some constants $a, b \geq 0$, then h is **complete**.

Remarks

→ $\varphi(r) = a + b r$ can be replaced with any Lipschitz function φ s.t.
 $\int_0^\infty \frac{1}{\varphi(r)} dr = \infty$.

→ similar types of bounds have been known since the 70s
[Abraham-Marsden, Foundations of mechanics, 1987]

Groups of linear growth

Let R be a LI Riemannian metric on a Lie group G .

Consider the map

$$r : G \longrightarrow \mathbb{R} \quad \text{where} \quad r(p) = d_R(1, p)$$

and d_R is the distance induced by the Riemannian metric R .

Groups of linear growth

Let R be a LI Riemannian metric on a Lie group G .

Consider the map

$$r : G \longrightarrow \mathbb{R} \quad \text{where} \quad r(p) = d_R(1, p)$$

and d_R is the distance induced by the Riemannian metric R .

Definition

(EFSZ, 23)

A Lie group G has (at most) **linear growth** if there exist

→ a LI Riemannian metric R on G

→ a Euclidean scalar product with norm $\|\cdot\|$ on \mathfrak{g}

$$\text{s.t.} \quad \frac{\|u\|}{a + b r(p)} \leq \|\text{Ad}_p(u)\| \leq (a + b r(p))\|u\|$$

for some constants $a, b \geq 0$, for every $p \in G$ and for every $u \in \mathfrak{g}$.

Groups of linear growth

Let R be a LI Riemannian metric on a Lie group G .

Consider the map

$$r : G \longrightarrow \mathbb{R} \quad \text{where} \quad r(p) = d_R(1, p)$$

and d_R is the distance induced by the Riemannian metric R .

Definition

(EFSZ, 23)

A Lie group G has (at most) **linear growth** if there exist

→ a LI Riemannian metric R on G

→ a Euclidean scalar product with norm $\|\cdot\|$ on \mathfrak{g}

$$\text{s.t.} \quad \frac{\|u\|}{a + b r(p)} \leq \|\text{Ad}_p(u)\| \leq (a + b r(p))\|u\|$$

for some constants $a, b \geq 0$, for every $p \in G$ and for every $u \in \mathfrak{g}$.

Remark: since R is LI, $r(p) = r(p^{-1})$, the two inequalities are equivalent, linear growth is independent of choice of LI R and $\|\cdot\|$.

Linear growth of Clairaut metrics

Theorem

(EFSZ, 23)

All the left-invariant pseudo-Riemannian metrics of a Lie group with linear growth are geodesically complete.

Linear growth of Clairaut metrics

Theorem

(EFSZ, 23)

All the left-invariant pseudo-Riemannian metrics of a Lie group with **linear growth** are geodesically **complete**.

Proof

Take LI PR g , choose ON basis, construct Wick rotated \tilde{g} and Clairaut h .
From the definition of h , can be computed that

$$h_p(p.u, p.u) \geq \frac{\tilde{g}_1(u, u)}{\|\text{Ad}_p\|^2}$$

Since $\|\text{Ad}_p\| \leq a + b r(p)$ then

$$\|v_p\|_h \geq \frac{\|v_p\|_{\tilde{g}}}{a + b r(p)}$$

and the result follows.



Linear growth of Clairaut metrics

Theorem

(EFSZ, 23)

All the left-invariant pseudo-Riemannian metrics of a Lie group with **linear growth** are geodesically **complete**.

Proof

Take LI PR g , choose ON basis, construct Wick rotated \tilde{g} and Clairaut h .
From the definition of h , can be computed that

$$h_p(p.u, p.u) \geq \frac{\tilde{g}_1(u, u)}{\|\text{Ad}_p\|^2}$$

Since $\|\text{Ad}_p\| \leq a + b r(p)$ then

$$\|v_p\|_h \geq \frac{\|v_p\|_{\tilde{g}}}{a + b r(p)}$$

and the result follows. □

Remark: $\text{Aff}^+(\mathbb{R})$ is not of linear growth.

Some groups of linear growth

Theorem

(EFSZ, 23)

The following classes of Lie groups have **linear growth**

- abelian, compact [in fact, bounded growth]
- 2-step nilpotent
- the semidirect product $K \ltimes_{\rho} \mathbb{R}^n$ where K is *pseudo-compact* and $\rho(K)$ is pre-compact in $\mathrm{GL}(n, \mathbb{R})$
- a subgroup or the direct product of the groups above

Some groups of linear growth

Theorem

(EFSZ, 23)

The following classes of Lie groups have **linear growth**

- abelian, compact [in fact, bounded growth]
- 2-step nilpotent
- the semidirect product $K \ltimes_{\rho} \mathbb{R}^n$ where K is *pseudo-compact* and $\rho(K)$ is pre-compact in $GL(n, \mathbb{R})$
- a subgroup or the direct product of the groups above

Corollary

All of the groups above have all their LI PR metrics **geodesically complete**.

Some groups of linear growth

Theorem

(EFSZ, 23)

The following classes of Lie groups have **linear growth**

- abelian, compact [in fact, bounded growth]
- 2-step nilpotent
- the semidirect product $K \ltimes_{\rho} \mathbb{R}^n$ where K is *pseudo-compact* and $\rho(K)$ is pre-compact in $GL(n, \mathbb{R})$
- a subgroup or the direct product of the groups above

Corollary

All of the groups above have all their LI PR metrics **geodesically complete**.

Proposition

(EFSZ, 23)

A k -step nilpotent Lie group, with $k \geq 3$, does not have linear growth.

An aside

An aside

Lemma

(F., Agricola, 2017)

G a compact Lie group.

There exists a Riemannian metric which is left-invariant for both

$G \times \mathfrak{g}$ and $G \ltimes_{\text{Ad}} \mathfrak{g}$.

An aside

Lemma

(F., Agricola, 2017)

G a compact Lie group.

There exists a Riemannian metric which is left-invariant for both

$G \times \mathfrak{g}$ and $G \ltimes_{\text{Ad}} \mathfrak{g}$.

Lemma

(EFSZ, 23)

K be a pseudo-compact Lie group, H be another Lie group s.t.

there is a homomorphism $\rho : K \longrightarrow \text{Aut}(H)$ with $\rho(K)$ pre-compact.

There exists a LI Riemannian metric on $K \ltimes_{\rho} H$ which is also LI for the direct product $K \times H$.

An aside

Lemma

(F., Agricola, 2017)

G a compact Lie group.

There exists a Riemannian metric which is left-invariant for both

$G \times \mathfrak{g}$ and $G \ltimes_{\text{Ad}} \mathfrak{g}$.

Lemma

(EFSZ, 23)

K be a pseudo-compact Lie group, H be another Lie group s.t.

there is a homomorphism $\rho : K \longrightarrow \text{Aut}(H)$ with $\rho(K)$ pre-compact.

There exists a LI Riemannian metric on $K \ltimes_{\rho} H$ which is also LI for the direct product $K \times H$.

Corollary

(EFSZ, 23)

Let K and H be two Lie groups as in Lemma above.

Then any pair of LI Riemannian metrics on $K \ltimes_{\rho} H$ and $K \times H$ are bi-Lipschitz bounded.

Thank you very much for the attention !

Proof of Lemma

Sketch.

- $G = K \ltimes_{\rho} H$
- K is pseudo-compact \Rightarrow a bi-invariant metric on K
- Moreover, $\rho(K)$ pre-compact \Rightarrow an $\text{Ad}(K)$ -invariant positive definite inner product on \mathfrak{g}
- R Riemannian metric on G induced by left translations
- Isometry group of (G, R) contains $K \times G$
- The map

$$(K \times G) \times G \longrightarrow G \quad \text{such that} \quad (k, x, y) \longmapsto xyk^{-1}$$

is an action of $K \times G$ on G which preserves the Riemannian metric R .

- Restrict this action to $K \times H$.
- The action of $K \times H$ on G is transitive and free
- Yields G as the principal homog. space $(K \times H)/\{1_G\} \cong K \times H$.