Higher transgressions of the Pfaffian form

Sergiu Moroianu

IMAR Bucharest

August 2023

Partly based on joint work with Daniel Cibotaru (Fortaleza) Partly supported by UEFISCDI

Sergiu Moroianu (IMAR Bucharest)

Transgressions of Pfaffian

August 2023 1 / 37

4 3 5 4 3

Motivation: volume of ideal hyperbolic 4-simplex



• $\alpha + \beta + \gamma = \pi$ dihedral angles

Sergiu Moroianu (IMAR Bucharest)

Transgressions of Pfaffian

August 2023 2 / 37

Motivation: volume of ideal hyperbolic 4-simplex



- $\alpha + \beta + \gamma = \pi$ dihedral angles
- Volume = $\Pi(\alpha) + \Pi(\beta) + \Pi(\gamma)$, where Π =Lobachevski function

$$\Pi(x) = -\int_0^x \log|2\sin(t)| \mathrm{d}t$$

Sergiu Moroianu (IMAR Bucharest)

Motivation: volume of ideal hyperbolic 4-simplex



- $\alpha + \beta + \gamma = \pi$ dihedral angles
- Volume = $\Pi(\alpha) + \Pi(\beta) + \Pi(\gamma)$, where Π =Lobachevski function

$$\Pi(x) = -\int_0^x \log|2\sin(t)| \mathrm{d}t$$

• How about dimension 4?

Euclidean (flat) geometry

• Sum of angles in a triangle = π



3

Euclidean (flat) geometry

• Sum of angles in a triangle = π



• Sum of exterior angles in every triangle = 2π

Sum of exterior angles

• Sum of exterior angles in every convex polygon = 2π



Exterior angles

• Two definitions of exterior angles



э

イロト イポト イヨト イヨト

Exterior angles



< E

э

Exterior angles



 Angle defect:= sum of ext angles -2π: In a planar polygon, the angle defect vanishes.

Sergiu Moroianu (IMAR Bucharest)

August 2023 5 / 37

-

Plane Gauss map

• Gauss map: the unit exterior normal is constant along each side; finite number of points on the unit circle; each arc between them has measure equal to an exterior angle



• Surface $\Sigma \subset \mathbb{R}^3$, Gauss map $G : \Sigma \to \mathbb{S}^2$, $p \mapsto \nu_p =$ unit normal to Σ in p.

イロト イポト イヨト イヨト

- Surface $\Sigma \subset \mathbb{R}^3$, Gauss map $G : \Sigma \to \mathbb{S}^2$, $p \mapsto \nu_p =$ unit normal to Σ in p.
- By definition $\kappa dg_{\Sigma} = G^* dg_{S^2}$



- Surface $\Sigma \subset \mathbb{R}^3$, Gauss map $G : \Sigma \to \mathbb{S}^2$, $p \mapsto \nu_p =$ unit normal to Σ in p.
- By definition $\kappa dg_{\Sigma} = G^* dg_{\mathbb{S}^2}$



• $\kappa(p) = \frac{\operatorname{Area}(A'B'C'D')}{\operatorname{Area}(ABCD)}$ for "very small" rectangle $ABCD \ni p$

- Surface $\Sigma \subset \mathbb{R}^3$, Gauss map $G : \Sigma \to \mathbb{S}^2$, $p \mapsto \nu_p =$ unit normal to Σ in p.
- By definition $\kappa dg_{\Sigma} = G^* dg_{\mathbb{S}^2}$



- $\kappa(p) = \frac{\operatorname{Area}(A'B'C'D')}{\operatorname{Area}(ABCD)}$ for "very small" rectangle $ABCD \ni p$
- Gauss Egregium Theorem: κ is a metric invariant of (Σ, g_{Σ})

- Surface $\Sigma \subset \mathbb{R}^3$, Gauss map $G : \Sigma \to \mathbb{S}^2$, $p \mapsto \nu_p =$ unit normal to Σ in p.
- By definition $\kappa dg_{\Sigma} = G^* dg_{\mathbb{S}^2}$



- $\kappa(p) = \frac{\operatorname{Area}(A'B'C'D')}{\operatorname{Area}(ABCD)}$ for "very small" rectangle $ABCD \ni p$
- Gauss Egregium Theorem: κ is a metric invariant of (Σ, g_{Σ})
- Angle defect in a geodesic polygon on Σ := sum of exterior angles -2π .

• Geodesic triangle *ABC*, exterior angles \angle_A^{ext} , etc.



э

• Geodesic triangle *ABC*, exterior angles \angle_A^{ext} , etc.



• Angle defect = $\angle \frac{\text{ext}}{A} + \angle \frac{\text{ext}}{B} + \angle \frac{\text{ext}}{C} - 2\pi$

э

• • = • • =

• Geodesic triangle *ABC*, exterior angles \angle_A^{ext} , etc.



- Angle defect = $\angle \frac{\text{ext}}{A} + \angle \frac{\text{ext}}{B} + \angle \frac{\text{ext}}{C} 2\pi$
- Gauss 1827: in a geodesic triangle ABC,

$$\int_{ABC} \kappa \mathrm{d}g_{\Sigma} + \text{angle defect} = 0$$

• Extrinsic curvature of a curve in a surface: infinitesimal version of the exterior angle.





• Extrinsic curvature of a curve in a surface: infinitesimal version of the exterior angle.



• $\Gamma \subset \Sigma$ curved parametrized by arc-length; ν unit normal vector field

• Extrinsic curvature of a curve in a surface: infinitesimal version of the exterior angle.



• $\Gamma \subset \Sigma$ curved parametrized by arc-length; ν unit normal vector field • curvature of Γ = length of the projection of $\partial_t \nu$ on Γ

• Extrinsic curvature of a curve in a surface: infinitesimal version of the exterior angle.



- $\Gamma \subset \Sigma$ curved parametrized by arc-length; ν unit normal vector field • curvature of Γ = length of the projection of $\partial_t \nu$ on Γ
- Essentially, equal to the second fundamental form of $\Gamma \subset \Sigma$.

• Extrinsic curvature of a curve in a surface: infinitesimal version of the exterior angle.



- $\Gamma \subset \Sigma$ curved parametrized by arc-length; ν unit normal vector field • curvature of Γ = length of the projection of $\partial_t \nu$ on Γ
- Essentially, equal to the second fundamental form of $\Gamma \subset \Sigma$.
- Bonnet 1848: $\Sigma \subset \mathbb{R}^3$ simply connected surface with polygonal boundary, not necessarily geodesic.

$$\int_{\Sigma} \kappa dg_{\Sigma} + \text{angle defect} = \int_{\partial \Sigma} \text{geodesic curvature}$$

Gauss-Bonnet theorem in popular culture

• 1872: Paul Féval, Les Compagnons du Trésor

Sergiu Moroianu (IMAR Bucharest)

Transgressions of Pfaffian

August 2023 10 / 37

э

- 1872: Paul Féval, Les Compagnons du Trésor
- On doit pouvoir se rendre compte de la direction et de la distance en faisant bien attention aux détours. Chacun sait qu'une voiture, en tournant, fait éprouver une sensation au voyageur, surtout si le coude du voyageur est en communication avec la paroi. Deux minutes ne s'étaient pas écoulées que Vincent eut la preuve matérielle de ce fait. On tourna à droite et il en eut complétement conscience.

Le cocher fouetta ses chevaux qui partirent au grand trot.

Vincent se disait :

— On doit pouvoir se rendre compte de la direction et de la distance en faisant bien attention aux détours.

Et il tint son esprit en arrêt.

Chacun sait qu'une voiture, en tournant, fait éprouver une sensation au voyageur, surtout si le coude du voyageur est en communication avec la paroi.

Deux minutes ne s'étaient pas écoulées que Vincent eut la preuve matérielle de ce fait.

On tourna à droite et il en eut complètement conscience.

-Est-ce le pont des Saints-Pères ou le pont Royal? demanda-t-il.

— Voilà! fit le colonel en riant bonnement, tu calcules déjà comme un malheureux! Je parie cinquante centimes avec toi que, dans une demi-heure.

August 2023 11 / 37

3

(日) (同) (三) (三)

- Everyone knows that a car, when turning, makes the traveler experience a sensation, especially if their elbow is in contact with the wall. One can calculate the direction and the distance by paying close attention to the detours.
 - Vincent had material proof of this fact. They turned right and he was fully aware of it.
 - "Is it the Pont des Saints-Pères or the Pont Royal?"he asked.
 - So ! said the colonel with a good laugh, you're already calculating like a wretch!

• Walther von Dyck 1888: $\Sigma \subset \mathbb{R}^3$ compact, no boundary.

Sergiu Moroianu (IMAR Bucharest)

Transgressions of Pfaffian

August 2023 13 / 37

- Walther von Dyck 1888: $\Sigma \subset \mathbb{R}^3$ compact, no boundary.
- $\chi(\Sigma)$ = alternate sum of Betti numbers = alternate sum of the numbers of simplices in each dimension in a triangulation:
 - = $V E + F \dots$, where V = #vertices, E = #edges, V = #faces.

$$\int_{\Sigma} \kappa dg_{\Sigma} = 2\pi \chi(\Sigma)$$
$$= 4\pi \times \frac{\chi(\Sigma)}{2}$$

- Walther von Dyck 1888: $\Sigma \subset \mathbb{R}^3$ compact, no boundary.

$$= V - E + F - \dots$$
, where $V = \#$ vertices, $E = \#$ edges, $V = \#$ faces.

$$\int_{\Sigma} \kappa dg_{\Sigma} = 2\pi \chi(\Sigma)$$
$$= 4\pi \times \frac{\chi(\Sigma)}{2}$$

•
$$4\pi = \operatorname{Vol}(\mathbb{S}^2)$$
 and $\chi(\Sigma)/2 = \chi(X)$ where $\partial X = \Sigma$.



- Walther von Dyck 1888: $\Sigma \subset \mathbb{R}^3$ compact, no boundary.

$$V = V - E + F - \dots$$
, where $V = \#$ vertices, $E = \#$ edges, $V = \#$ faces.

$$\int_{\Sigma} \kappa dg_{\Sigma} = 2\pi \chi(\Sigma)$$
$$= 4\pi \times \frac{\chi(\Sigma)}{2}$$

•
$$4\pi = \operatorname{Vol}(\mathbb{S}^2)$$
 and $\chi(\Sigma)/2 = \chi(X)$ where $\partial X = \Sigma$.



• Inclusion/exclusion principle: $\chi(2X) = 2\chi(X) - \chi(\Sigma)$.

Sergiu Moroianu (IMAR Bucharest)

Transgressions of Pfaffian

August 2023 13 / 37

Hypersurfaces in \mathbb{R}^{2n+1}

 Σ ⊂ ℝ²ⁿ⁺¹ hypersurface, X = the interior of Σ, ∂X = Σ. Heinz Hopf 1925: Extend the unit normal G to a vector field ν on X, with isolated zeros of the form ν = Σ_{j=1}²ⁿ⁺¹ ±x_j∂_{x_j}



August 2023

• • = • • = •

14 / 37

Hypersurfaces in \mathbb{R}^{2n+1}

 Σ ⊂ ℝ²ⁿ⁺¹ hypersurface, X = the interior of Σ, ∂X = Σ. Heinz Hopf 1925: Extend the unit normal G to a vector field ν on X, with isolated zeros of the form ν = Σ_{j=1}²ⁿ⁺¹ ±x_j∂_{x_j}



 Index of ν at p₁ in the picture is -1. Index = parity of the number of incoming directions (number of - signs).

Sergiu Moroianu (IMAR Bucharest)

Transgressions of Pfaffian

August 2023 14 / 37

Hopf's proof

Define a unit vector field on Σ \ Z(ν) = {p₁, p₂,...} = the (finite) zero set of ν by V = ν/|ν|. Equivalently, the function V : Σ \ Z(ν) → S²ⁿ extends the Gauss map G.

3

< ロ > < 同 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ >

Hopf's proof

- Define a unit vector field on Σ \ Z(ν) = {p₁, p₂,...} = the (finite) zero set of ν by V = ν/|ν|. Equivalently, the function V : Σ \ Z(ν) → S²ⁿ extends the Gauss map G.
- $V^* dg_{S^{2n}}$ is a closed 2*n*-form since $dg_{S^{2n}}$ is closed

3

イロト 不得下 イヨト イヨト
Hopf's proof

- Define a unit vector field on Σ \ Z(ν) = {p₁, p₂,...} = the (finite) zero set of ν by V = ν/|ν|. Equivalently, the function V : Σ \ Z(ν) → S²ⁿ extends the Gauss map G.
- $V^* dg_{\mathbb{S}^{2n}}$ is a closed 2*n*-form since $dg_{\mathbb{S}^{2n}}$ is closed
- Stokes formula on $\Sigma \setminus B_{\epsilon}(p_j)$:

$$\begin{split} \int_{\Sigma} V^* \mathrm{d}g_{\mathbb{S}^{2n}} &= \sum \int_{\mathbb{S}_{\epsilon}(p_j)} V^* \mathrm{d}g_{\mathbb{S}^{2n}} \\ &= \mathrm{Vol}(\mathbb{S}^{2n}) \sum \mathrm{index}(p_j) = \mathrm{Vol}(\mathbb{S}^{2n})\chi(X) \end{split}$$

 $(\chi(X) = \deg(G) = \sum index(p_j)$, independent of the choice of ν)

イロト イポト イヨト イヨト 二日

• Hopf Egregium Thm: $G^* dg_{\mathbb{S}^{2n}}$ is *intrinsic* to (Σ, g_{Σ}) . Up to a constant, it is the *Pfaffian* of the curvature R^{Σ}

3

(日) (周) (日) (日)

- Hopf Egregium Thm: $G^* dg_{\mathbb{S}^{2n}}$ is *intrinsic* to (Σ, g_{Σ}) . Up to a constant, it is the *Pfaffian* of the curvature R^{Σ}
- Case n = 1: $Pf(R^{\Sigma}) = G^* dg_{\mathbb{S}^{2n}} = \kappa dg_{\Sigma}$ where $\kappa = R_{1221}^{\Sigma}$ in any orthonormal frame e_1, e_2 .

イロト イポト イヨト イヨト 二日

- Hopf Egregium Thm: G^{*}dg_{S²ⁿ} is *intrinsic* to (Σ, g_Σ). Up to a constant, it is the *Pfaffian* of the curvature R^Σ
- Case n = 1: $Pf(R^{\Sigma}) = G^* dg_{S^{2n}} = \kappa dg_{\Sigma}$ where $\kappa = R_{1221}^{\Sigma}$ in any orthonormal frame e_1, e_2 .
- Jacobian of the Gauss map = the shape operator ↔ the second fundamental form. So G^{*}dg_{S²ⁿ} = det(II)dg_Σ. Gauss equation for a hypersurface in ℝ²ⁿ⁺¹ with second fundamental form II:

$$R^{\Sigma}(X,Y,Z,T) = \mathrm{I}(X,T)\mathrm{I}(Y,Z) - \mathrm{I}(X,Z)\mathrm{I}(Y,T)$$

イロト 不得下 イヨト イヨト 二日

- Hopf Egregium Thm: G^{*}dg_{S²ⁿ} is *intrinsic* to (Σ, g_Σ). Up to a constant, it is the *Pfaffian* of the curvature R^Σ
- Case n = 1: $Pf(R^{\Sigma}) = G^* dg_{S^{2n}} = \kappa dg_{\Sigma}$ where $\kappa = R_{1221}^{\Sigma}$ in any orthonormal frame e_1, e_2 .
- Jacobian of the Gauss map = the shape operator ↔ the second fundamental form. So G^{*}dg_{S²ⁿ} = det(II)dg_Σ. Gauss equation for a hypersurface in ℝ²ⁿ⁺¹ with second fundamental form II:

$$R^{\Sigma}(X,Y,Z,T) = \mathrm{I}(X,T)\mathrm{I}(Y,Z) - \mathrm{I}(X,Z)\mathrm{I}(Y,T)$$

• Equivalently: $R^{\Sigma} = -\frac{1}{2}II^2 = -\frac{1}{2}(II_{ik}e_i \otimes e_k)^2 = -\frac{1}{2}II_{ik}II_{jl}e_i \wedge e_j \otimes e_k \wedge e_l$. How to get det(II) from II²?

▲日▼ ▲冊▼ ▲目▼ ▲目▼ 目 ろの⊙

• $A \in \operatorname{End}^{-}(\mathbb{R}^{2n})$ skew-symmetric, real, even dimension. Then

 $\det(A) \ge 0...$

• $A \in \operatorname{End}^{-}(\mathbb{R}^{2n})$ skew-symmetric, real, even dimension. Then

 $det(A) \ge 0...$

• ...because \exists a polynomial with (2n-1)!! monomials with coeff. ± 1 in the n(2n-1) variables a_{ij} , $1 \le i < j \le 2n$ of A, with

 $\operatorname{Pf}(A)^2 = \det(A).$

• $A \in \operatorname{End}^{-}(\mathbb{R}^{2n})$ skew-symmetric, real, even dimension. Then

 $det(A) \ge 0...$

• ...because \exists a polynomial with (2n-1)!! monomials with coeff. ± 1 in the n(2n-1) variables a_{ij} , $1 \le i < j \le 2n$ of A, with

0

$$Pf(A)^{2} = det(A).$$

Example: $n = 1$, $A = \begin{bmatrix} 0 & a \\ -a & 0 \end{bmatrix}$, $Pf(A) = a$.

Sergiu Moroianu (IMAR Bucharest)

۰

• $A \in \operatorname{End}^{-}(\mathbb{R}^{2n})$ skew-symmetric, real, even dimension. Then

 $det(A) \ge 0...$

• ...because \exists a polynomial with (2n-1)!! monomials with coeff. ± 1 in the n(2n-1) variables a_{ij} , $1 \le i < j \le 2n$ of A, with

$$\operatorname{Pf}(A)^2 = \det(A).$$

• Example:
$$n = 1$$
, $A = \begin{bmatrix} 0 & a \\ -a & 0 \end{bmatrix}$, $Pf(A) = a$.
• Example: $n = 2$, $A = \begin{bmatrix} 0 & a & b & c \\ -a & 0 & d & f \\ -b & -d & 0 & g \\ -c & -f & -g & 0 \end{bmatrix}$, $Pf(A) = ag - bf + cd$.

 E²ⁿ oriented even-dimensional real vector space endowed with a non-degenerate symmetric bilinear form. The *Berezin integral ℬ* : Λ²ⁿE → ℝ is the map of "erasing"the volume form:

$$\Lambda^{2n}(E^*) \ni \lambda \cdot \mathrm{vol} \longmapsto \lambda \in \mathbb{R}$$

 E²ⁿ oriented even-dimensional real vector space endowed with a non-degenerate symmetric bilinear form. The *Berezin integral ℬ* : Λ²ⁿE → ℝ is the map of "erasing"the volume form:

$$\Lambda^{2n}(E^*) \ni \lambda \cdot \mathrm{vol} \longmapsto \lambda \in \mathbb{R}$$

• Let $A \in End^{-}(E)$ be skew-symmetric relative to h

 E²ⁿ oriented even-dimensional real vector space endowed with a non-degenerate symmetric bilinear form. The *Berezin integral ℬ* : Λ²ⁿE → ℝ is the map of "erasing"the volume form:

$$\Lambda^{2n}(E^*) \ni \lambda \cdot \mathrm{vol} \longmapsto \lambda \in \mathbb{R}$$

Let A ∈ End⁻(E) be skew-symmetric relative to h
ω_A ∈ Λ²(V^{*}) is the associated exterior 2-form:

 $\omega_A(X,Y) = h(X,AY).$

 E²ⁿ oriented even-dimensional real vector space endowed with a non-degenerate symmetric bilinear form. The *Berezin integral ℬ* : Λ²ⁿE → ℝ is the map of "erasing"the volume form:

$$\Lambda^{2n}(E^*) \ni \lambda \cdot \mathrm{vol} \longmapsto \lambda \in \mathbb{R}$$

Let A ∈ End⁻(E) be skew-symmetric relative to h
ω_A ∈ Λ²(V^{*}) is the associated exterior 2-form:

$$\omega_A(X,Y) = h(X,AY).$$

• The Pfaffian of A:

$$\operatorname{Pf}(A) = \frac{1}{n!} \mathscr{B}(\omega_A^n) = \frac{1}{n!} \frac{\omega_A^n}{\operatorname{vol}_h}$$

Sergiu Moroianu (IMAR Bucharest)

18 / 37

• Let A, B be \mathbb{R} -algebras. Then $A \otimes B$ is also an algebra:

```
a \otimes b \cdot a' \otimes b' = aa' \otimes bb'.
```

3

A B A A B A A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A

• Let A, B be \mathbb{R} -algebras. Then $A \otimes B$ is also an algebra:

```
a \otimes b \cdot a' \otimes b' = aa' \otimes bb'.
```

• If A, B are graded, $a \in A^k$, $b \in B^h$, then $a \otimes b$ has type (k, h).

э

• Let A, B be \mathbb{R} -algebras. Then $A \otimes B$ is also an algebra:

```
a \otimes b \cdot a' \otimes b' = aa' \otimes bb'.
```

- If A, B are graded, $a \in A^k$, $b \in B^h$, then $a \otimes b$ has type (k, h).
- M = smooth manifold, $E \rightarrow M$ vector bundle. A *form*: section in the bundle Λ^*M of differential forms. A *double form*: section in the bundle of algebras

 $\Lambda^*(M)\otimes\Lambda^*(E^*)$

Sergiu Moroianu (IMAR Bucharest)

• Let A, B be \mathbb{R} -algebras. Then $A \otimes B$ is also an algebra:

$$a \otimes b \cdot a' \otimes b' = aa' \otimes bb'.$$

- If A, B are graded, $a \in A^k$, $b \in B^h$, then $a \otimes b$ has type (k, h).
- M = smooth manifold, $E \rightarrow M$ vector bundle. A *form*: section in the bundle Λ^*M of differential forms. A *double form*: section in the bundle of algebras

$$\Lambda^*(M)\otimes\Lambda^*(E^*)$$

• Example: a Riemannian metric is a (1,1) form for *E* = *TM*. The Ricci tensor: also (1,1) form

• Let A, B be \mathbb{R} -algebras. Then $A \otimes B$ is also an algebra:

$$a \otimes b \cdot a' \otimes b' = aa' \otimes bb'.$$

- If A, B are graded, $a \in A^k$, $b \in B^h$, then $a \otimes b$ has type (k, h).
- M = smooth manifold, $E \rightarrow M$ vector bundle. A *form*: section in the bundle Λ^*M of differential forms. A *double form*: section in the bundle of algebras

$$\Lambda^*(M)\otimes\Lambda^*(E^*)$$

- Example: a Riemannian metric is a (1,1) form for E = TM. The Ricci tensor: also (1,1) form
- If Q is a (k, h) form, then $d^{\nabla}Q$ is a (k+1, h) form.

M manifold; *E*²ⁿ → *M* oriented vector bundle of even rank; *h* = metric on *E*, ∇ = connection compatible with *h*.

- M manifold; E²ⁿ → M oriented vector bundle of even rank; h = metric on E, ∇ = connection compatible with h.
- The curvature tensor $R = R^{\nabla}$ is a double form of type (2,2)

$$R\in \Omega^2(M)\otimes \operatorname{End}^-(E)\simeq \Omega^2(M)\otimes \Omega^2(E^*).$$

- M manifold; E²ⁿ → M oriented vector bundle of even rank; h = metric on E, ∇ = connection compatible with h.
- The curvature tensor $R = R^{\nabla}$ is a double form of type (2,2)

$$R\in \Omega^2(M)\otimes \operatorname{End}^-(E)\simeq \Omega^2(M)\otimes \Omega^2(E^*).$$

• The Berezin integral \mathcal{B}_h acts in the second component:

 $\mathscr{B}_h(\alpha \otimes \operatorname{vol}_h) = \alpha.$

- M manifold; E²ⁿ → M oriented vector bundle of even rank; h = metric on E, ∇ = connection compatible with h.
- The curvature tensor $R = R^{\nabla}$ is a double form of type (2,2)

$$R\in \Omega^2(M)\otimes \operatorname{End}^-(E)\simeq \Omega^2(M)\otimes \Omega^2(E^*).$$

• The Berezin integral \mathscr{B}_h acts in the second component:

 $\mathscr{B}_h(\alpha \otimes \operatorname{vol}_h) = \alpha.$

• $R^n \in \Omega^{2n}(M) \otimes \Omega^{2n}(E^*)$. Define

$$\mathrm{Pf}(\nabla) = \frac{1}{n!} \mathcal{B}_h(R^n) \in \Omega^{2n}(M).$$

Sergiu Moroianu (IMAR Bucharest)

August 2023 20 / 37

- Pf(R) closed. Proof: Bianchi identity $d^{\nabla}R = 0$. Write $R^n = Pf(R) \otimes vol_h$. Since $\nabla h = 0$, also $\nabla vol_h = 0$ so $0 = d^{\nabla}R^n = dPf(R) \otimes vol_h$.
- $\operatorname{Pf}(R^{\nabla_1}) \operatorname{Pf}(R^{\nabla_2})$ exact

• $\operatorname{Pf}(R)$ closed. Proof: Bianchi identity $d^{\nabla}R = 0$. Write $R^n = \operatorname{Pf}(R) \otimes \operatorname{vol}_h$. Since $\nabla h = 0$, also $\nabla \operatorname{vol}_h = 0$ so $0 = d^{\nabla}R^n = d\operatorname{Pf}(R) \otimes \operatorname{vol}_h$.

•
$$\operatorname{Pf}(R^{\nabla_1}) - \operatorname{Pf}(R^{\nabla_2})$$
 exact

• The Pfaffian form is natural under pull-back

•
$$\operatorname{Pf}(R^{\nabla_1}) - \operatorname{Pf}(R^{\nabla_2})$$
 exact

- The Pfaffian form is natural under pull-back
- If there exists a *parallel* section $0 \neq s \in C^{\infty}(M, E)$ then $Pf(R) \equiv 0$

•
$$\operatorname{Pf}(R^{\nabla_1}) - \operatorname{Pf}(R^{\nabla_2})$$
 exact

- The Pfaffian form is natural under pull-back
- If there exists a *parallel* section $0 \neq s \in C^{\infty}(M, E)$ then $Pf(R) \equiv 0$
- If $\exists s$ everywhere nonzero section \implies Pf(R) exact

•
$$\operatorname{Pf}(R^{\nabla_1}) - \operatorname{Pf}(R^{\nabla_2})$$
 exact

- The Pfaffian form is natural under pull-back
- If there exists a *parallel* section $0 \neq s \in C^{\infty}(M, E)$ then $Pf(R) \equiv 0$
- If $\exists s$ everywhere nonzero section \implies Pf(R) exact
- (Last two properties not true for characteristic classes $Tr(R^k)$.)

The generalized Gauss-Bonnet theorem

Take E = TM, ∇ the Levi-Civita connection of g and R its curvature.

Theorem

(M,g) compact Riemannian manifold of dimension 2n.

$$(2\pi)^n\chi(M)=\int_M \operatorname{Pf}(R).$$

Gauss (1821), Bonnet (1848), Walther von Dyck(1888), Hopf (1925), Allendoerfer (1940), Fenchel (unpublished), Allendoerfer&Weil (1943), Chern (1944).

The generalized Gauss-Bonnet theorem

Take E = TM, ∇ the Levi-Civita connection of g and R its curvature.

Theorem

(M,g) compact Riemannian manifold of dimension 2n.

$$(2\pi)^n\chi(M)=\int_M \operatorname{Pf}(R).$$

Gauss (1821), Bonnet (1848), Walther von Dyck(1888), Hopf (1925), Allendoerfer (1940), Fenchel (unpublished), Allendoerfer&Weil (1943), Chern (1944).

- Allendoerfer&Weil: polyhedral manifolds

ヘロト 不得 とうき とうとう ほう

The generalized Gauss-Bonnet theorem

Take E = TM, ∇ the Levi-Civita connection of g and R its curvature.

Theorem

(M,g) compact Riemannian manifold of dimension 2n.

$$(2\pi)^n\chi(M)=\int_M \operatorname{Pf}(R).$$

Gauss (1821), Bonnet (1848), Walther von Dyck(1888), Hopf (1925), Allendoerfer (1940), Fenchel (unpublished), Allendoerfer&Weil (1943), Chern (1944).

- Allendoerfer: If M → ℝⁿ isometric embedding, then Hopf's formula holds (corollary of Hopf applied to the boundary of a tubular neighborhood).
- Allendoerfer&Weil: polyhedral manifolds
- Chern: intrinsic proof for manifolds with boundary using transgression

3

Polyhedra and their outer angles

• *Polyhedron*: subset in a vector space defined by a finite set of affine inequalities. *Polytope*: compact polyhedron

Polyhedra and their outer angles

- *Polyhedron*: subset in a vector space defined by a finite set of affine inequalities. *Polytope*: compact polyhedron
- Minkowski-Weyl theorem: A polytope is the same thing as the convex hull of some finite set



August 2023 23 / 37

Polyhedra and their outer angles

- *Polyhedron*: subset in a vector space defined by a finite set of affine inequalities. *Polytope*: compact polyhedron
- Minkowski-Weyl theorem: A polytope is the same thing as the convex hull of some finite set



 The *outer cone* of a face Y: the set of vectors (orthogonal to Y), making an angle greater than π with every interior-pointing vector. The *outer angle*: set of unit vectors in the outer cone.

Transgressions of the Pfaffian

X^I polytope (e.g. a simplex of dimension I); M = smooth manifold of any dimension; E²ⁿ → M oriented real vector bundle with metric h, compatible connection ∇

Transgressions of the Pfaffian

- X^I polytope (e.g. a simplex of dimension I); M = smooth manifold of any dimension; E²ⁿ → M oriented real vector bundle with metric h, compatible connection ∇
- $V: X \to C^{\infty}(M, E)$) family indexed by X of unit sections in E
- X^I polytope (e.g. a simplex of dimension I); M = smooth manifold of any dimension; E²ⁿ → M oriented real vector bundle with metric h, compatible connection ∇
- $V: X \to C^{\infty}(M, E)$) family indexed by X of unit sections in E
- $\nabla V \in C^{\infty}(X, \Omega^{1,1}(M, E))$ = family of (1,1)-forms

イロト 不得下 イヨト イヨト 二日

- X^I polytope (e.g. a simplex of dimension I); M = smooth manifold of any dimension; E²ⁿ → M oriented real vector bundle with metric h, compatible connection ∇
- $V: X \to C^{\infty}(M, E)$) family indexed by X of unit sections in E
- $\nabla V \in C^{\infty}(X, \Omega^{1,1}(M, E))$ = family of (1,1)-forms
- $d^X V \in \Omega^1(X, \Omega^{0,1}(M, E))$ differential of V in the X directions

イロト 不得下 イヨト イヨト 二日

- X^I polytope (e.g. a simplex of dimension I); M = smooth manifold of any dimension; E²ⁿ → M oriented real vector bundle with metric h, compatible connection ∇
- $V: X \to C^{\infty}(M, E)$) family indexed by X of unit sections in E
- $\nabla V \in C^{\infty}(X, \Omega^{1,1}(M, E))$ = family of (1,1)-forms
- d^XV ∈ Ω¹(X, Ω^{0,1}(M, E)) differential of V in the X directions
 R ∈ Ω^{2,2}(M, E)

イロト 不得下 イヨト イヨト 二日

X^I polytope (e.g. a simplex of dimension I); M = smooth manifold of any dimension; E²ⁿ → M oriented real vector bundle with metric h, compatible connection ∇

• $V: X \to C^{\infty}(M, E)$) family indexed by X of unit sections in E

• $\nabla V \in C^{\infty}(X, \Omega^{1,1}(M, E))$ = family of (1,1)-forms

d^XV ∈ Ω¹(X, Ω^{0,1}(M, E)) differential of V in the X directions
 R ∈ Ω^{2,2}(M, E)

•
$$c(n,k,l) := \frac{2^k k!}{(n-1-k)!(2k+1-l)!} \in \mathbb{Q}$$

Definition

The $(l+1)^{\text{th}}$ transgression of the Pfaffian, $\mathcal{T}_{V}^{(l+1)} \in \Omega^{2n-l-1}(M)$

$$\mathcal{T}_{V}^{(l+1)} = \sum_{l \leq 2k+1 \leq 2n-1} \frac{c(n,k,l)}{l!} \int_{X} \mathcal{B}\left[V(d^{X}V)^{l} (\nabla V)^{2k+1-l} R^{n-1-k}\right]$$

For I = 0: Chern (1944).

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 のへで

• $E \rightarrow M$ vector bundle, metric h and compatible connection ∇

э

A B A A B A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A

- $E \rightarrow M$ vector bundle, metric h and compatible connection ∇
- V = family of unit-length sections in $E \rightarrow M$ indexed by an oriented *l*-dimensional polytope X.

Theorem

$$d\mathcal{T}_{X}^{(l+1)} = \begin{cases} -\mathcal{T}_{\partial X}^{(l)} & \text{for } l = \dim X \ge 1, \\ -\operatorname{Pf}(\nabla) & \text{for } l = \dim(X) = 0 \end{cases}$$

 $\mathcal{T}_{\partial X}^{(l)} \in \Omega^{2n-l}(M)$ is the sum of the transgression forms corresponding to the oriented hyperfaces of X.

Sergiu Moroianu (IMAR Bucharest)

・ 得 ト ・ ヨ ト ・ ヨ ト

• $\pi: SE \to M$ unit sphere bundle. Pull back the vector bundle E on SE. It has metric h and compatible connection $\nabla^1 = \pi^* \nabla$

3

< □ > < □ > < □ > < □ > < □ > < □ >

- π : SE → M unit sphere bundle. Pull back the vector bundle E on SE. It has metric h and compatible connection ∇¹ = π^{*}∇
- Tautological section S in $\pi^* E$. Explicit metric connection $\nabla^0 = \nabla^1 A$ with $\nabla^0 S = 0$. Connection $\tilde{\nabla} = t \nabla^1 + (1 - t) \nabla^0 + d^{[0,1]}$ on $SE \times [0,1]$

Image: A matrix and a matrix

- $\pi: SE \to M$ unit sphere bundle. Pull back the vector bundle E on SE. It has metric h and compatible connection $\nabla^1 = \pi^* \nabla$
- Tautological section S in $\pi^* E$. Explicit metric connection $\nabla^0 = \nabla^1 A$ with $\nabla^0 S = 0$. Connection $\tilde{\nabla} = t \nabla^1 + (1 - t) \nabla^0 + d^{[0,1]}$ on $SE \times [0,1]$
- Recall V : X × M → SE family of unit sections. Pull back ∇ through (x, m, t) ↦ (V(x, m), t) to a connection D on E over X × M × [0,1]

3

・ロト ・ 一下 ・ ・ 三 ト ・ 三 ト

- $\pi: SE \to M$ unit sphere bundle. Pull back the vector bundle E on SE. It has metric h and compatible connection $\nabla^1 = \pi^* \nabla$
- Tautological section S in $\pi^* E$. Explicit metric connection $\nabla^0 = \nabla^1 A$ with $\nabla^0 S = 0$. Connection $\tilde{\nabla} = t \nabla^1 + (1 - t) \nabla^0 + d^{[0,1]}$ on $SE \times [0,1]$
- Recall $V : X \times M \to SE$ family of unit sections. Pull back $\tilde{\nabla}$ through $(x, m, t) \mapsto (V(x, m), t)$ to a connection D on E over $X \times M \times [0, 1]$
- Definition 2 of the higher transgression form: ∫_{X×[0,1]} Pf(D). Hard part: compute it explicitly as in Def. 1.

$$\begin{split} R^{D} &= R^{\nabla} - (t-1)R^{\nabla}V \wedge V + \frac{1-t^{2}}{2} (\mathrm{d}^{X}V + \nabla V)^{2} \\ &+ \mathrm{d}t \otimes V \cdot (\mathrm{d}^{X}V + \nabla V). \end{split}$$

3

・ロト ・ 一下 ・ ・ 三 ト ・ 三 ト

- $\pi: SE \to M$ unit sphere bundle. Pull back the vector bundle E on SE. It has metric h and compatible connection $\nabla^1 = \pi^* \nabla$
- Tautological section S in $\pi^* E$. Explicit metric connection $\nabla^0 = \nabla^1 A$ with $\nabla^0 S = 0$. Connection $\tilde{\nabla} = t \nabla^1 + (1 - t) \nabla^0 + d^{[0,1]}$ on $SE \times [0,1]$
- Recall $V : X \times M \to SE$ family of unit sections. Pull back $\tilde{\nabla}$ through $(x, m, t) \mapsto (V(x, m), t)$ to a connection D on E over $X \times M \times [0, 1]$
- Definition 2 of the higher transgression form: ∫_{X×[0,1]} Pf(D). Hard part: compute it explicitly as in Def. 1.

$$\begin{split} R^D &= R^\nabla - (t-1) R^\nabla V \wedge V + \frac{1-t^2}{2} (\mathrm{d}^X V + \nabla V)^2 \\ &+ \mathrm{d} t \otimes V \cdot (\mathrm{d}^X V + \nabla V). \end{split}$$

• The computation breaks down for characteristic forms of the type $\operatorname{Tr}(R^k)$ where $R \in \Omega^2(M, \operatorname{End}(E))$ (Chern, Pontriagin classes).

Polyhedral manifolds

• Compact, separated topological space *M*, locally homeo to some polyhedra of fixed dimension, with smooth atlas.



Polyhedral manifolds

• Compact, separated topological space *M*, locally homeo to some polyhedra of fixed dimension, with smooth atlas.



• Riemannian metric: locally it extends from the polyhedron to the ambient euclidean space

Polyhedral manifolds

• Compact, separated topological space *M*, locally homeo to some polyhedra of fixed dimension, with smooth atlas.



- Riemannian metric: locally it extends from the polyhedron to the ambient euclidean space
- Outer cone bundle of a boundary face Y: family of cones in TM consisting of those vectors making an angle $\geq \pi/2$ with every interior vector.

• Outer angle of a face Y: unit vectors in the outer cone of Y



э

A B A B A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A
 A

• Outer angle of a face Y: unit vectors in the outer cone of Y



• Locally trivial bundle over Y, fibers = spherical polyhedra denoted Y^*

• Outer angle of a face Y: unit vectors in the outer cone of Y



• Locally trivial bundle over Y, fibers = spherical polyhedra denoted Y^*

• Complex M^{out} of polyhedral manifolds (locally homeo to some set of faces in a polyhedron) of dimension dim(M) - 1

• Outer angle of a face Y: unit vectors in the outer cone of Y



• Locally trivial bundle over Y, fibers = spherical polyhedra denoted Y^*

- Complex M^{out} of polyhedral manifolds (locally homeo to some set of faces in a polyhedron) of dimension dim(M) 1
- $\partial_{n-2}M^{\text{out}} = 0$ (Wintgen's normal cycle)

Theorem

Let M^{2n} be a compact Riemannian polyhedral manifold. Then

$$(2\pi)^{n}\chi(M) - \int_{M} \operatorname{Pf}(R) = \sum_{l=1}^{2n} \sum_{k=\left\lceil \frac{l}{2} \right\rceil}^{n} \frac{(-1)^{l} 2^{k-1} (k-1)!}{(n-k)! (2k-l)!}$$
$$\sum_{Y \in \mathscr{F}^{(l)}(M)} \int_{S^{\operatorname{out}} Y} \mathscr{B}_{Y} \left[(R^{Y} - \frac{1}{2}g(A, A))^{n-k} (A^{*})^{2k-l} \right] |dg|$$

• $A \in \Lambda^1 Y \otimes \Lambda^1 Y \otimes N_Y$ is the second fundamental form of $Y \hookrightarrow M$.

э

Theorem

Let M^{2n} be a compact Riemannian polyhedral manifold. Then

$$(2\pi)^{n}\chi(M) - \int_{M} \operatorname{Pf}(R) = \sum_{l=1}^{2n} \sum_{k=\left\lceil \frac{l}{2} \right\rceil}^{n} \frac{(-1)^{l} 2^{k-1} (k-1)!}{(n-k)! (2k-l)!}$$
$$\sum_{Y \in \mathcal{F}^{(l)}(M)} \int_{S^{\operatorname{out}} Y} \mathcal{B}_{Y} \left[(R^{Y} - \frac{1}{2}g(A, A))^{n-k} (A^{*})^{2k-l} \right] |dg|$$

A ∈ Λ¹Y ⊗ Λ¹Y ⊗ N_Y is the second fundamental form of Y → M.
g(A, A) is a (2,2) double form on Y.

Theorem

Let M^{2n} be a compact Riemannian polyhedral manifold. Then

$$(2\pi)^{n}\chi(M) - \int_{M} \operatorname{Pf}(R) = \sum_{l=1}^{2n} \sum_{k=\left\lceil \frac{l}{2} \right\rceil}^{n} \frac{(-1)^{l} 2^{k-1} (k-1)!}{(n-k)! (2k-l)!}$$
$$\sum_{Y \in \mathcal{F}^{(l)}(M)} \int_{S^{\operatorname{out}} Y} \mathcal{B}_{Y} \left[(R^{Y} - \frac{1}{2}g(A, A))^{n-k} (A^{*})^{2k-l} \right] |dg|$$

- $A \in \Lambda^1 Y \otimes \Lambda^1 Y \otimes N_Y$ is the second fundamental form of $Y \hookrightarrow M$.
- g(A, A) is a (2,2) double form on Y.
- A^{*} ∈ C[∞](N_Y, Λ¹Y ⊗ Λ¹Y) is the contraction with the tautological section:

$$A^*(V)(X,Y) = g(A(X,Y),V).$$

Theorem

Let M^{2n} be a compact Riemannian polyhedral manifold. Then

$$(2\pi)^{n}\chi(M) - \int_{M} \operatorname{Pf}(R) = \sum_{l=1}^{2n} \sum_{k=\left\lceil \frac{l}{2} \right\rceil}^{n} \frac{(-1)^{l} 2^{k-1} (k-1)!}{(n-k)! (2k-l)!}$$
$$\sum_{Y \in \mathcal{F}^{(l)}(M)} \int_{S^{\operatorname{out}} Y} \mathcal{B}_{Y} \left[(R^{Y} - \frac{1}{2}g(A, A))^{n-k} (A^{*})^{2k-l} \right] |dg|$$

- $A \in \Lambda^1 Y \otimes \Lambda^1 Y \otimes N_Y$ is the second fundamental form of $Y \hookrightarrow M$.
- g(A, A) is a (2,2) double form on Y.
- $A^* \in C^{\infty}(N_Y, \Lambda^1 Y \otimes \Lambda^1 Y)$ is the contraction with the tautological section:

$$A^*(V)(X,Y) = g(A(X,Y),V).$$

• $\mathcal{F}^{(l)}(M)$ is the set of faces of codimension *l*.

29 / 37

• Start with U vector field on M with nondegenerate zeros and such that -U is inward-pointing. Set $V_0 = U/|U|$.

3

< ロ > < 同 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < 回 > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ >

- Start with U vector field on M with nondegenerate zeros and such that -U is inward-pointing. Set $V_0 = U/|U|$.
- The graph of $V_0 \subset SM$ is diffeo to M where the zero-set of U is replaced by the spheres at those points (real blow-up)



- Start with U vector field on M with nondegenerate zeros and such that -U is inward-pointing. Set $V_0 = U/|U|$.
- The graph of $V_0 \subset SM$ is diffeo to M where the zero-set of U is replaced by the spheres at those points (real blow-up)



• The Pfaffian is exact along this graph, with explicit primitive $\mathcal{T}^1(V_0)$. By Stokes, its integral localizes on those spheres (yielding $\chi(M)$), and on the boundary hyperfaces, $\int_Y \mathcal{T}^1(V_0)$.

• Y^* outer cone of face Y; $\mathscr{C}Y^*$ spherical cone over Y^*



• Y^* outer cone of face Y; $\mathscr{C}Y^*$ spherical cone over Y^*



 From V₀ and Y^{*}, construct family of unit vector fields on M indexed by X = CY^{*}.

3

(日) (周) (日) (日)

• Y^* outer cone of face Y; $\mathscr{C}Y^*$ spherical cone over Y^*



- From V_0 and Y^* , construct family of unit vector fields on M indexed by $X = \mathscr{C}Y^*$.
- $\mathcal{T}^1(V_0) = \mathcal{T}^1(Y^*) + \mathrm{d}\mathcal{T}^2(\mathscr{C}Y^*)$

ヨトィヨト

< (17) × <

• Y^* outer cone of face Y; $\mathscr{C}Y^*$ spherical cone over Y^*



- From V₀ and Y*, construct family of unit vector fields on M indexed by X = CY*.
- $\mathcal{T}^1(V_0)=\mathcal{T}^1(Y^*)+\mathrm{d}\mathcal{T}^2(\mathcal{C}Y^*)$
- $\int_Y \mathrm{d}\mathcal{T}^2(\mathscr{C}Y^*) = \int_{\partial Y} \mathcal{T}^2(\mathscr{C}Y^*)$. These add up to

• Y* outer cone of face Y; CY* spherical cone over Y*



- From V₀ and Y*, construct family of unit vector fields on M indexed by X = CY*.
- $\mathcal{T}^1(V_0) = \mathcal{T}^1(Y^*) + \mathrm{d}\mathcal{T}^2(\mathcal{C}Y^*)$
- $\int_Y \mathrm{d}\mathcal{T}^2(\mathscr{C}Y^*) = \int_{\partial Y} \mathcal{T}^2(\mathscr{C}Y^*)$. These add up to
- $\int_Z \mathcal{T}^2(\partial \mathcal{C} Z^*) \mathcal{T}^2(Z^*)$ for all Z of codim 2, etc.

э.

• Y* outer cone of face Y; CY* spherical cone over Y*



- From V₀ and Y*, construct family of unit vector fields on M indexed by X = CY*.
- $\mathcal{T}^1(V_0) = \mathcal{T}^1(Y^*) + \mathrm{d}\mathcal{T}^2(\mathcal{C}Y^*)$
- $\int_Y d\mathcal{T}^2(\mathscr{C}Y^*) = \int_{\partial Y} \mathcal{T}^2(\mathscr{C}Y^*)$. These add up to
- $\int_Z \mathcal{T}^2(\partial \mathcal{C} Z^*) \mathcal{T}^2(Z^*)$ for all Z of codim 2, etc.
- For a face Y of codim k, can compute $\int_{\partial Y} \mathcal{T}^k(Y^*)$, indep of V_0

э.

Theorem

Let (N,g) be a compact Riemannian polyhedral manifold of odd dimension 2n-1. Then

$$(2\pi)^{n}\chi(N) = \sum_{l=1}^{2n-1} \sum_{k=\left\lceil \frac{l-1}{2} \right\rceil}^{n-1} \frac{(-1)^{l-1}\pi(2k-1)!!}{(n-1-k)!(2k+1-l)!}$$
$$\sum_{Y \in \mathcal{F}^{(l)}(N)} \int_{S^{\text{out}}Y} \mathcal{B}_{Y} \left[(R^{Y} - \frac{1}{2}g(A,A))^{n-1-k} (A^{*})^{2k+1-l} \right] |dg|$$

• For closed manifolds, both sides are zero by algebraic reasons.

Sergiu Moroianu (IMAR Bucharest)

Transgressions of Pfaffian

August 2023 32 / 37

э

E 5 4 E

Theorem

Let (N,g) be a compact Riemannian polyhedral manifold of odd dimension 2n-1. Then

$$(2\pi)^{n}\chi(N) = \sum_{l=1}^{2n-1} \sum_{k=\left\lceil \frac{l-1}{2} \right\rceil}^{n-1} \frac{(-1)^{l-1}\pi(2k-1)!!}{(n-1-k)!(2k+1-l)!}$$
$$\sum_{Y \in \mathcal{F}^{(l)}(N)} \int_{S^{\text{out}}Y} \mathcal{B}_{Y} \left[(R^{Y} - \frac{1}{2}g(A,A))^{n-1-k} (A^{*})^{2k+1-l} \right] |dg|$$

• For closed manifolds, both sides are zero by algebraic reasons.

• Proof: apply the even-dimensional formula to $M = N \times [0, 1]$

э

- A TE N - A TE

Flat polyhedral manifolds

• M^k = flat compact polyhedral manifold with totally geodesic faces.

$$\operatorname{vol}(S^{k-1})\chi(M) = \sum_{Y = \operatorname{vertex}} \angle^{\operatorname{out}} Y.$$

The Euler characteristic of a flat compact polyhedral manifold with totally geodesic faces is always non-negative; positive as soon as M has at least one vertex, vanishes if no vertex.

Flat polyhedral manifolds

• M^k = flat compact polyhedral manifold with totally geodesic faces.

$$\operatorname{vol}(S^{k-1})\chi(M) = \sum_{Y = \operatorname{vertex}} \angle^{\operatorname{out}} Y.$$

The Euler characteristic of a flat compact polyhedral manifold with totally geodesic faces is always non-negative; positive as soon as M has at least one vertex, vanishes if no vertex.

• Clear for $M^k \subset \mathbb{R}^k$ polytope.



Theorem

Let M be a d-dimensional compact polyhedral manifold of constant sectional curvature \mathfrak{k} , with totally geodesic faces. Then

$$\frac{\chi(M)}{2} = \sum_{j \ge 0} \sum_{Y \in \mathcal{F}^{(d-2j)}} \mathfrak{t}^j \frac{\operatorname{vol}_{2j}(Y)}{\operatorname{vol}(S^{2j})} \frac{\angle^{\operatorname{out}} Y}{\operatorname{vol}(S^{d-2j-1})}$$

where $\mathscr{F}^{(d-2j)}$ is the set of faces of M of dimension 2j, S^k is the standard unit sphere in \mathbb{R}^{k+1} , and $\angle^{\text{out}}Y$ is the measure of the outer angle at the face Y.
Ideal hyperbolic 4-simplex

• *M* is the convex hull in \mathbb{H}^4 of 5 points in $\partial \mathbb{H}^4$.

$$\operatorname{vol}(M) = -2\pi^2 + \frac{\pi}{3} \sum_{Y \in \mathcal{F}^{(2)}(M)} \angle^{\operatorname{out}}(Y)$$

 $\angle^{\text{out}}(Y)$ is the outer dihedral angle of the ideal triangle Y in M.



Ideal hyperbolic 4-simplex

• *M* is the convex hull in \mathbb{H}^4 of 5 points in $\partial \mathbb{H}^4$.

$$\operatorname{vol}(M) = -2\pi^2 + \frac{\pi}{3} \sum_{Y \in \mathcal{F}^{(2)}(M)} \angle^{\operatorname{out}}(Y)$$

 $\angle^{\text{out}}(Y)$ is the outer dihedral angle of the ideal triangle Y in M.



• *M* is an ideal polyhedron in \mathbb{H}^4 .

$$\operatorname{vol}(M) = \frac{2\pi^2(2 - n_0(M))}{3} + \frac{\pi}{3} \sum_{Y=2-\mathsf{face}} (n_0(Y) - 2) \angle^{\operatorname{out}}(Y)$$

Sergiu Moroianu (IMAR Bucharest)

August 2023

35 / 37

Gauss-Bonnet for edge metrics

(N, h) oriented 2k - 1-dimensional Riemannian manifold. Define

$$\mathrm{Pf}^{\mathrm{odd}}(h) \coloneqq \sum_{j=0}^{k-1} (-1)^{k+j} (2k-2j-3)!! \mathscr{B}_h\left(\frac{(R^h)^j \wedge h^{2k-1-2j}}{j!(2k-2j-1)!}\right) \in \Lambda^{2k-1}(N).$$

 (M^{2k}, g) manifold with edge singularities: $\pi : \partial M \to B$ fibration, r boundary-defining function for the boundary; In a product collar neighborhood of $\partial M = \{r = 0\}$, the metric is

$$g = dr^2 \oplus g(r),$$
 $g(r) = r^2 g^V \oplus \pi^* g^B$

where g^B = metric on B, g^V = Riemannian metric on the fibers.

Theorem

If dim(B) is even,

$$(2\pi)^k \chi(M) = \int_M \operatorname{Pf}^g - \int_B \left(\operatorname{Pf}(g^B) \int_{\partial M/B} \operatorname{Pf}^{\operatorname{odd}}(g^V) \right).$$

Sergiu Moroianu (IMAR Bucharest)

Transgressions of Pfaffian

August 2023 36 / 37

Higher transgressions of the Pfaffian (2022) Odd Pfaffian forms (with Daniel Cibotaru), (2021)

э