

$$\zeta \widehat{\widetilde{\mathcal{K}}_w} = \overbrace{1 - z\ddot{w} - \zeta \ddot{w}}^{\nu} \Rightarrow g \bowtie \widetilde{\mathcal{K}}_w = \widetilde{\mathcal{K}}_{w^{-1}} \overbrace{a - b\ddot{w}}^{\nu}$$

$$\begin{aligned} \zeta \widehat{\widetilde{\mathcal{K}}_w} &= \overbrace{1 - z\ddot{w} - \zeta \ddot{w}}^{\nu} = \overbrace{1 - \underline{z + \zeta \ddot{w}}}^{\nu} \Rightarrow g \bowtie \widetilde{\mathcal{K}}_w = \widetilde{\mathcal{K}}_{w^{-1}} \overbrace{a - b\ddot{w}}^{\nu} \\ &= \frac{\zeta}{a|b} \overbrace{\begin{array}{c|c} a & b \\ \hline c & d \end{array}} \bowtie \widetilde{\mathcal{K}}_w = \frac{\zeta}{c|d} \overbrace{\begin{array}{c|c} a & b \\ \hline c & d \end{array}} \bowtie \widehat{\overset{-1}{a+zc} \overset{b+zd}{\mathcal{K}}_w} = \frac{\zeta}{c} \overbrace{\begin{array}{c|c} a+zc & 0 \\ \hline d - c\underbrace{a+zc}_{-1} & \underline{b+zd} \end{array}} \bowtie \widehat{\overset{-1}{a+zc} \overset{b+zd}{\mathcal{K}}_w} \end{aligned}$$

$$\begin{aligned} &= \frac{\zeta}{a+zc+\zeta c} \overbrace{\begin{array}{c} \nu \\ 1 - \underbrace{\overset{-1}{a+zc+\zeta c} \zeta \widehat{d - c \underline{a+zc} \underline{b+zd}}}_{-1} + \overset{-1}{a+zc} \widehat{b+zd} \ddot{w} \end{array}}^{\nu} \\ &= \overbrace{a+zc+\zeta c - \zeta \widehat{d - c \underline{a+zc} \underline{b+zd}} \ddot{w} - \underbrace{a+zc+\zeta c \widehat{a+zc} \widehat{b+zd} \ddot{w}}_{-1}}^{\nu} \\ &= \overbrace{a+zc+\zeta c - \zeta \widehat{d \ddot{w} + c \underline{a+zc} \underline{b+zd} \ddot{w}} - b\ddot{w} - zd\ddot{w} - \zeta c \underline{a+zc} \underline{b+zd} \ddot{w}}^{\nu} \\ &= \overbrace{a-b\ddot{w} + \underline{z+\zeta c-d\ddot{w}}}^{\nu} = \overbrace{1 + \underline{z+\zeta c-d\ddot{w}} \overbrace{a-b\ddot{w}}_{-1}}^{\nu} \overbrace{a-b\ddot{w}}^{\nu} = \overbrace{1 + \underline{z+\zeta} \overbrace{\widehat{\overset{*}{\ddot{a}-w\ddot{b}}} \widehat{\overset{*}{\ddot{c}-w\ddot{d}}}}_{-1}}^{\nu} \overbrace{a-b\ddot{w}}^{\nu} \\ g^{-1} = J \overset{*}{g} J &= \begin{array}{c|c} \ddot{a} & -\ddot{c} \\ \hline -\ddot{b} & \ddot{d} \end{array} \Rightarrow w \overset{-1}{g} = \widehat{\ddot{a}-w\ddot{b}} \widehat{\ddot{w}\ddot{d}-\ddot{c}} \end{aligned}$$

$${}^z_TG_w^\lambda \overbrace{{}^z_TK_{\partial T}^{\mu z}G_w^{-\lambda}}^z = (\lambda)_\mu {}^z_TK_{w^z}^\mu$$

$$\begin{aligned} {}^z_TG_w^{-\lambda} &= \sum_\mu (\lambda)_\mu {}^z_TK_w^\mu \Rightarrow {}^0\overbrace{{}^z_TK_{\partial T}^{\mu z}G_w^{-\lambda}}^0 = {}^z_TK_\zeta^\mu \boxtimes {}^z_TG_w^{-\lambda} = \sum_\kappa (\lambda)_\kappa {}^z_TK_\zeta^\mu \boxtimes {}^z_TK_w^\kappa = (\lambda)_\mu {}^z_TK_w^\mu \\ {}^x\overbrace{\mathbf{t}_z \boxtimes {}^z_TG_w^{-\lambda}}^x &= {}^{x+z}\overbrace{TG_w^{-\lambda}}^z = \underbrace{1 - x\hat{w} - z\hat{w}}_{-\lambda} = \underbrace{1 - x\hat{w}}_{-1} \underbrace{1 - z\hat{w}}_{-\lambda} \\ &= {}^z_TG_w^{-\lambda} {}^x_TG_{w^z}^{-\lambda} = {}^z_TG_w^{-\lambda} \sum_\kappa (\lambda)_\kappa {}^x_TK_{w^z}^\kappa \\ \Rightarrow {}^z\overbrace{{}^z_TK_{\partial T}^{\mu z}G_w^{-\lambda}}^z &= {}^0\overbrace{\mathbf{t}_z \boxtimes {}^z_TK_{\partial T}^{\mu z}G_w^{-\lambda}}^0 = {}^0\overbrace{{}^z_TK_\partial^\mu \mathbf{t}_z \boxtimes {}^z_TG_w^{-\lambda}}^0 = {}^z_TK_\zeta^\mu \boxtimes \underbrace{\mathbf{t}_z \boxtimes {}^z_TG_w^{-\lambda}}_z \\ &= {}^z_TG_w^{-\lambda} \sum_\kappa (\lambda)_\kappa {}^z_TK_\zeta^\mu \boxtimes {}^z_TK_{w^z}^\kappa = {}^z_TG_w^{-\lambda} (\lambda)_\mu {}^z_TK_{w^z}^\mu \end{aligned}$$

$$D_{\Delta_{\omega}^2} \underbrace{\lambda \boxtimes Z_{\Delta_{\hat{\omega}}^n} \mathbb{C}}_{\mathbb{C}} \leftarrow D_{\Delta_{\omega}^2} {}^{n+\lambda} \mathbb{C}$$

$$\zeta|z \widehat{\mathcal{I}\mathfrak{N}} = \sum_\mu \frac{(-n)_\mu}{(\lambda)_\mu} {}^z\overbrace{{}^z_TK_\partial^\mu \mathfrak{N}}^z = {}^z\overbrace{{}^z_\lambda \mathfrak{f}_\partial^{-n} \mathfrak{N}}^z$$

$$n \geqslant \mu_1 \geqslant \dots \geqslant \mu_r \geqslant 0 \Rightarrow \begin{bmatrix} n+r \\ r \end{bmatrix} \text{ terms}$$

$${}^z_TG_w^\lambda \overbrace{{}^z_T\mathcal{I}G_w^{-\lambda}}^{\zeta|z} = {}^z_TG_{w^z}^\lambda$$

$$\text{LHS} = {}^z_TG_w^\lambda \sum_\mu \frac{(-n)_\mu}{(\lambda)_\mu} {}^z\overbrace{{}^z_TK_{\partial T}^{\mu z}G_w^{-\lambda}}^z = \sum_\mu \frac{(-n)_\mu}{(\lambda)_\mu} (\lambda)_\mu {}^z_TK_{w^z}^\mu = \sum_\mu (-n)_\mu {}^z_TK_{w^z}^\mu = {}^z_TG_{w^z}^\lambda$$

$$\text{neu } {}^z_TG_w^\lambda \overbrace{{}^z_T\mathcal{I}G_w^{-\lambda \zeta^z B_w^{-1}}}^{\zeta|z} = {}^z_TG_w^{-n/p} \overbrace{{}^z_Tg_w \boxtimes {}^{w^{w+1}}\mathfrak{A}}^{\zeta} = {}^z_TG_w^{-n/p} {}^z_TG_w^n {}^{w^w + \zeta^z g_w} \mathfrak{A} = {}^z_TG_{w^z}^n {}^{w^w + \zeta^z g_w} \mathfrak{A}$$

$$\overleftarrow{\frac{-\nu}{a+wc}}^* \zeta \overbrace{_{U'}^{w\tilde{g}^\nu}\mathbf{1}} = {}^0 \cdot {}^w_U \tilde{g} + \zeta {}^w \overline{\tilde{g}} \mathbf{1}$$

$$\begin{aligned} \dot{w} {}^w \underline{g} &= \overbrace{a+wc}^{-1} \dot{w} \underbrace{d-c \overbrace{a+wc}^{-1} \overbrace{b+wd}}_{-1} \Rightarrow \dot{w} {}^w \underline{g}^* = \overbrace{a+wc}^{-*} \dot{w} \overbrace{d-c \overbrace{a+wc}^{-*} \overbrace{b+wd}}_{-1} \\ \frac{\zeta}{\alpha \left| \begin{array}{c} \beta \\ \gamma \end{array} \right| \delta} \mathbf{1} &= \overleftarrow{\alpha + \zeta \gamma}^* \overbrace{\alpha + \zeta \gamma}^{-1} \overbrace{\beta + \zeta \delta}^* \mathbf{1} \Rightarrow 0 \cdot {}^w_U \tilde{g} = \overbrace{a+wc}^{-*} \overbrace{c}^* \\ {}^w_U \tilde{g} &= \frac{\overbrace{a+wc}^*}{0} \left| \begin{array}{c} \overbrace{c}^* \\ \overbrace{d-c \overbrace{a+wc}^{-*} \overbrace{b+wd}}_{-1} \end{array} \right. \\ \overleftarrow{\frac{-\nu}{a+wc}}^* \zeta \overbrace{_{U'}^{w\tilde{g}^\nu}\mathbf{1}} &= \overbrace{a+wc}^{-*} \overbrace{\zeta \overbrace{\overbrace{d-c \overbrace{a+wc}^{-1} \overbrace{b+wd}}_{-1}}^*}^* \mathbf{1} = {}^0 \cdot {}^w_U \tilde{g} + \zeta {}^w \overline{\tilde{g}} \mathbf{1} \end{aligned}$$

$$\overleftarrow{\frac{-\nu}{a+wc}}^* {}^w_U \tilde{g}^\nu \mathbf{1} = {}^w \underline{\tilde{g}} \bowtie \mathbf{1} + \underbrace{0 \cdot {}^w_U \tilde{g}}_0 \mathbf{1}$$

$$0 \cdot {}^w_U \tilde{g} = \underbrace{0 \cdot {}^w_U \tilde{g}}_0 \mathbf{t}_w^*$$

$$\overleftarrow{\frac{-\nu}{a+wc}}^* {}^w_U \tilde{g}^\nu \left(\mathbf{1} + \underbrace{w_w \mathbf{1}}_0 \right)$$

$$\overleftarrow{\frac{\lambda}{1-z\tilde{w}}} \overbrace{\mathcal{I} \overleftarrow{\frac{-\lambda}{1-z\tilde{w}}}}^{\zeta | z} = \overleftarrow{\frac{n}{1-\zeta w^z}}$$

$$\text{LHS} = \overleftarrow{\frac{\lambda}{1-z\tilde{w}}} \sum_\mu \frac{(-n)_\mu}{K \lambda_\mu} \overbrace{\zeta K_\partial^\mu \overleftarrow{\frac{-\lambda}{1-z\tilde{w}}}}^z = \sum_\mu \frac{(-n)_\mu}{K \lambda_\mu} {}_K \lambda_\mu \zeta K_{w^z}^\mu = \sum_\mu (-n)_\mu \zeta K_{w^z}^\mu = \overleftarrow{\frac{n}{1-\zeta w^z}}$$

$$\begin{aligned} \text{neu } \overleftarrow{\frac{\lambda}{1-z\tilde{w}}} \overbrace{\mathcal{I} \overleftarrow{\frac{-\lambda}{1-z\tilde{w}}}}^{\zeta | z} \zeta {}_K^z G_w^{-1} \mathbf{1} &= \overleftarrow{\frac{-n}{1-z\tilde{w}}} \overbrace{{}^z g_w \bowtie \mathbf{1}}^{\zeta | z} = \overleftarrow{\frac{-n}{1-z\tilde{w}}} \overleftarrow{\frac{n}{1-\underbrace{z+\zeta \tilde{w}}_0}} {}^{w^w + \zeta^z g_w} \mathbf{1} = \overleftarrow{\frac{n}{1-\zeta w^z}} {}^{w^w + \zeta^z g_w} \mathbf{1} \\ \overleftarrow{\frac{-\nu}{a+wc}}^* {}^w_U \tilde{g}^\nu \bowtie \mathbf{1} &= {}^w_U \tilde{g}^\nu \bowtie \mathbf{1} + \underbrace{0 \cdot {}^w_U \tilde{g}}_0 \mathbf{1} \\ 0 \cdot {}^w_U \tilde{g} &= \underbrace{0 \cdot {}^w_U \tilde{g}}_0 \mathbf{t}_w^* \end{aligned}$$

$$\begin{aligned}
& \xleftarrow[a+wc]{-\nu} {}^w_Ug^* \ltimes \left(1 + \underline{w^w}1\right) = {}^w_Kg^* \ltimes 1 + \underbrace{0 \cdot {}^w_Ug^* + w^w}_{}1 = {}^w_Kg^* \ltimes 1 + \underbrace{(wg)^{wg}}_{{}^w_Kg^*} {}^w_Kg^* \ltimes 1 = {}^w_{\underline{U}}g^* \ltimes 1 + \underbrace{0 \cdot {}^w_{\underline{U}}g^*}_{}1 \\
& = {}^w_{\underline{U}}g^* \ltimes 1 + \underbrace{0 \cdot {}^w_{\underline{U}}g^* + w^w}_{}1 = {}^w_{\underline{U}}g^* \ltimes 1 + \underbrace{(wg)^{wg}}_{{}^w_{\underline{U}}g^*} {}^w_{\underline{U}}g^* \ltimes 1 \\
& 0 \cdot {}^w_{\underline{U}}g^* + w^w = \underbrace{(wg)^{wg}}_{{}^w_{\underline{U}}g^*} {}^w_{\underline{U}}g^* = \underbrace{(wg)^{wg}}_{{}^w_Kg^*} {}^w_Kg^* \\
& \underbrace{w^w}_{{}^w_Kg^*} {}^w_Kg^{1/2} = w
\end{aligned}$$